



Development of MicroTCA based LLRF control systems at cERL and STF

Feng QIU (KEK) Oct. 18, 2018



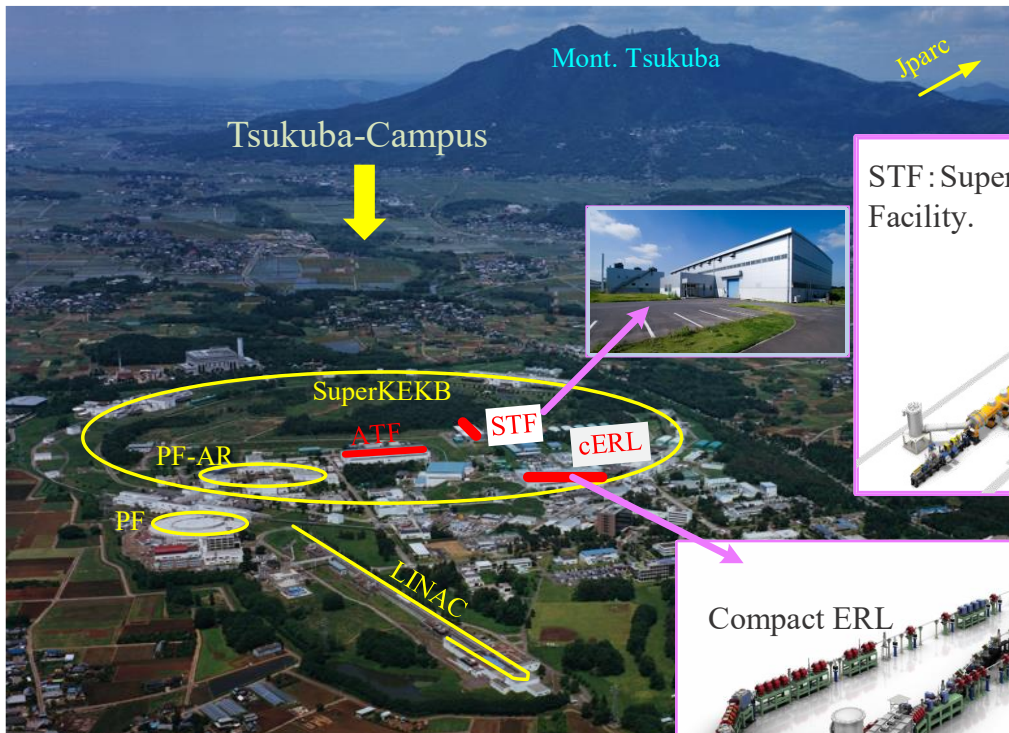


- Introduction of cERL and STF facilities
- Development of the μ TCA Low Level RF systems
- Performance of the LLRF systems

Facilities in KEK



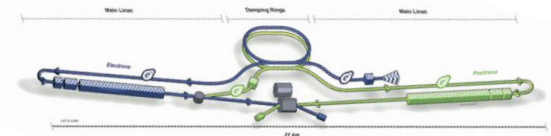
- Compact ERL (cERL): Test facility for 3 GeV light source, 1.3 GHz, Super-conducting (SC) and continuous wave (CW) mode.
- Super-conducting Test Facility (STF): Test facility for ILC, 1.3 GHz, SC and Pulse mode.



Cryomodule Cool-down Test: 2016
Beam Commissioning: 2019~

STF: Super-conducting Test Facility.

ILC: International Linear Collider

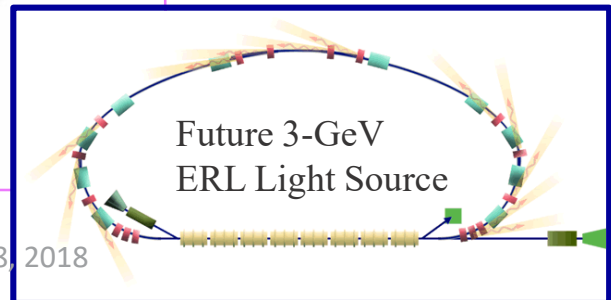


Compact ERL

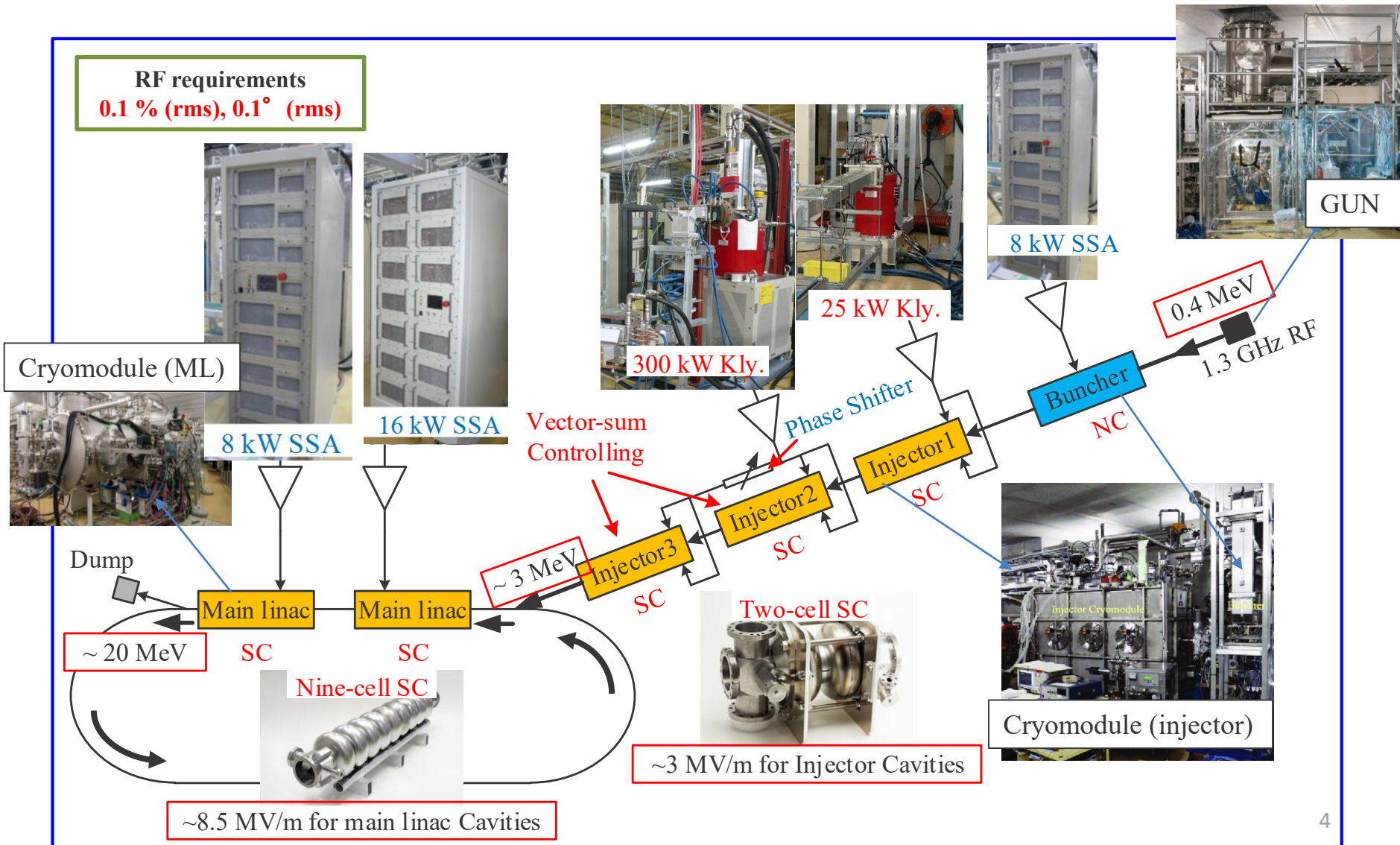
Beam Commissioning: 2013~2018



Future 3-GeV
ERL Light Source



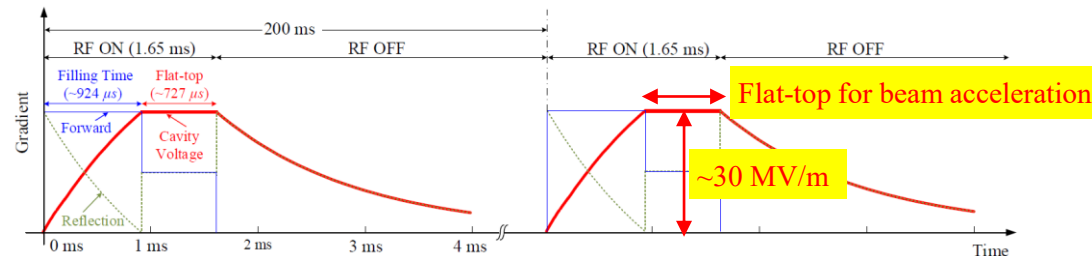
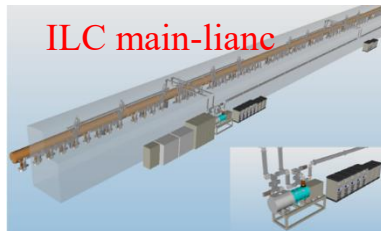
- Injector: 4 cavities (3-SC+1-NC), Mainlinac: 2 SC cavities.
- Various of Power Sources



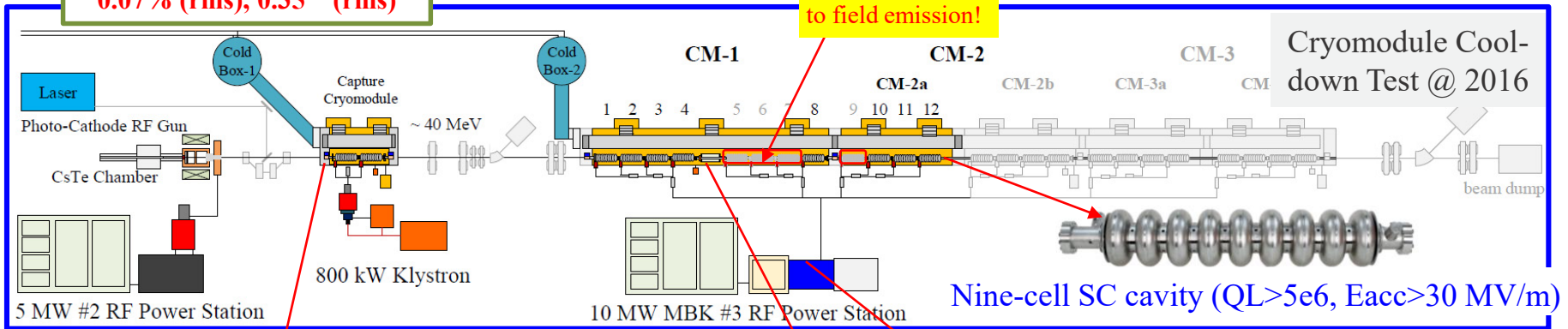
STF facility



- Motivation: Confirmation of the SC cavity technology, and cryomodule fabrication for ILC.
- PS mode (5 Hz, ~ 1.65 ms). SC nine-cell cavities ($QL \approx 5e6$, E_{acc} about 30 MV/m). Multi-beam klystron (MBK), 10 MW (65%).



RF requirements of ILC
0.07% (rms), 0.35° (rms)



10 MW MBK, ($\sim 65\%$), Toshiba E3736H



μ TCA LLRF systems

→Need a feedback system to stabilize the cavity field.

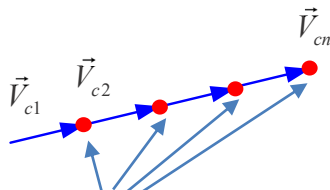
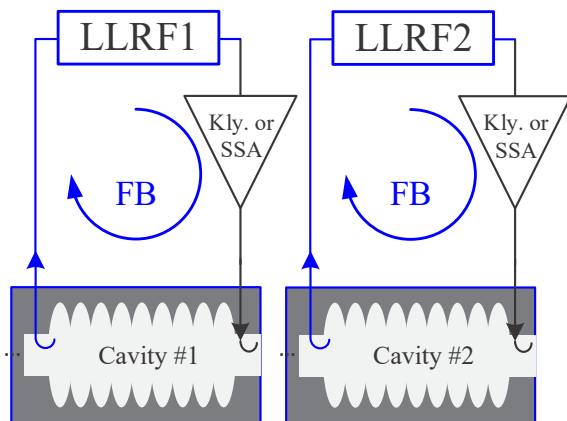
We need an FPGA board to implement the DSP algorithms.



LLRF Systems for cERL and STF

- Individual cavity control (cERL), Vector-sum control (STF).

cERL: One RF source (Kly. or SSA) drives one cavity (except injector2 & 3).

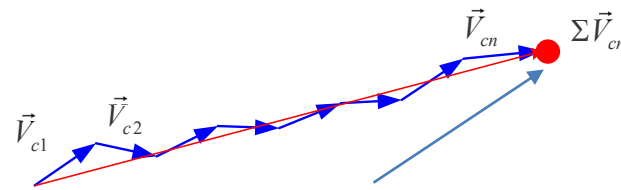
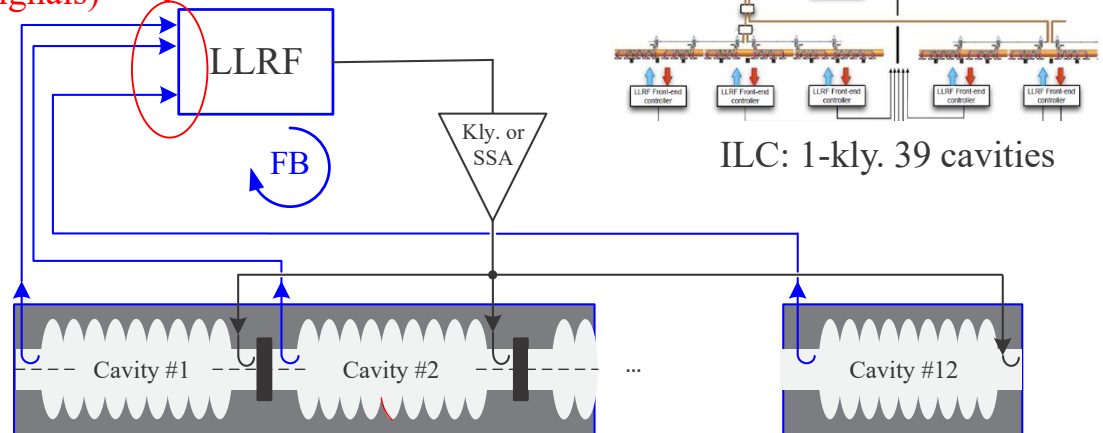


We control every ($\vec{V}_{c1}, \vec{V}_{c2} \dots \vec{V}_{cn}$)

RF requirements
0.1 % (rms), 0.1° (rms)

STF: One RF source drives twelve cavities (actually eight).

Vector-sum field (LLRF needs to process lots of signals)

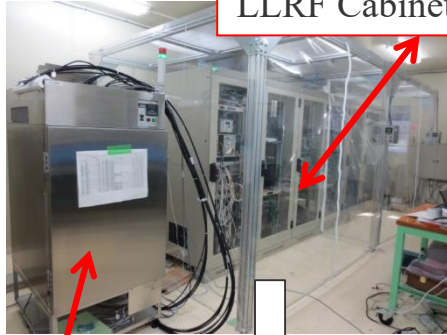


We only control VS ($\Sigma \vec{V}_{cn}$)

RF requirements of ILC
0.07% (rms), 0.35° (rms)

Example: LLRF system @cERL

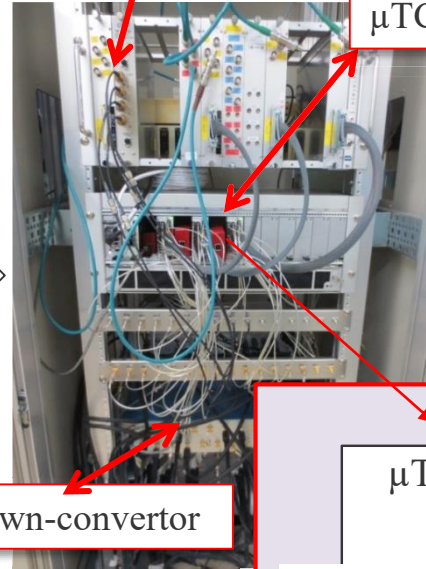
LLRF Cabinet



Thermostatic Chamber
(0.1 deg.)

IQ Mod.

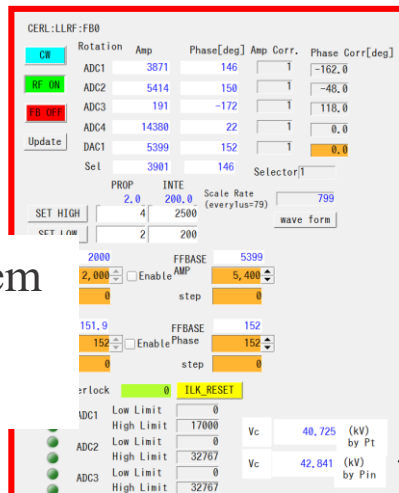
μ TCA



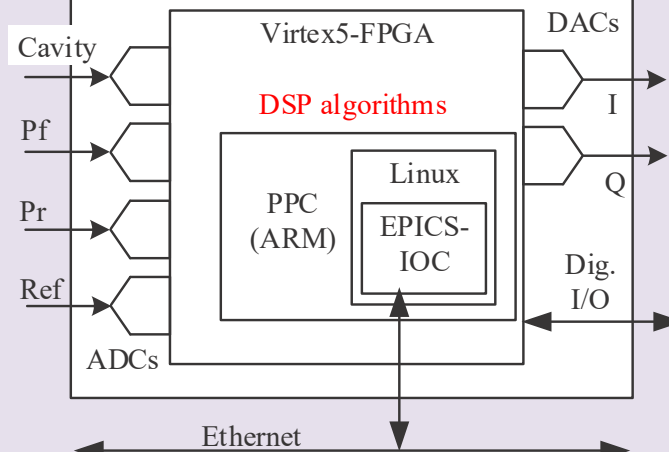
Down-converter

EPICS is installed inside μ TCA and is used as the DAQ (data acquisition) system.

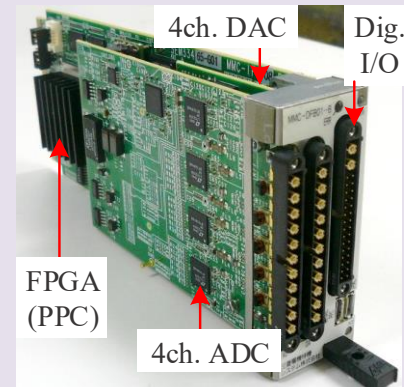
Control System
Studio (user
interface)



μ TCA FPGA board



μ TCA board

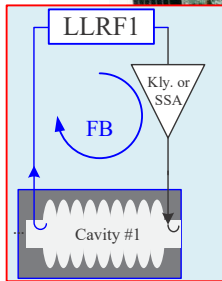


μ TCA boards (3 types)



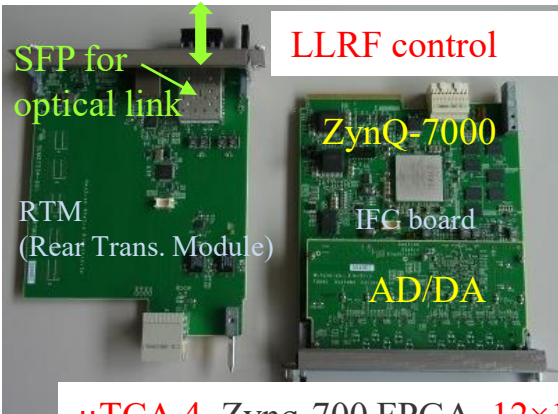
cERL (Type I, μ TCA.0)

LLRF control



μ TCA.0, Virtex-5 FPGA, 4 $\times$ 16-bits ADCs, 4 $\times$ 16-bits DACs

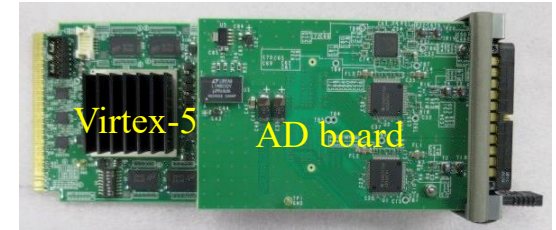
STF (Type II, μ TCA.4)



μ TCA.4, Zynq-700 FPGA, 12 $\times$ 16-bits ADCs, 2 $\times$ 16-bits DACs

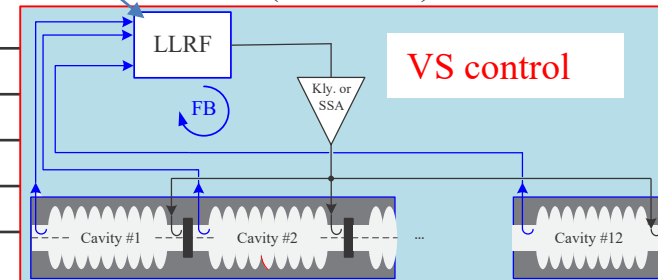
cERL&STF (Type III, μ TCA.0)

Monitor the long-term drift (directly sampling)



μ TCA.0, Virtex-5 FPGA, 2 $\times$ 14-bits fast ADCs (400 MHz)

TYPE	TYPE I	TYPE II	TYPE III
Facilities	cERL	STF-II	ERL & STF
Function	LLRF	LLRF	Monitor
Standard	μ TCA.0	μ TCA.4	μ TCA.0
ADC	4 $\times$ 16-bits (LTC2208, 130 MSPS)	14 $\times$ 16-bits (AD9650, 105 MSPS)	2 $\times$ 14-bits (ADS5474, 400MSPS)
FPGA	Virtex-5 FX	Virtex-5 FX	Zynq-7000
DAC	4 $\times$ 16-bits (AD9783, 500 MSPS)	2 $\times$ 16-bits (AD9783, 500 MSPS)	N/A
CPU	PPC 440	ARM	PPC 440
OS	Wind River Linux	Xilinx Linux	Wind River Linux

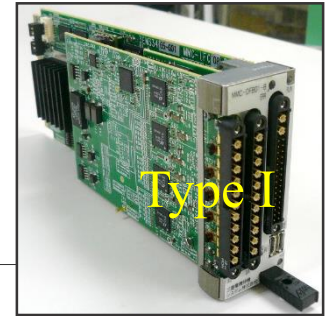
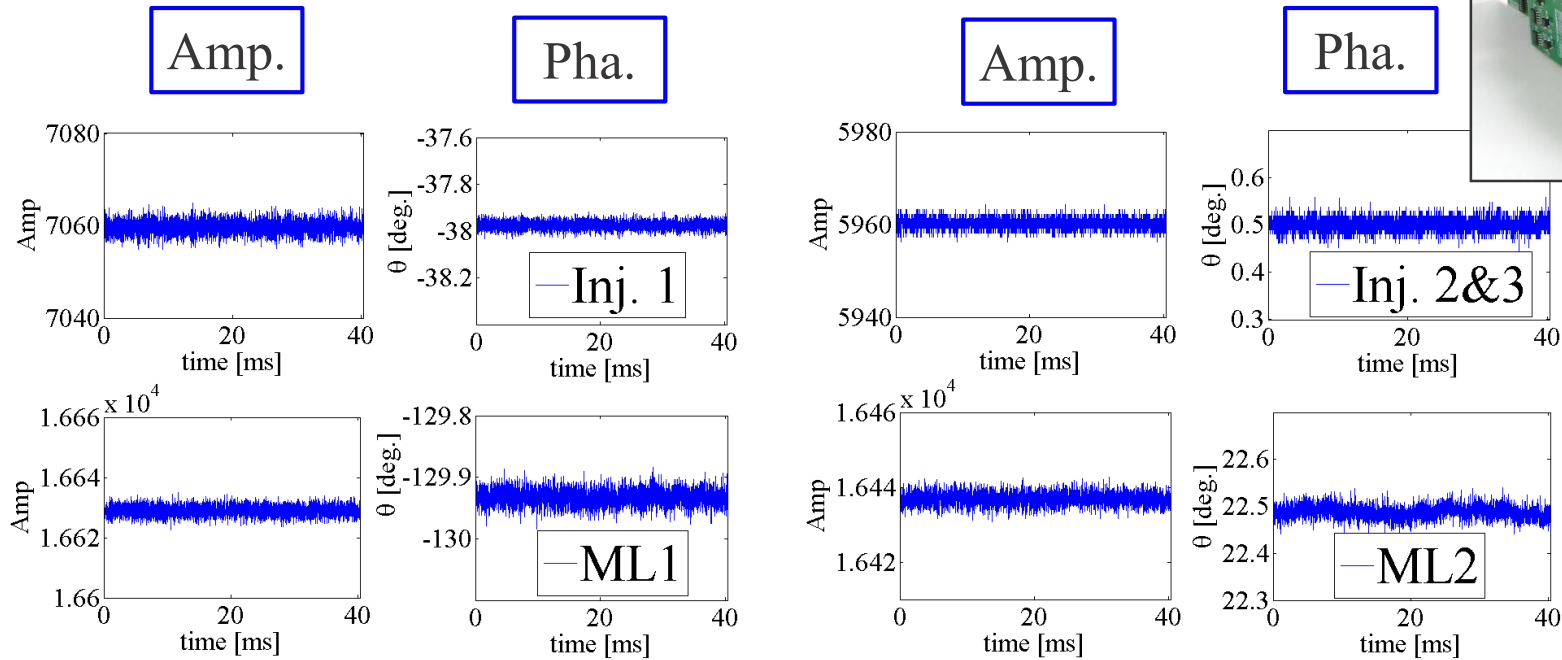


**Mitsubishi Electric
TOKKI System Co.,Ltd.**



Performance of LLRF systems

Performance @ cERL (RF stabilities)

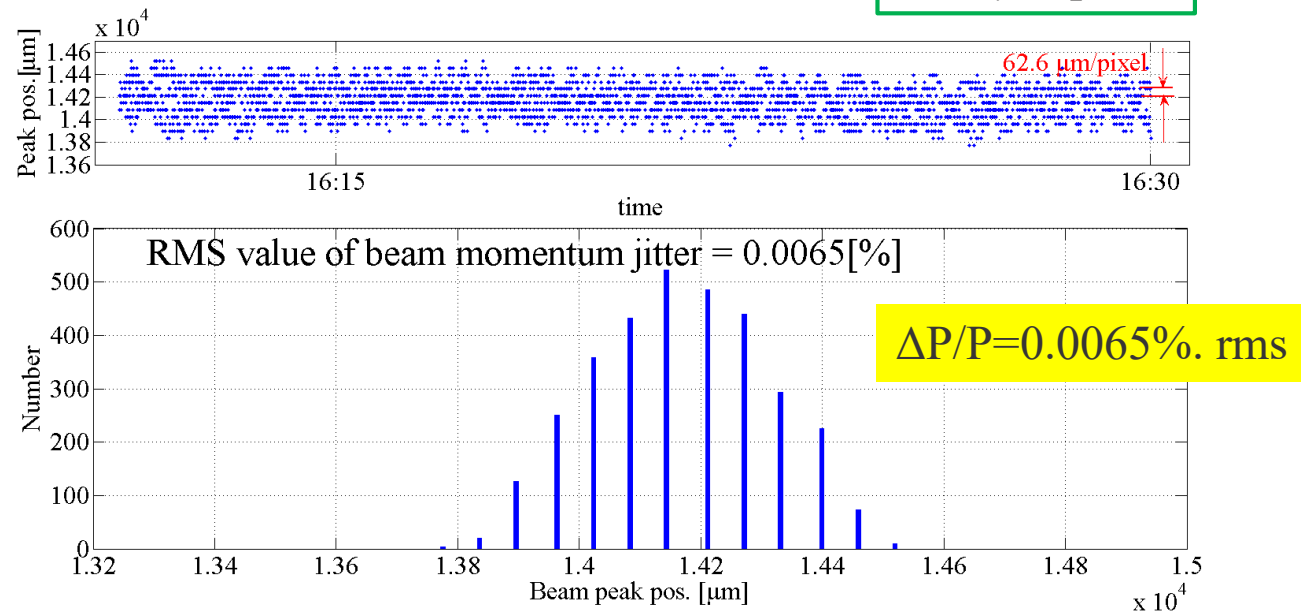
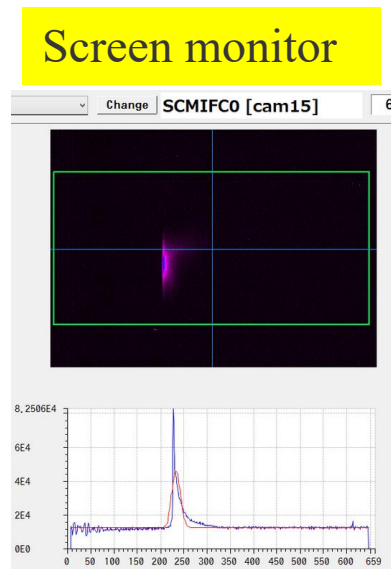
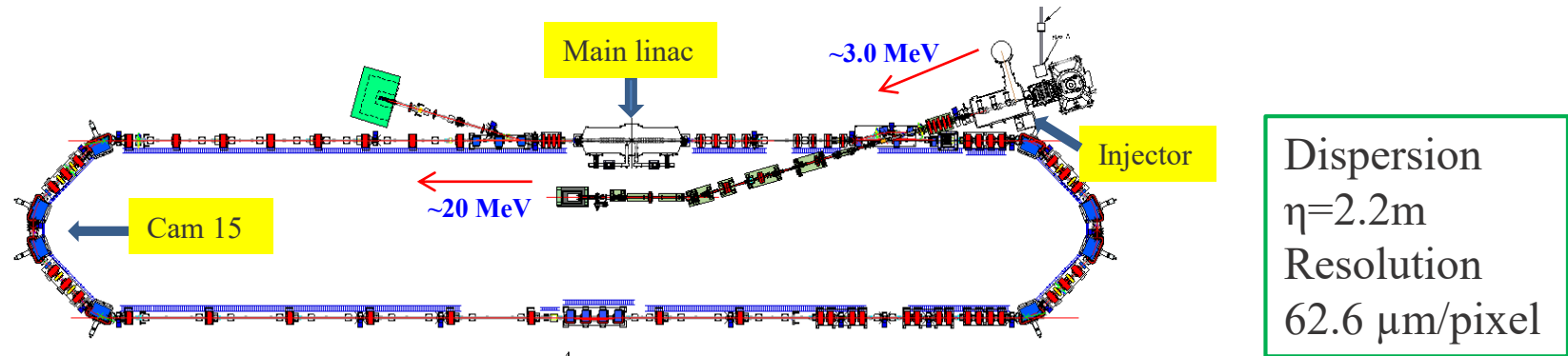


RF stability	Bun.	Inj. 1	Inj. 2&3 (VS)	ML1	ML2	Requirement
$\Delta A/A$ [% .rms]	0.07%	0.02%	0.02%	0.01%	0.01%	0.1%
$\Delta \theta$ [$^{\circ}$.rms]	0.04 $^{\circ}$	0.02 $^{\circ}$	0.015 $^{\circ}$	0.01 $^{\circ}$	0.01 $^{\circ}$	0.1 $^{\circ}$

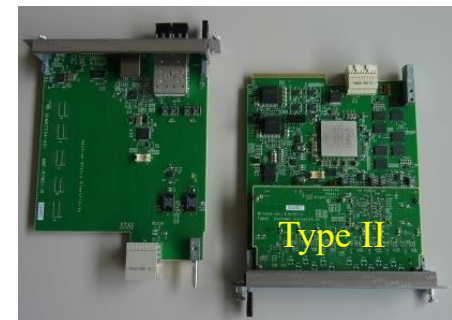
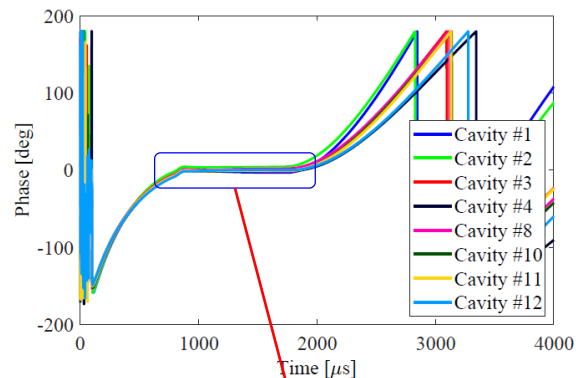
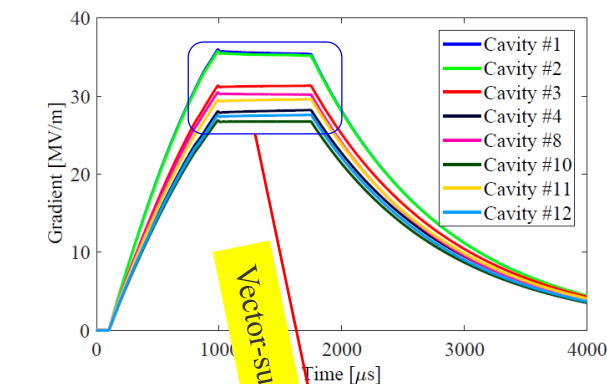
The results need to be confirmed by beam energy stabilities.

Performance @ cERL (Beam energy)

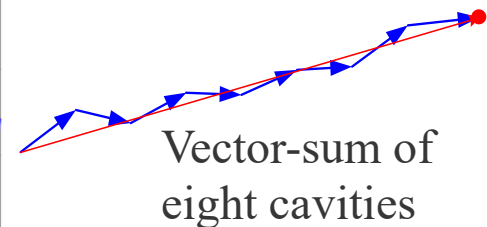
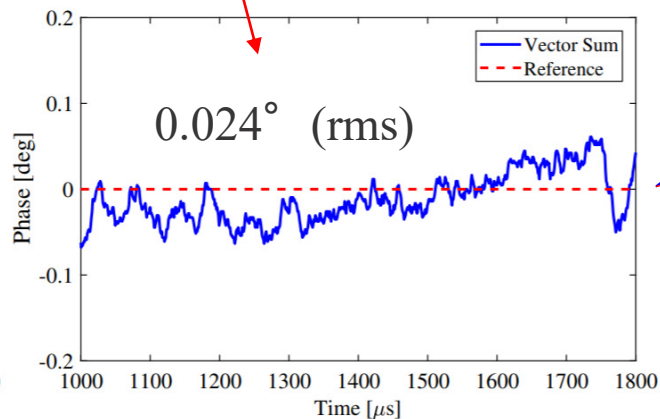
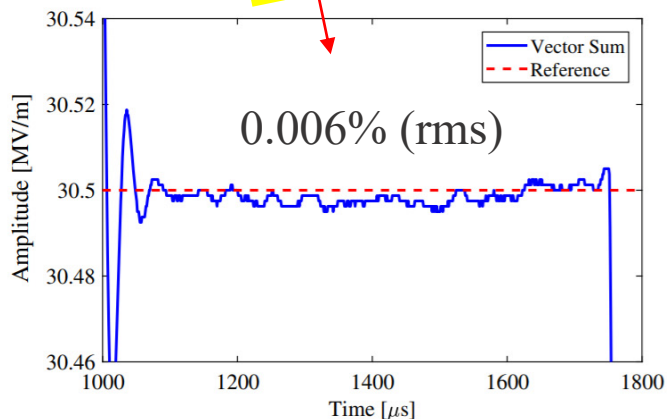
- Beam momentum jitter is measured by screen monitor and determined by the peak point of the projection of the screen.



Performance @ STF (RF Stabilities)



12 ADC channels



RF stability	Vector-sum (8 cavities)	Requirement
$\Delta A/A$ [% rms]	0.006%	0.07%
$\Delta \theta$ [° rms]	0.024°	0.35°

Summary



- LLRF control systems with μ TCA standards have been developed in cERL and STF.
- Performances satisfied our requirements.



Thank you for your attention