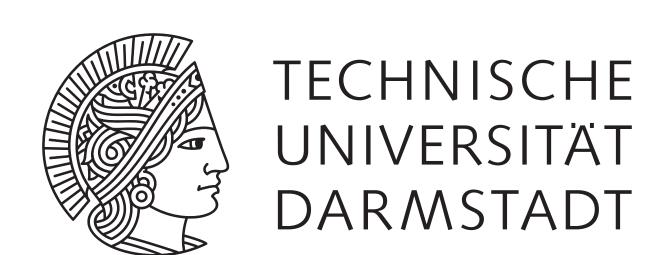
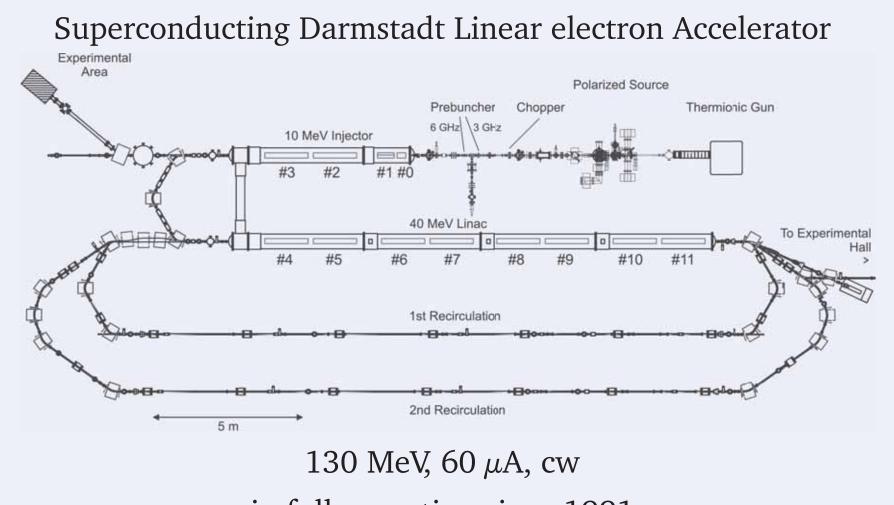
Status of the Migration of the S-DALINAC Accelerator Control System to EPICS*



C. Burandt[†], U. Bonnes, J. Enders, F. Hug, M. Konrad, N. Pietralla

Institut für Kernphysik, Technische Universität Darmstadt, Germany

S-DALINAC

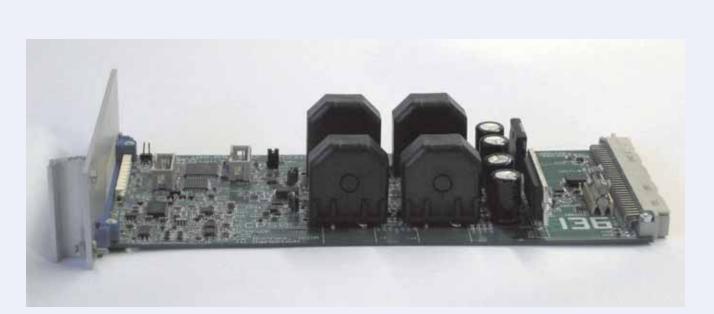


in full operation since 1991 control system formerly based on VME/VxWorks/OpenVMS

Hardware

In-house developed Hardware Family CAN power supplies

- approx. 200 magnet power supplies with $I_{Out} < 10 A$
- few power supplies (5 % of total number) with $I_{Out} > 10 \text{ A}$
- in-house developed preferred for cost reasons

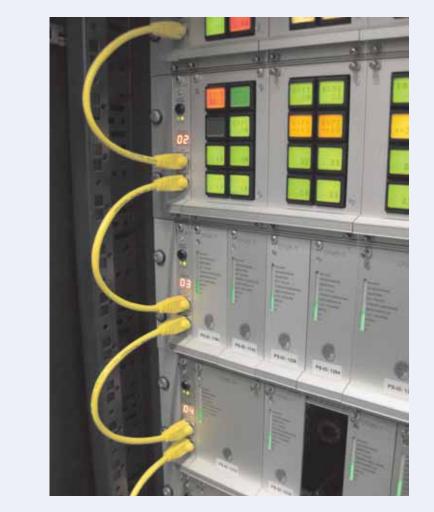


CAN Bus for Communication

- allows connection of multiple devices to one interface
- 1 Mbit/s for distances up to 40 m
- microcontrollers with integrated CAN controller available
- little configuration needed (in comparison to ethernet devices)
- transportable USB interfaces are available and make on-site diagnostics easy
- robust RJ-45 connectors

The Whole Hardware Family

- magnet power supplies
- multi-purpose measurement system
- low-level RF control system
- controller for scintillating screens
- various electronics for experimental sites



Firmware

All devices are equipped with a microcontroller. The firmware is the same for all devices. It determines the type of hardware it is running on and adapts its behaviour accordingly. That is, the commands being individual for each kind of hardware are provided.

EPICS at the S-DALINAC

Why EPICS was chosen

- Linux compatibility
- highly configurable without programming
- no Licence issues

Custom CAN device support

- based on socketCAN stack
- different application can access CAN interface at the same time
- independent of CAN interface device manufacturer
- see dedicated contribution **THPD13**

Custom USB 2.0 device support

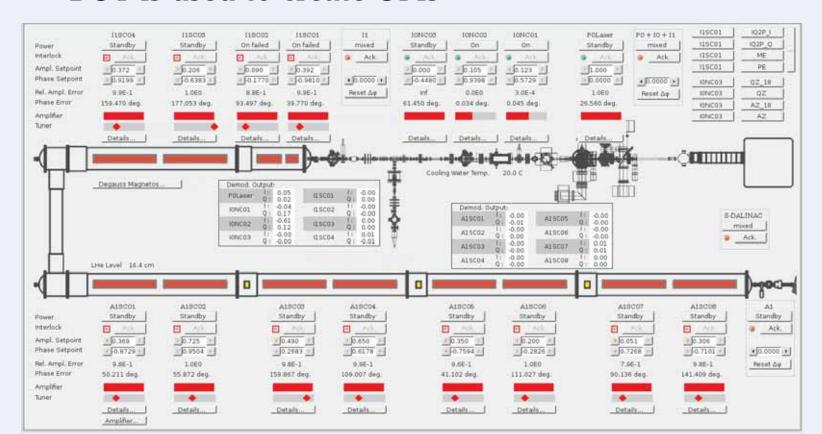
- allows diagnostics for digital low-level RF control system
- full resolution of 18 bit at 1 MS/s
- receives streaming data

Input Output Controller

- configured from relational database
- utilize custom device support or Asyn/StreamDevice
- running on Debian Linux
- one physical or virtual machine per IOC

Operator Interfaces

- Control System Studio
- BOY is used to create OPIs



Custom Rotary Knobs + Touchscreens

- not EPICS compatible yet
- essential for efficient beam optimization



Infrastructure General • Debian FAI (Fully Automated Installation) Build Server **Revision Control** System **Control Room** Bugtracker **PCs** • Wiki Wiki **Automatic Installation** Office **Build Server** Gateway Computers • install production machines **Bug Tracking** within minutes System Database install procedure is LINAC completly documentated and FAI stored in a central place Experiments **EPICS** specific CA Gateway **IOC** installation Archiver with PostgreSQL backend **IOCs** (see dedicated contribution WEPD03) • State Machines (Sequencer)

Summary

Done

- 2 years of successful operation
- several essential subsystems migrated (low-level RF!)
- migration is approximatly 50 % finished

To be done

- magnet power supplies are to be migrated
- operator interfaces: physical rotary knobs
- alarm system toolkit like BEAST



