



OUR PASSION:
To deliver high quality and be respected for that

Control System for New Large Experiments

Rok Sabjan

rok.sabjan@cosylab.com

PCaPAC 2010, Saskatoon, Canada



Thank you for organizing this workshop

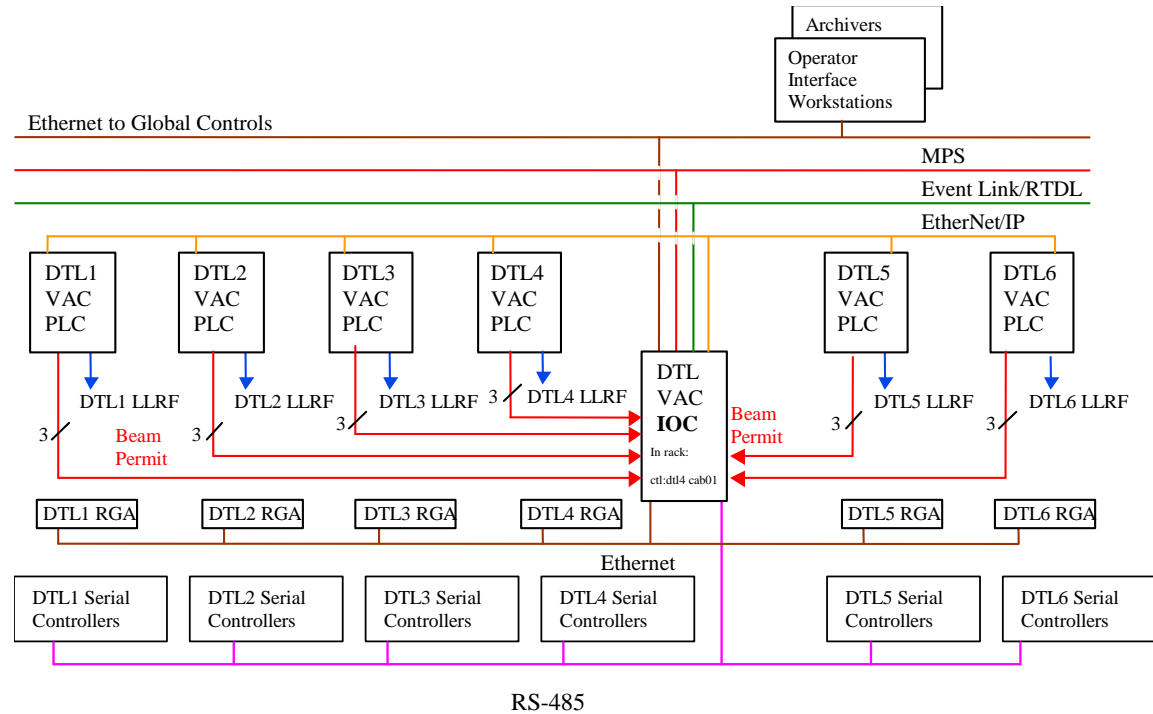


PCaPAC 2008 Group Photo

Change in Control System Development



1980s



Today

What has changed?

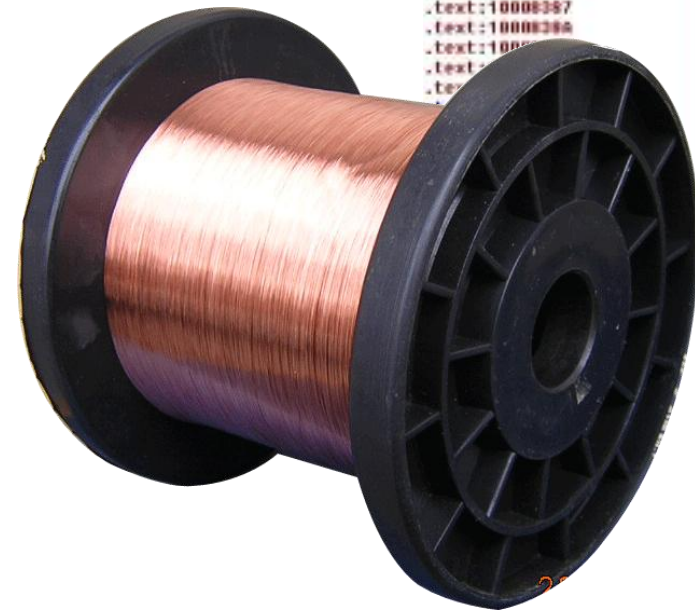
“Ancient history” – build everything yourself



```

ds:GetCurrentThread
[ebp-0004h], eax
push ecx
call ds:Sleep
lea eax, [ebp-0004h]
push eax
lea ecx, [ebp-0004h]
push ecx
lea edx, [ebp-4000h]
push edx
lea eax, [ebp-4000h]
push eax
mov ecx, [ebp-0004h]
push ecx
call ds:GetThreadTimes
mov edx, [ebp+8]
mov byte ptr [edx+3], 0C9h
mov eax, [ebp+8]
mov byte ptr [eax+4], 7
mov ecx, [ebp+8]
mov byte ptr [ecx+5], 0C3h
call sub_10008800
mov edx, [ebp+8]
mov byte ptr [edx+6], 6Ch
mov eax, [ebp+8]
mov byte ptr [eax+7], 52h
mov ecx, [ebp+8]
mov byte ptr [ecx+8], 34h
dword ptr [edx]
lea edx, [ebp-4000h]
mov eax, [ebp-4000h]
mov ecx, [ebp-4000h]
dword ptr [edx]
dword ptr [edx]
byte ptr [edx]
cnp dword ptr [edx]
jz short loc_10008800
mov ecx, [ebp-4000h]
push ecx
call ds:RegCloseKey

```



SDSS TELESCOPE PERFORMANCE MONITOR									
TPM IOC UPTIMES:		2.27 Hours	4097.25 Hours	tpm_v3_5_0		ABOUT			
MJD:		54924	DETAILS	TEMPERATURES	SYSTEM CHECKS	INTERLOCKS	TIME SERIES	Weather	
MINUTES INTO TRACK:		0.00							
		POSITION	ERROR	CURRENT	DEWARS				
ALTITUDE	30.02	6	632	239.50	22.24	1b - SPECTRO - psi			
AZIMUTH	121.00	-35	546	73.00	0.16	1b - IMAGER - psi			
ROTATOR	0.00	2	599			INST ID 1: <input type="text"/> CRPT 5			
						INST ID 2: <input type="text"/> CRPT 5			
						INST ID 3: <input type="text"/> CRPT 5			
M1 Axial A	-0.3290	M1 Lateral F (West)		12.1920					
M1 Axial B	-0.2740	M2 Axial A		18.4420					
M1 Axial C	-0.3360	M2 Axial B		15.4800					
M1 Transverse D	-0.7600	M2 Axial C		13.6640					
M1 Lateral E (East)	10.5918	M2 Y		15.1140					

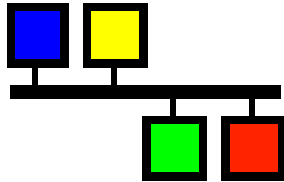
Small markets → unique solutions

Today, we do not start from scratch

- Start by picking the control system package of your choice



EPICS



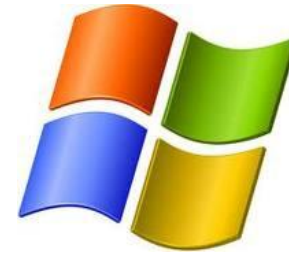
FESA

DOOCS

The Distributed Object Oriented Control System

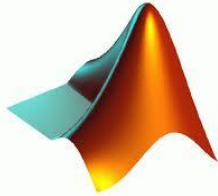


And pick your favorite platform



Standard packages and solutions available

High level applications and machine physics



XAL

Relational DataBases



ORACLE®

Timing systems



Beam Position Monitors



Machine protection systems



... but we have to deliver faster and
with lower budget

- Typically reduced from 10% to 5% of a machine budget
- Limitation on the man-power, need to manage risks
- Only can be achieved with standard, well-tested components AND by focusing on development processes

- Control systems are built from off-the-shelf components, which are getting increasingly more complex
- Complex systems require more integration time
 - Study requirements and technologies
 - Understand interfaces
 - Making choices early in the project
 - Test plans
 - Prototypes
 - Plan B

Integration makes the system work

■ Integration know-how

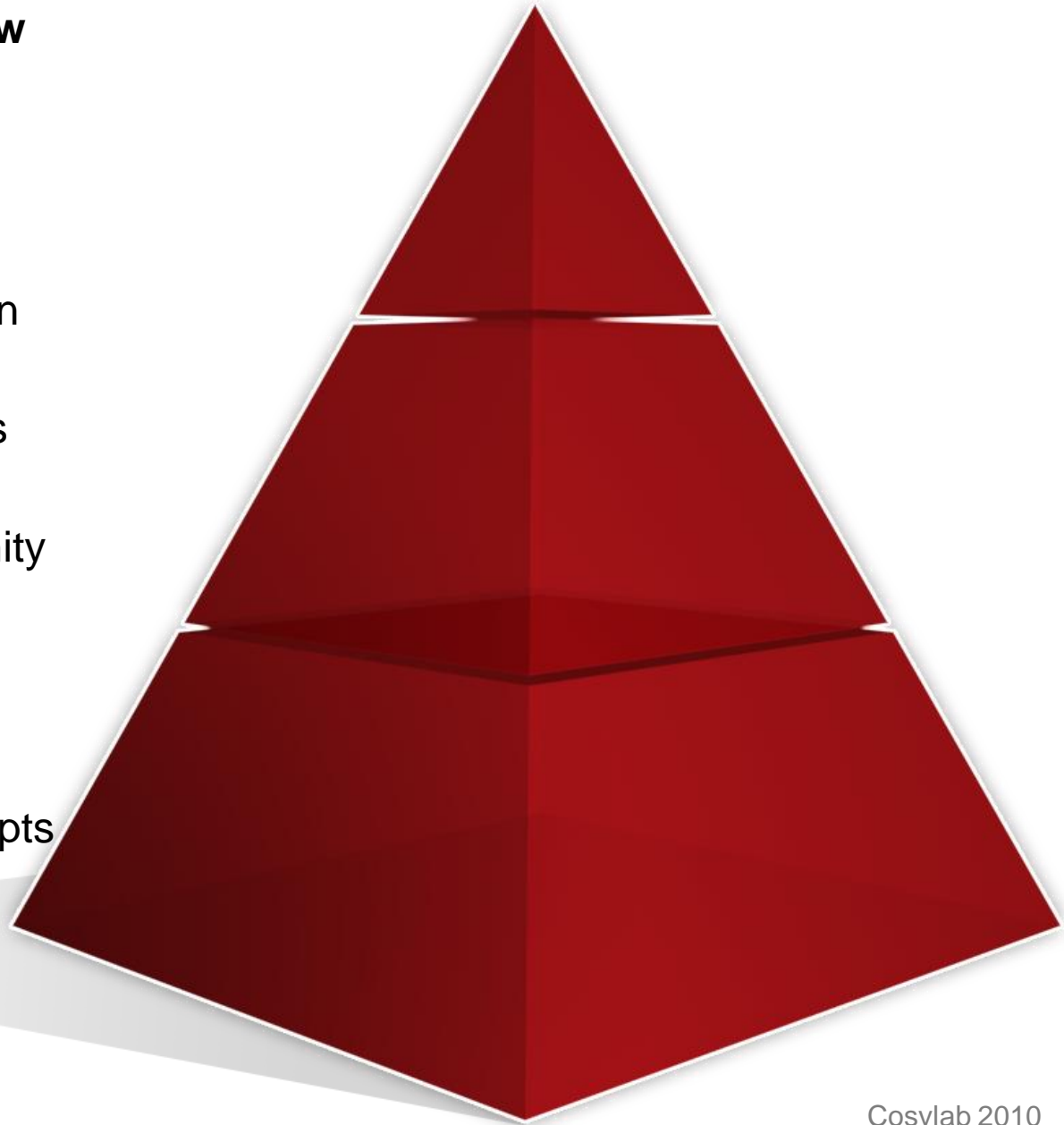
- Understand accelerator / integration
- Best practices

■ Hw/Sw implementation

- FPGAs for geeks
- Coding buzzwords
- network
- COTS or community support

■ Specific domain knowledge

- understand concepts



In every project there are also unsolved issues

- Complex new machines have new use cases
 - Hard Real-time feedback
 - Machine Protection System
 - Timing System
- Examples will show efforts towards standardization of new development

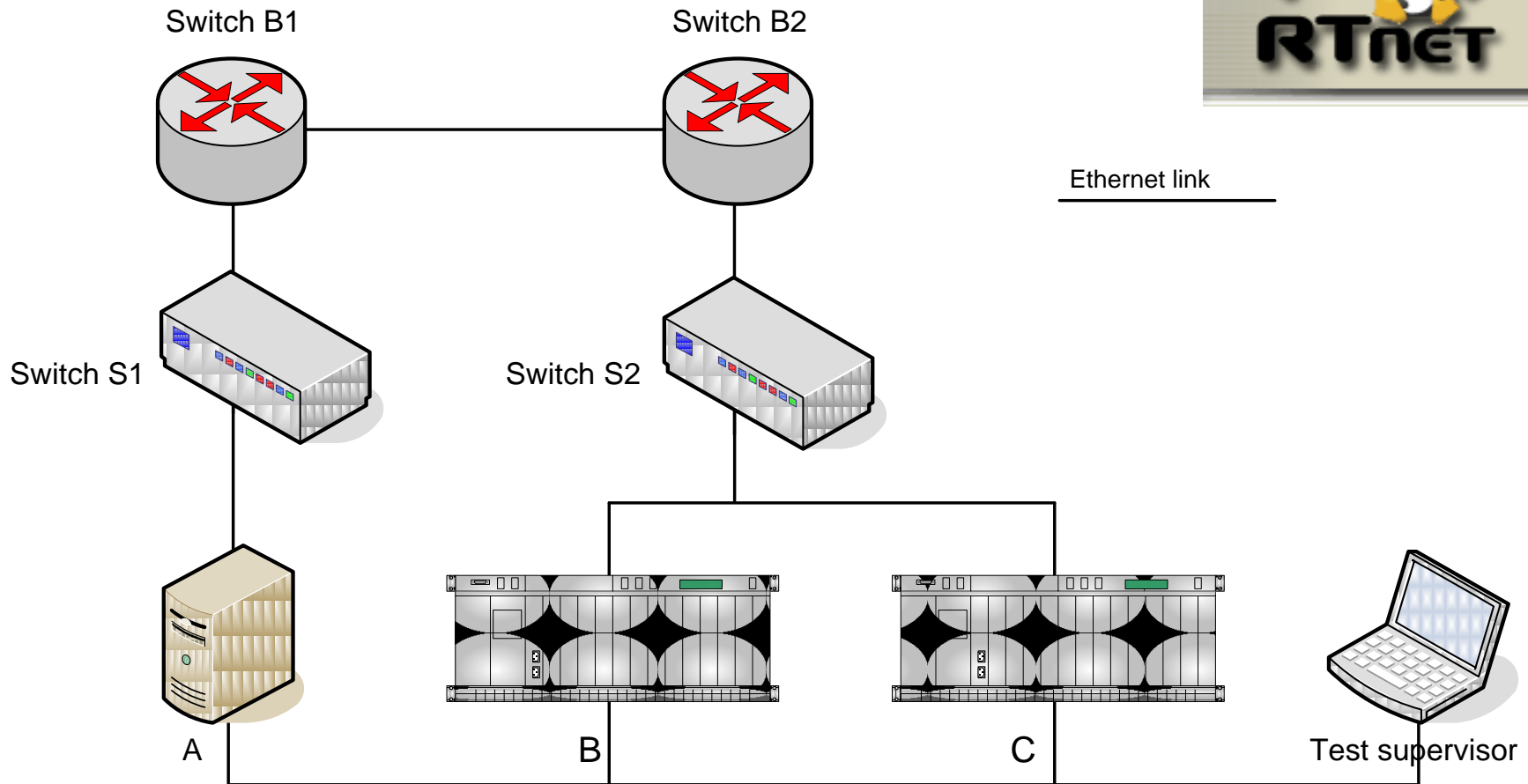
- Existing feedback solutions
 - ☐ Proprietary Reflective Memory
 - ☐ Custom Fast Orbit Feedback solutions

- Synchronous Databus Network (SDN) Evaluation for ITER
 - ☐ Requirements (1 kHz cycle, 40 kB data, 10 usec jitter)
 - ☐ Market research
 - ☐ Demonstrator
 - ☐ Recommendation

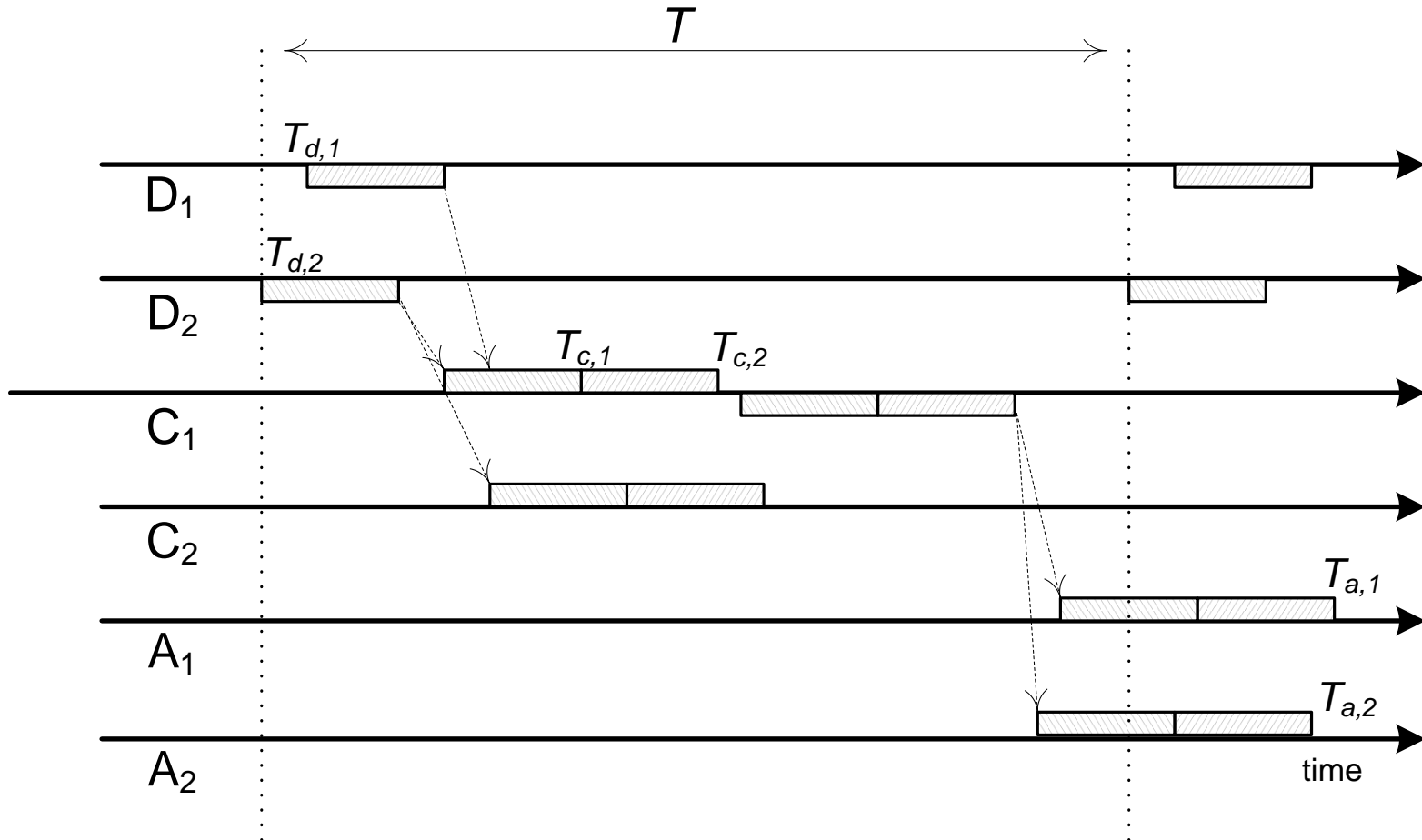
- ☐ We decided to look at Gigabit Ethernet.

ITER SDN – Gigabit Ethernet Evaluation

■ Test stand

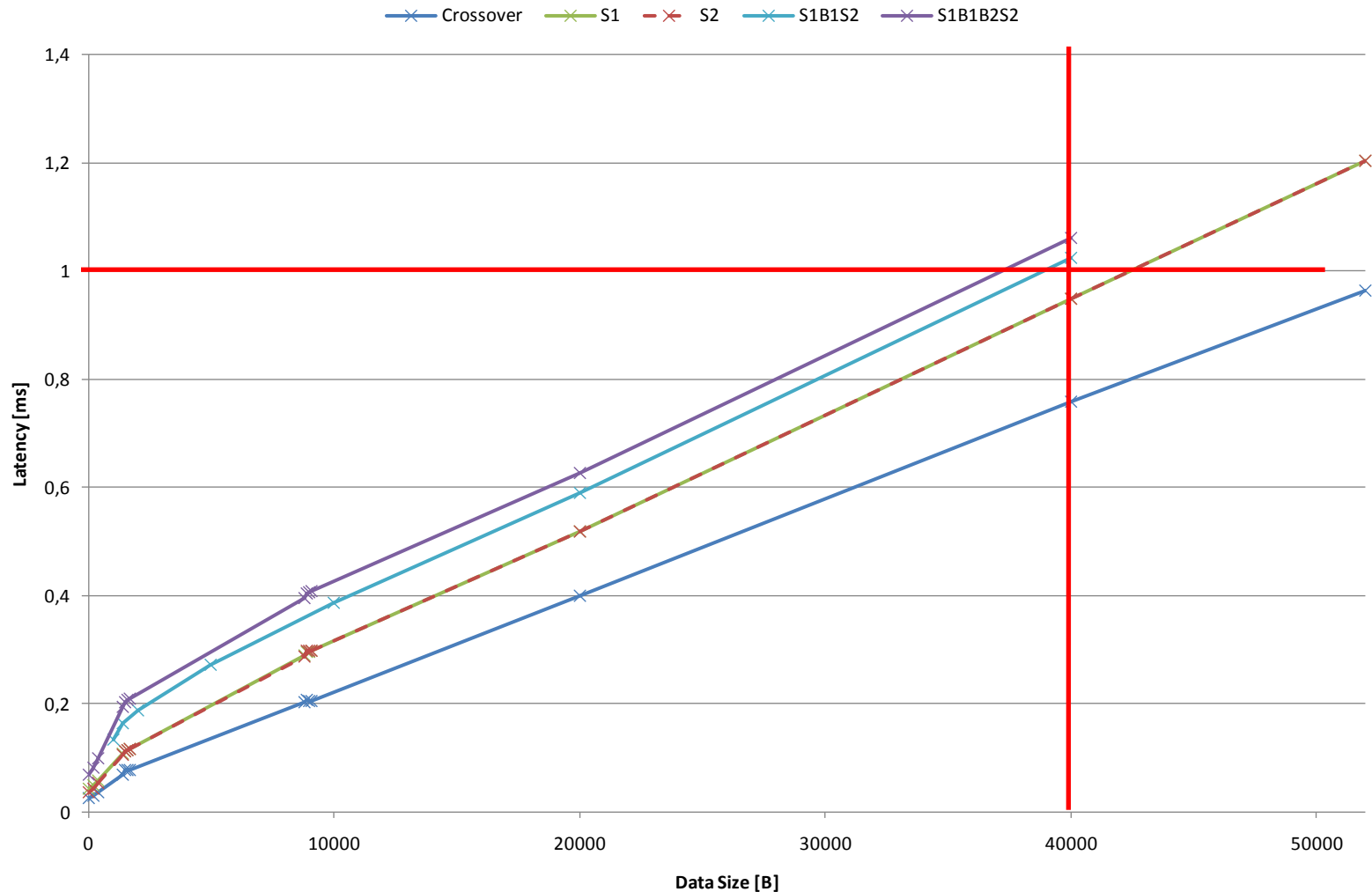


■ Test scenario

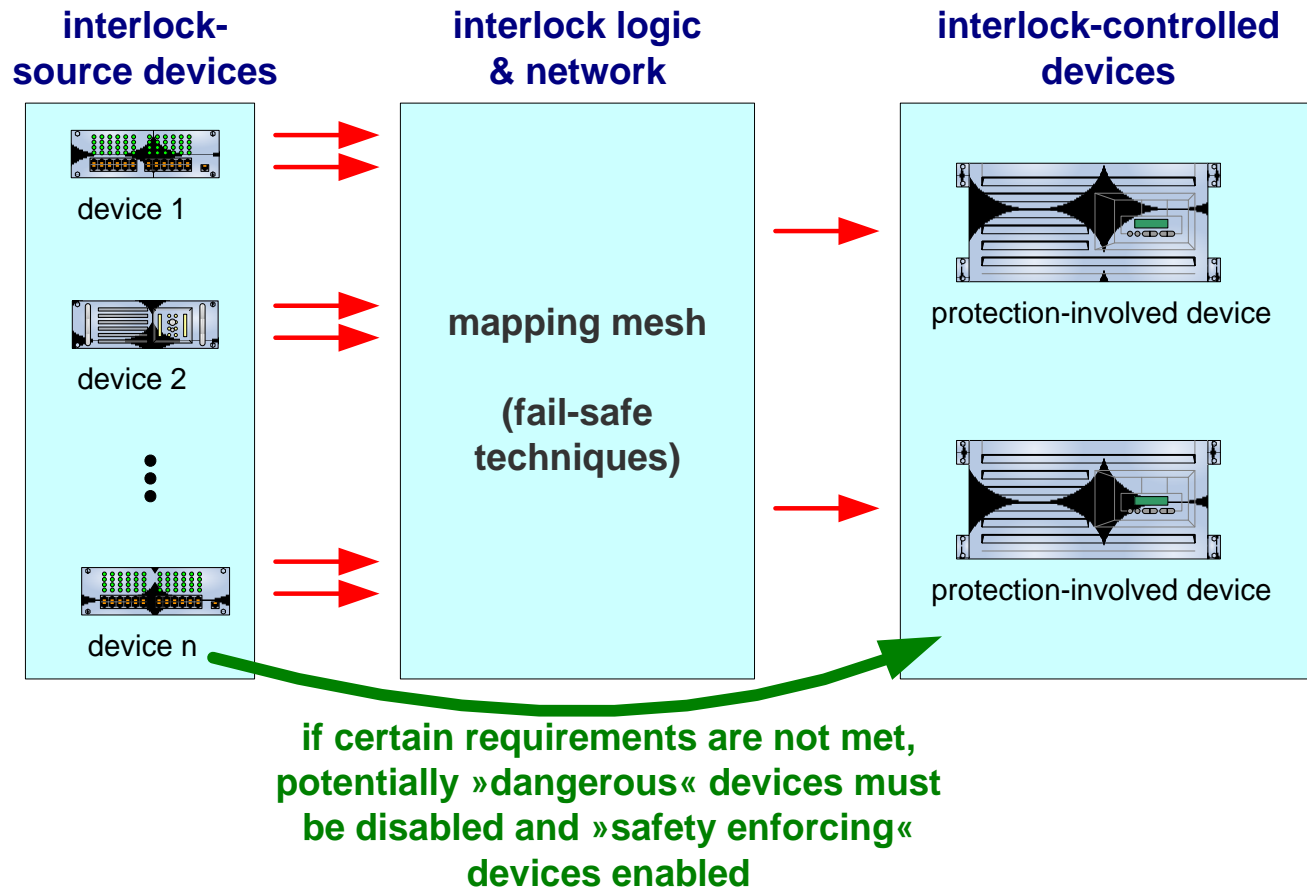


SDN – Gigabit Ethernet Evaluation

- Result: Cycles of 2 kHz and more are achieved with data sizes common in accelerators
- Not good for ITER requirements today, but will be soon

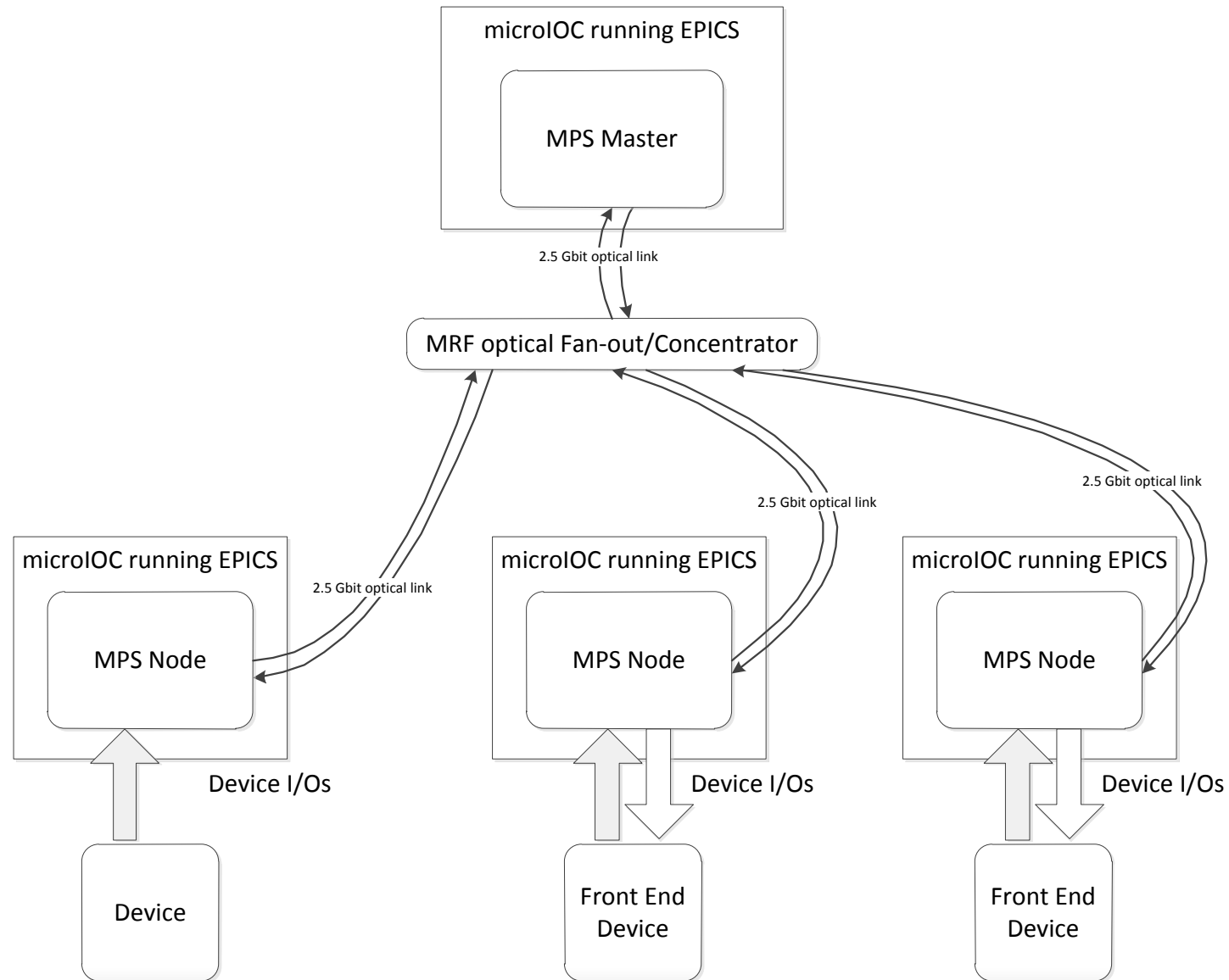


Machine Protection and Interlocks Concept

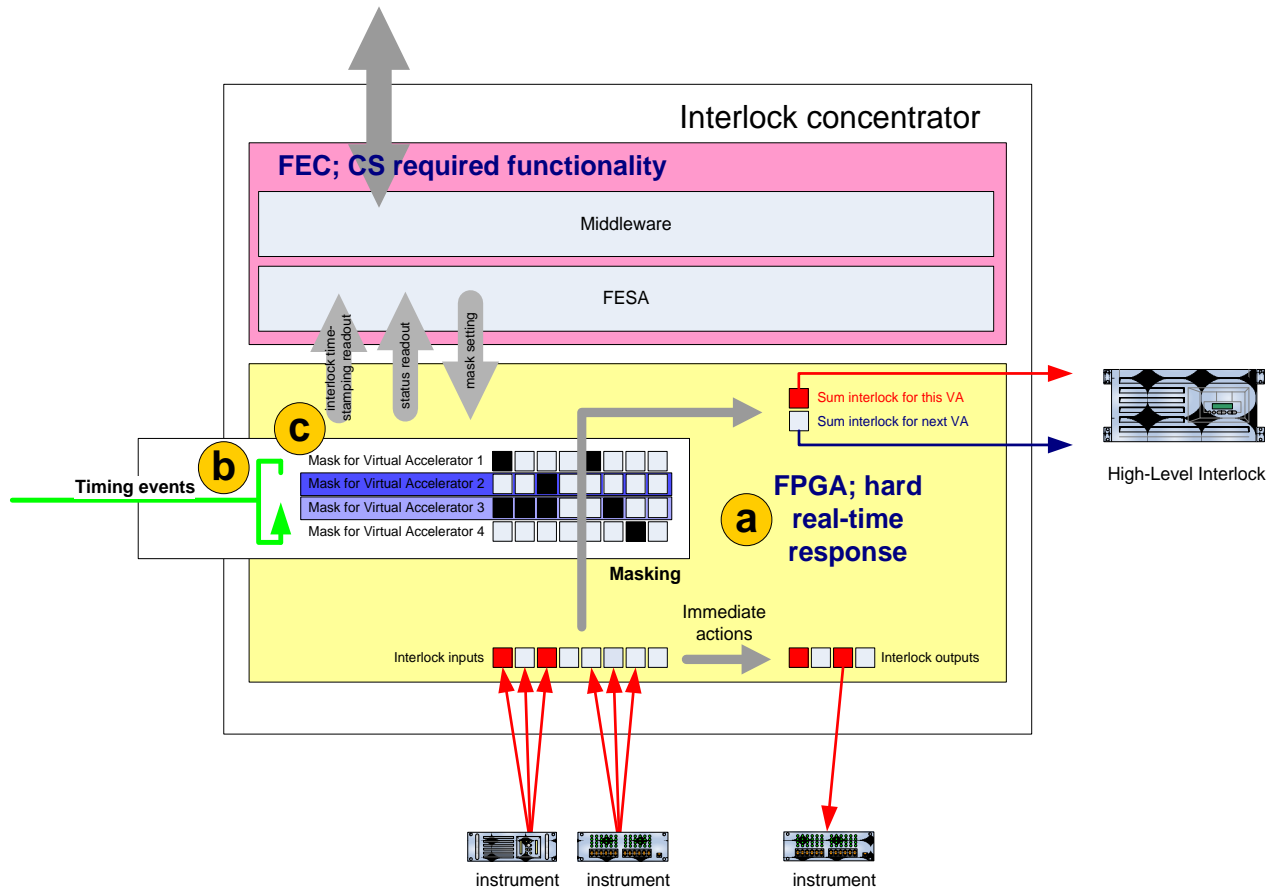


- Monitor device operation and provide **fast** feedback in case of faults
 - Inputs for fault signals
 - Outputs for driving Front End Devices
 - **Reconfigurable I/O matrix (support different common use-cases)**
- Flexibly adapt to machine mode of operation
 - **Bypass certain fault signals or threshold levels**
 - Integration with Control and Timing System ensures real-time adaptation
 - Automatic recovery is able to restore beam
- **Perform operation diagnostics and postmortem analysis**
 - High resolution **logging** of fault signal changes
 - **Timeline** for postmortem dump can be reconstructed
 - Oversee machine and system health
 - Machine health can be monitored by Control System
 - Local displays for troubleshooting and status

Star topology



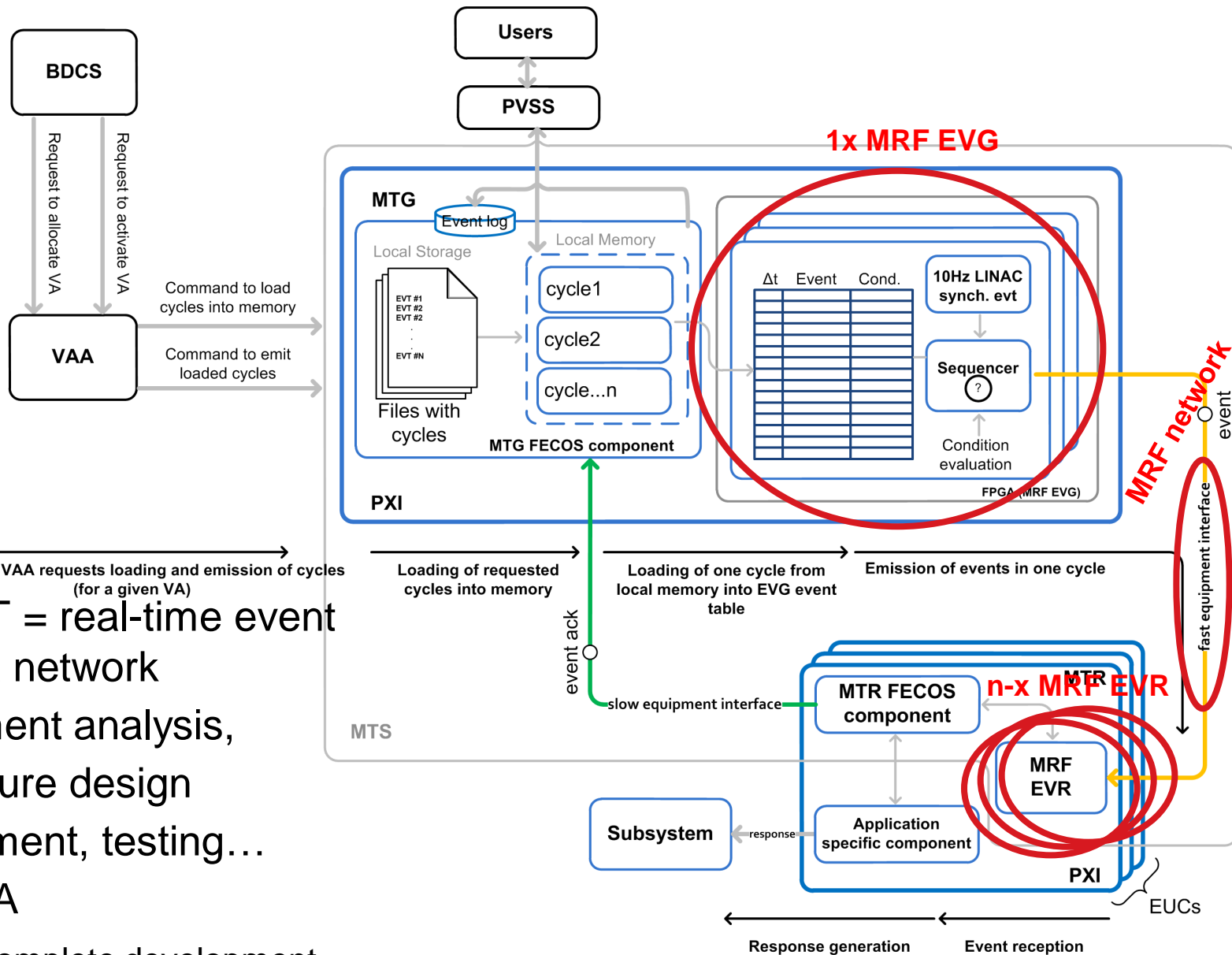
Machine Protection and Interlocks Concentrator/Master



Interlock concentrator schematic overview

- Calculated response times
- System parameters
 - 60 nodes (MPS Nodes) → 9 1-to-8 Fan-Out/Concentrators in two levels
 - 32 inputs per node
 - 1 km of fiber cable between MPS Master and each MPS Node
- Postmortem log resolution: 8 ns
- Local response: ~ 290 ns
- Global response: ~ 11 μ s (10.2 μ s of this is fiber delay)

Example: MedAustron timing integration



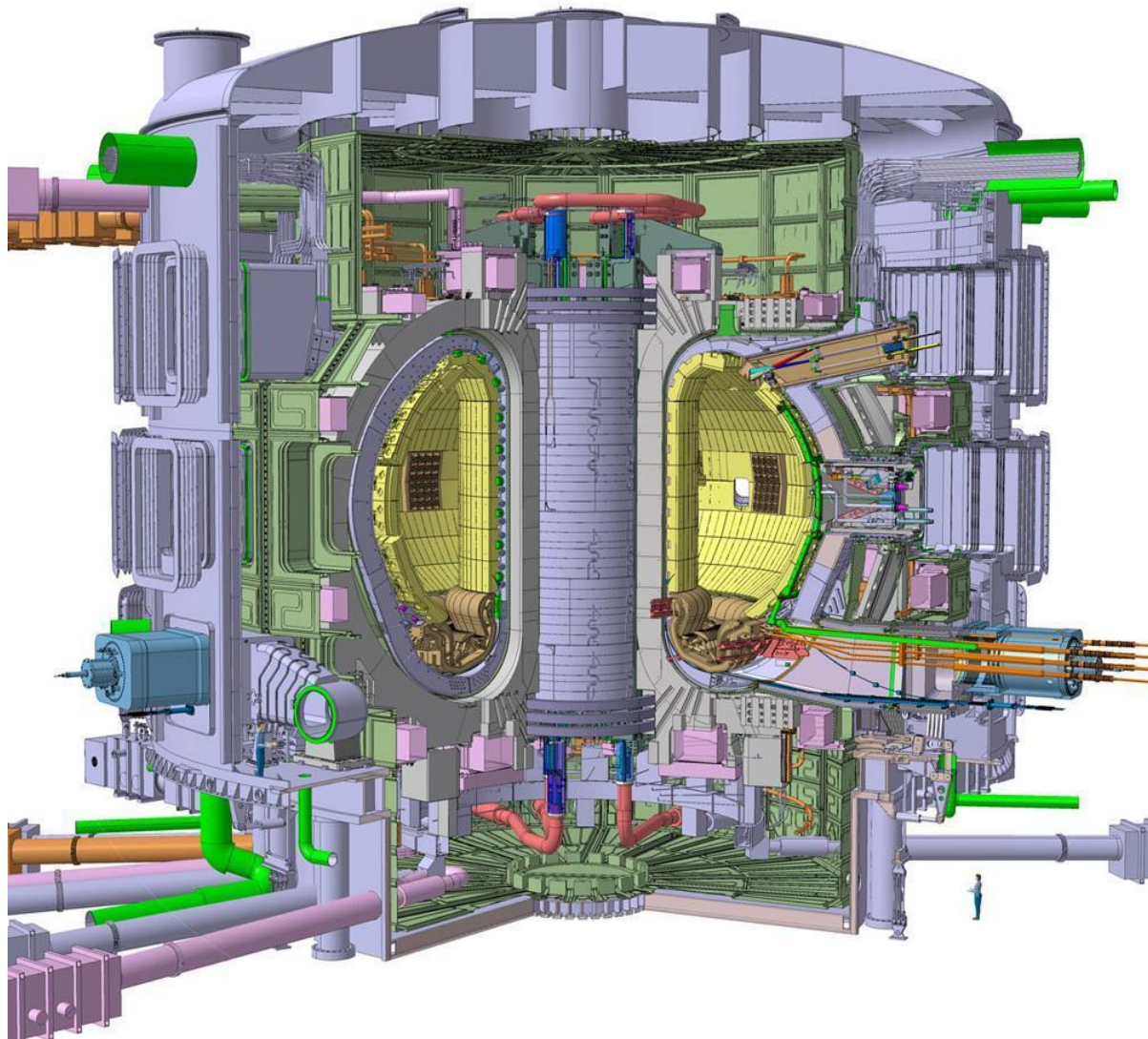
- REDNET = real-time event and data network
- requirement analysis,
- architecture design
- development, testing...
 - FPGA
 - LV (complete development framework)...

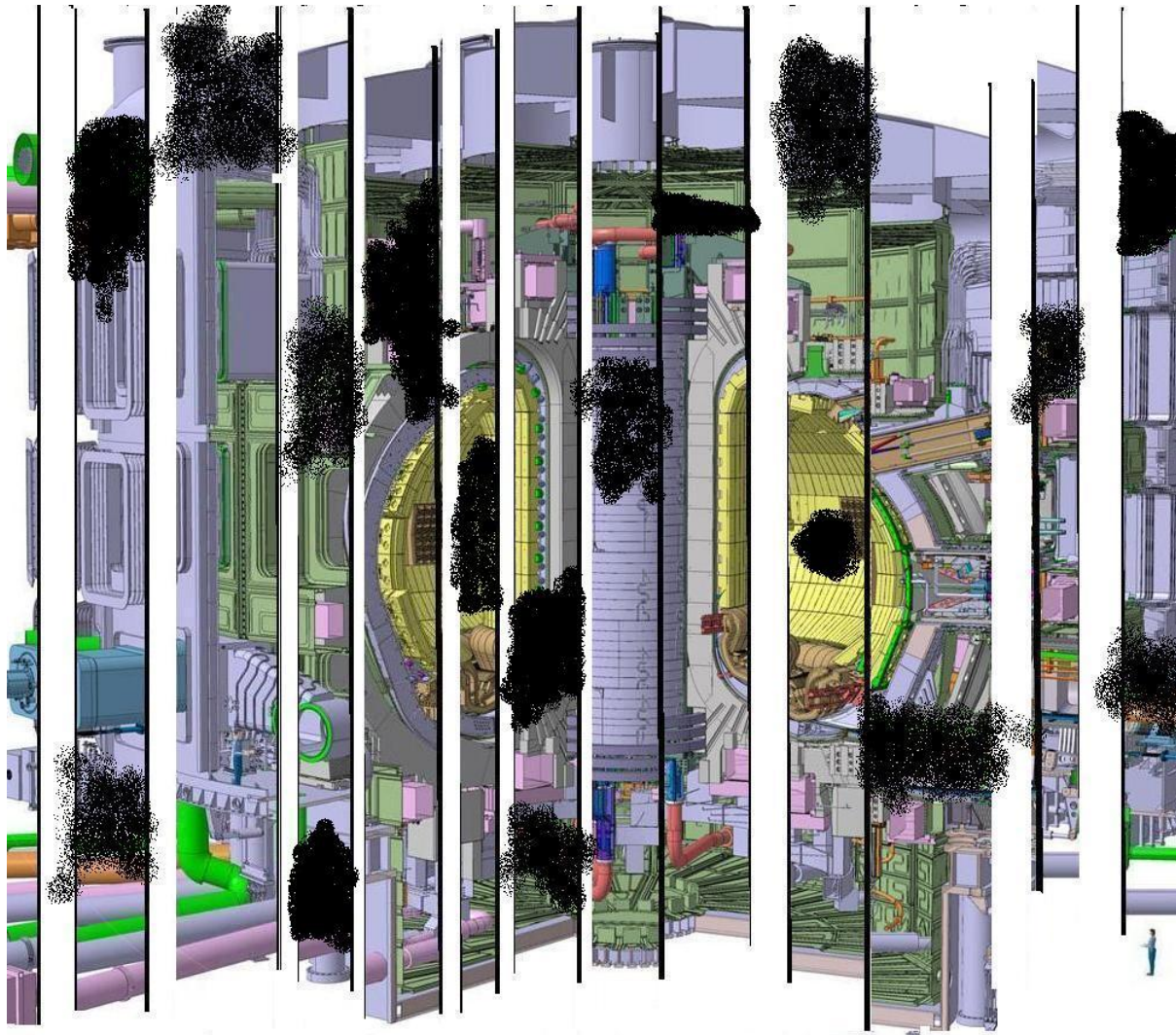
International projects are organizationally more complex

- Dave Gurd: “Building an accelerator at six geographically dispersed sites is quite mad, but politically expedient” (thanks Todd!)
- In-kind contributions
- 100s of developers
- Different culture of developers



china eu india japan korea russia usa

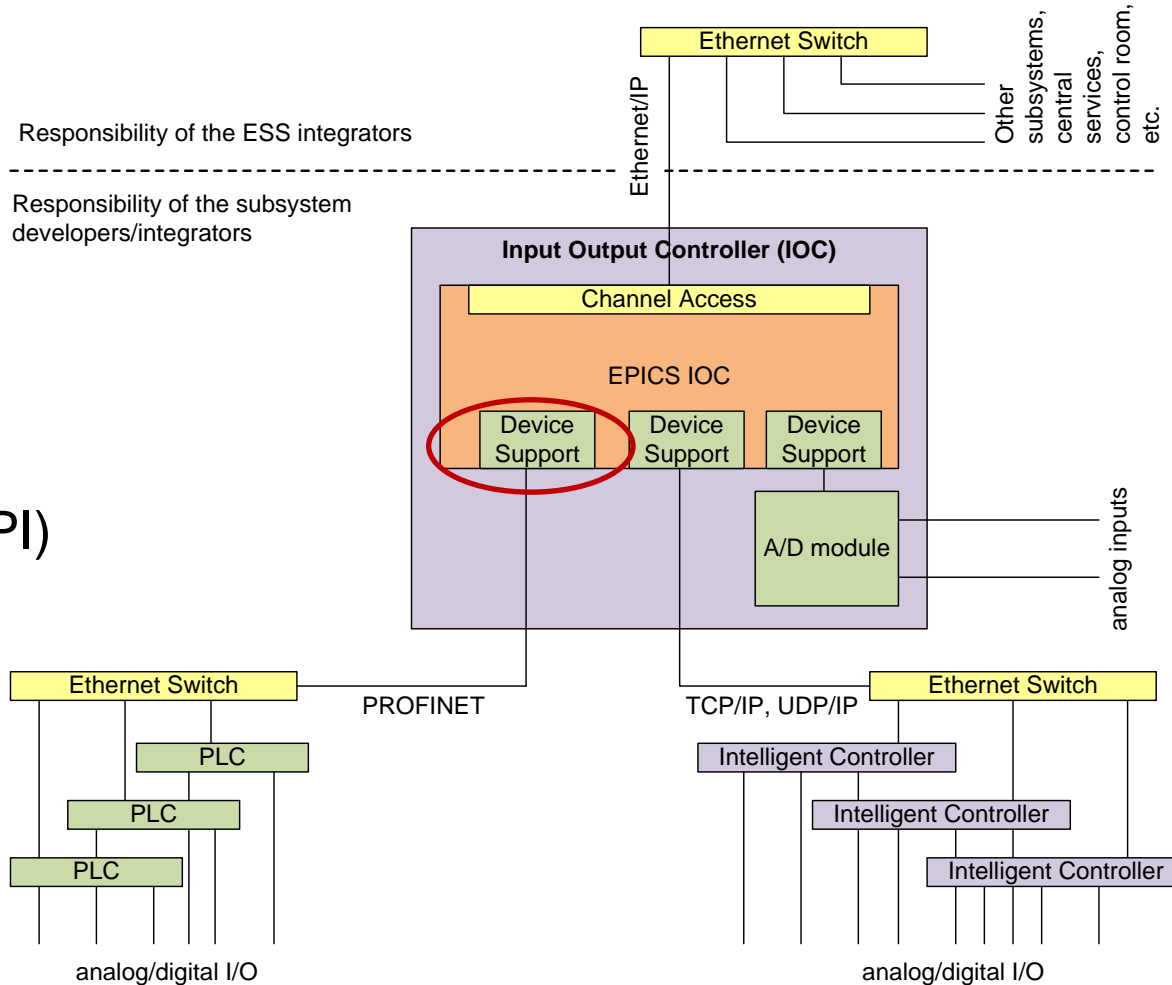




Example: ITER Plant Control Design Handbook & Core System

- Topics covered by the PCDH:
 - Project life-cycle including roles and QA
 - Architecture
 - Naming conventions
 - Software specifications
 - Hardware specifications
- ITER IO provides CODAC Core system, the uniform software package for the development of the plant systems instrumentation & control (I&C) supporting the PCDH standards.

ESS Control Box



■ Control Box

- Hardware
- Software (IOC, OPI)
- Procedures

■ Benefits

- Encourage consistency between sub-systems
 - including target and experimental stations,
- Enable factory acceptance testing of subsystems through control system,
- Validate technology decisions,
- Minimize throw-away hardware and software development

- **Relatively low technical risk**
- **Higher organizational risk**
 - Collaboration of partner institutions
 - Control system comes late in the project
 - Integrates with most of other subsystems
- Control Systems are an **engineering** discipline like all the others, but with an even more complicated cycle
 - Write specifications
 - Architecture
 - Design
 - Prototyping – **fun part**
 - Test procedures
 - Implementation (coding)
 - Documentation
 - Testing
 - Debugging
 - Acceptance
- Iterative development (evolution through upgrade phases)
- Advancement of technologies

What is Really Important in a Control System?

- Don't worry:
 - modern computer technology allows any reasonable implementation of software and hardware to function properly
- So what is really important?
 - To define the development procedures
 - To make everyone agree on the interfaces (API) from the start
 - To have the naming convention ASAP
 - To get test plan and documentation **before** implementation starts
 - Especially important in very large international collaborations, such as ESS, ITER and FAIR.

*Preempt creativity => **Apply the Control Box concept***

The use of the Control Box addresses most of the issues that are important for the CS from a project (and not technical) point of view

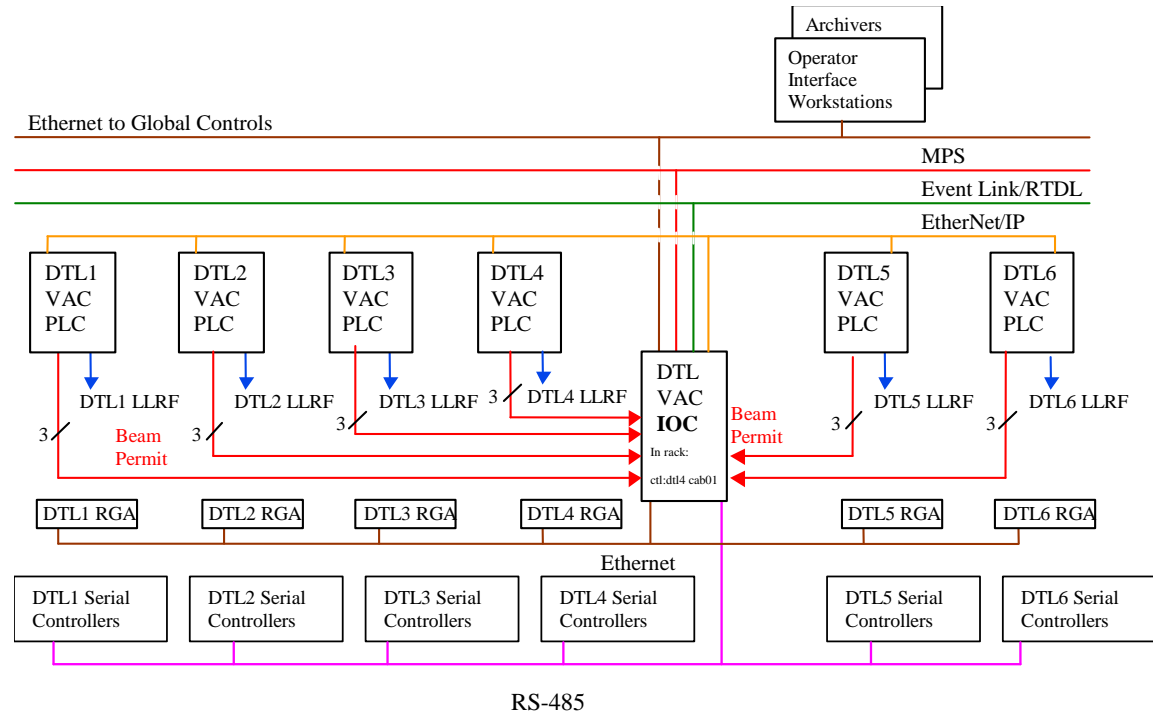
- it allows the individual teams and also the project leadership to establish standards and processes early on in the project.

- Standardization is the key trend
- Integration is the biggest aspect of controls work today
- Organizational risks are increasing with complex projects, focus on development process
- In short, control system development is becoming more and more an engineering discipline and less like a science.

Change in Control System Development



1980s



Today

Thank you!

BACKUP SLIDES

Example Of Interlock Rule For High Power Linac

- Figure: Examples of how beam losses integrated over the previous second may cause rate limiting: A. Pulses 1 through 4 are below threshold but pulse 5 exceeds threshold-3 and sets the beam to a zero rate. B. Pulses 6 through 9 integrate a loss that exceeds threshold-1, lowering the rate to 10 Hz. C. Pulses 12 through 14 integrate a loss that exceeds threshold-2, lowering the rate to 1 Hz.

