

The APS Transfer Line from Linac to Injector Synchrotron*

R. K. Koul and E. Crosbie
Argonne National Laboratory
Advanced Photon Source
9700 South Cass Avenue
Argonne, IL 60439

Abstract

The design of the APS transfer line from linac to injector synchrotron has been completed. The details of this transfer line are given below.

This paper describes the low-energy-transfer-line designed for the APS. The low energy transfer line constitutes two transport lines. One of these lines runs from linac to the positron accumulator ring, also called "PAR", and is 23.7138 m long. The second part of the low energy transport line runs from the "PAR" to the injector synchrotron and is about 30.919 m long. The above length includes two quadrupoles, a bend magnet and a septum magnet in the injector synchrotron (see Fig. 1 and Table 2).

The positron bunches of emittance $\epsilon_N = 6.6$ mm-mrad arriving at the end of the linac at 450 MeV have twiss parameters as given by Nassiri [1].

$$\alpha_x = 1.6808, \beta_x = 7.2161, \alpha_y = -1.77586, \beta_y = 6.6888 \quad (1)$$

The transfer line (see also Yoon and Crosbie [2]) from linac to "PAR" is made up of ten quadrupoles and one bending magnet B4 (see Fig. 1). The bending magnet bends the beam by 0.2 radians towards the septum magnet in the "PAR". The five quadrupoles in the region between the bend magnet and the septum magnet in the "PAR" give a phase shift of 2π radians, in order to get dispersion free bunch at the end of the septum magnet. The twiss parameters at the end of the linac given above are matched with the twiss parameters and the dispersion functions at the end of the septum magnet, in the "PAR" lattice structure. These parameters at the end of the "PAR" septum are given by

$$\alpha_x = -0.94910, \beta_x = 2.1261, \alpha_y = -0.02429, \\ \beta_y = 8.2401, \eta_x = 0.0, \eta'_x = 0.0 \quad (2)$$

The matching procedure was carried out using computer code "COMFORT". The distance (2.9 m) between the last quadrupole and the septum magnet in the "PAR" is fixed because of the considerations of the available space in that region. The layout of this region of the transfer line is shown in Fig. 1.

Details of the magnet dimensions and their strengths are

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given in Table 1. The order of the magnets is the order in which they appear in the transfer line as one traverses from the linac to "PAR". The β functions in the horizontal and the vertical plane along with the dispersion function, η , in the horizontal plane are shown in Fig. 2. The maximum β_y is approximately 20 m and occurs at the quadrupole before the bend magnet. The maximum value of the β_x is about 16 m.

In addition to the above elements, the linac to "PAR" part of the low energy transfer line contains eight steering magnets and seven beam position monitors. Of the eight steering magnets four are for steering in the horizontal plane and the remaining four are to be used for steering in the vertical plane. Similarly, out of the seven beam position monitors three are to be used for diagnostics in the horizontal plane and the remaining four for diagnostics in the vertical plane. The relative positions of these steering magnets are also given in Fig. 1. The calculations for the strength and the dimension of these steering magnets was carried out using a computer code locally developed for this purpose. However the code was tested for the calculation of twiss parameters against the "COMFORT" run.

The second part of the low energy transport line carries the positron bunches from the "PAR" septum to the injector synchrotron. Again the energy of the positron bunches is about 450 MeV. This section is made up of two bend magnets (B1, B2), and eleven quadrupoles joining the "PAR" septum magnet "B3" on the one end and the injector synchrotron septum magnet on the other end. The bend magnet B2 bends the bunch, coming from the "PAR" septum magnet (bend angle of -0.2 radians) through an angle of 0.2 radians. The section between the bend magnet B2 and the septum magnet B3 is the same as the section between the bend magnet B4 and the septum magnet B3. It produces a dispersion free beam in the region between B2 and B1. The next section between bending magnet B2 and the bending magnet B1 has four quadrupoles which can be used as tuning quadrupoles for tuning on to four twiss parameters in the vertical and horizontal direction. The bend magnet B1 bends the beam at an angle of approximately -0.1859 radians towards the injector synchrotron septum. There are two quadrupoles in the section between the bend magnet B1 and the injector synchrotron septum, which are arranged such that the bunches entering the injector synchrotron are dispersion free at the end of the dipole magnet B (see Table 2). The detailed layout can be seen in Fig. 1, and the relative positions, the dimensions and the strengths of the magnets are given in Table 2. The maximum value of the β function from B2 to the injector synchrotron septum is about 26 m. In

designing the transfer line from the "PAR" to the injector synchrotron, some part of the injector synchrotron is included. The twiss parameters given by the injector synchrotron lattice at the beginning of the drift O1 (see Table 2) are matched with the twiss parameters given at the beginning of the "PAR" septum magnet given above (sign of the α function must be reversed) through the transfer line. Again, the computer code "COMFORT" was used for matching purposes. The twiss parameters at the position O1 are given below. The sign of the α function corresponds to the motion from "PAR" to the injector synchrotron.

$$\alpha_x = 0.4620, \beta_x = 2.1724, \alpha_y = -2.5084, \beta_y = 15.6557 \quad (3)$$

The detailed form of the β_x , β_y and the η_x is given in Fig. 3. In addition to the above components this part of the transfer line contains six steering magnets and seven beam position monitors. Of the six steering magnets, three are used for steering in the horizontal direction and the remaining three in the vertical direction. Similarly, of the seven beam position monitors four are to be used for monitoring the horizontal position and the remaining three for monitoring the vertical position. The maximum $B\ell = 0.012$ T.m for these steering magnets. These calculations were also carried out using the locally developed code. The details of their positions and other parameters are given in the Table 2.

Table 1
LTOP Parameters

(150 MeV, $B\rho = 1.503$ T-meter, -Positive K_1 means horizontal defocussing.)
Input Twiss Parameters: $\alpha_x = 1.6808, \beta_x = 7.2161, \alpha_y = -1.7586, \beta_y = 6.6888$
Output Twiss Parameters: $\alpha_x = -0.0919, \beta_x = 2.1261, \alpha_y = -0.0213, \beta_y = 8.2101$

Element	Length	# of Magnet Strength $K_1 = B/\rho[m]^{-1} \cdot \beta[m]$	Theta1	Theta2
DRIFT O1	1.01			
Steering _x	0.02	0.18		
DRIFT O1	0.1			
QUAD Q1	0.3	1.2518191		
DRIFT O2	2.28			
QUAD Q2	0.3	-0.72191915		
DRIFT O3	0.1			
Steering _y	0.05	0.18		
DRIFT O3	0.05			
QUAD Q3	0.3	-1.2215308		
DRIFT O4	7.01			
BPM _x	0.1			
DRIFT O4	0.1			
QUAD Q4	0.3	2.2227231		
DRIFT O5	0.1			
Steering _x	0.05	0.18		
DRIFT O5	0.05			
SEC'D B2	0.1	0.2	0.1	0.1
DRIFT O6	0.40			
BPM _y	0.1			
DRIFT O7	0.1			
QUAD Q5	0.3	-2.9556007		
DRIFT O8	0.1			
Steering _y	0.05	0.18		
DRIFT O8	0.05			
SEC'D B2	0.1	0.2	0.1	0.1
DRIFT O9	0.40			
BPM _x	0.1			
DRIFT O9	0.1			
QUAD Q6	0.3	1.1366163		
DRIFT O10	0.1			
Steering _x	0.05	0.18		
DRIFT O10	0.05			
BPM _y	0.1			
DRIFT O11	0.1			
QUAD Q7	0.3	-1.87910321		
DRIFT O12	0.1			
Steering _y	0.05	0.18		
DRIFT O12	0.05			
BPM _x	0.1			
DRIFT O13	0.1			
QUAD Q8	0.3	1.1366163		
DRIFT O14	0.1			
Steering _x	0.05	0.18		
DRIFT O14	0.05			
BPM _y	0.1			
DRIFT O15	0.1			
QUAD Q9	0.3	-2.32101118		
DRIFT O16	0.1			
Steering _y	0.05	0.18		
DRIFT O16	0.05			
BPM _x	0.1			
DRIFT O17	0.1			
QUAD Q10	0.3	2.1505532		
DRIFT O18	0.1			
Steering _x	0.05	0.18		
DRIFT O18	0.05			
BPM _y	0.1			
DRIFT O19	0.1			
QUAD Q11	0.3	2.7150532		
DRIFT O20	0.1			
Steering _y	0.05	0.18		
DRIFT O20	0.05			
BPM _x	0.1			
DRIFT O21	0.1			
QUAD Q12	0.3	-1.87910321		
DRIFT O22	0.1			
Steering _x	0.05	0.18		
DRIFT O22	0.05			
BPM _y	0.1			
DRIFT O23	0.1			
QUAD Q13	0.3	0.318257169		
DRIFT O24	0.1			
BPM _x	0.1			
DRIFT O25	0.1			
QUAD Q14	0.3	-3.61756031		
DRIFT O26	0.1			
Steering _y	0.05	0.21		
DRIFT O26	0.05			
BPM _y	0.1			
DRIFT O27	0.1			
QUAD Q15	0.3	10.2311		
DRIFT O28	0.1			
Steering _x	0.05	0.07		
DRIFT O28	0.05			
BPM _x	0.1			
DRIFT O29	0.1			
QUAD Q16	0.3	-1.87910321		
DRIFT O30	0.1			
Steering _y	0.05	0.133		
DRIFT O30	0.05			
BPM _y	0.1			
DRIFT O31	0.1			
QUAD Q17	0.3	-1.87910321		
DRIFT O32	0.1			
Steering _x	0.05	0.13		
DRIFT O32	0.05			
BPM _x	0.1			
DRIFT O33	0.1			
QUAD Q18	0.3	4.13661613		
DRIFT O34	0.1			
Steering _y	0.05	0.13		
DRIFT O34	0.05			
BPM _y	0.1			
DRIFT O35	0.1			
QUAD Q19	0.3	-1.87910321		
DRIFT O36	0.1			
Steering _x	0.05	0.13		
DRIFT O36	0.05			
BPM _x	0.1			
DRIFT O37	0.1			
QUAD Q20	0.3	2.33513532		
DRIFT O38	0.1			
Steering _y	0.05	0.18		
DRIFT O38	0.05			
BPM _y	0.1			
DRIFT O39	0.1			
QUAD Q21	0.3	-2.32101118		
DRIFT O40	0.1			
Steering _x	0.05	0.18		
DRIFT O40	0.05			
BPM _x	0.1			
DRIFT O41	0.1			
QUAD Q22	0.3	2.33513532		
DRIFT O42	0.1			
Steering _y	0.05	0.18		
DRIFT O42	0.05			
BPM _y	0.1			
DRIFT O43	0.1			
QUAD Q23	0.3	-2.32101118		
DRIFT O44	0.1			
Steering _x	0.05	0.18		
DRIFT O44	0.05			
BPM _x	0.1			
DRIFT O45	0.1			
QUAD Q24	0.3	2.33513532		
DRIFT O46	0.1			
Steering _y	0.05	0.18		
DRIFT O46	0.05			
BPM _y	0.1			
DRIFT O47	0.1			
QUAD Q25	0.3	-2.32101118		
DRIFT O48	0.1			
Steering _x	0.05	0.18		
DRIFT O48	0.05			
BPM _x	0.1			
DRIFT O49	0.1			
QUAD Q26	0.3	2.33513532		
DRIFT O50	0.1			
Steering _y	0.05	0.18		
DRIFT O50	0.05			
BPM _y	0.1			
DRIFT O51	0.1			
QUAD Q27	0.3	-2.32101118		
DRIFT O52	0.1			
Steering _x	0.05	0.18		
DRIFT O52	0.05			
BPM _x	0.1			
DRIFT O53	0.1			
QUAD Q28	0.3	2.33513532		
DRIFT O54	0.1			
Steering _y	0.05	0.18		
DRIFT O54	0.05			
BPM _y	0.1			
DRIFT O55	0.1			
QUAD Q29	0.3	-2.32101118		
DRIFT O56	0.1			
Steering _x	0.05	0.18		
DRIFT O56	0.05			
BPM _x	0.1			
DRIFT O57	0.1			
QUAD Q30	0.3	2.33513532		
DRIFT O58	0.1			
Steering _y	0.05	0.18		
DRIFT O58	0.05			
BPM _y	0.1			
DRIFT O59	0.1			
QUAD Q31	0.3	-2.32101118		
DRIFT O60	0.1			
Steering _x	0.05	0.18		
DRIFT O60	0.05			
BPM _x	0.1			
DRIFT O61	0.1			
QUAD Q32	0.3	2.33513532		
DRIFT O62	0.1			
Steering _y	0.05	0.18		
DRIFT O62	0.05			
BPM _y	0.1			
DRIFT O63	0.1			
QUAD Q33	0.3	-2.32101118		
DRIFT O64	0.1			
Steering _x	0.05	0.18		
DRIFT O64	0.05			
BPM _x	0.1			
DRIFT O65	0.1			
QUAD Q34	0.3	2.33513532		
DRIFT O66	0.1			
Steering _y	0.05	0.18		
DRIFT O66	0.05			
BPM _y	0.1			
DRIFT O67	0.1			
QUAD Q35	0.3	-2.32101118		
DRIFT O68	0.1			
Steering _x	0.05	0.18		
DRIFT O68	0.05			
BPM _x	0.1			
DRIFT O69	0.1			
QUAD Q36	0.3	2.33513532		
DRIFT O70	0.1			
Steering _y	0.05	0.18		
DRIFT O70	0.05			
BPM _y	0.1			
DRIFT O71	0.1			
QUAD Q37	0.3	-2.32101118		
DRIFT O72	0.1			
Steering _x	0.05	0.18		
DRIFT O72	0.05			
BPM _x	0.1			
DRIFT O73	0.1			
QUAD Q38	0.3	2.33513532		
DRIFT O74	0.1			
Steering _y	0.05	0.18		
DRIFT O74	0.05			
BPM _y	0.1			
DRIFT O75	0.1			
QUAD Q39	0.3	-2.32101118		
DRIFT O76	0.1			
Steering _x	0.05	0.18		
DRIFT O76	0.05			
BPM _x	0.1			
DRIFT O77	0.1			
QUAD Q40	0.3	2.33513532		
DRIFT O78	0.1			
Steering _y	0.05	0.18		
DRIFT O78	0.05			
BPM _y	0.1			
DRIFT O79	0.1			
QUAD Q41	0.3	-2.32101118		
DRIFT O80	0.1			
Steering _x	0.05	0.18		
DRIFT O80	0.05			
BPM _x	0.1			
DRIFT O81	0.1			
QUAD Q42	0.3	2.33513532		
DRIFT O82	0.1			
Steering _y	0.05	0.18		
DRIFT O82	0.05			
BPM _y	0.1			
DRIFT O83	0.1			
QUAD Q43	0.3	-2.32101118		
DRIFT O84	0.1			
Steering _x	0.05	0.18		
DRIFT O84	0.05			
BPM _x	0.1			
DRIFT O85	0.1			
QUAD Q44	0.3	2.33513532		
DRIFT O86	0.1			
Steering _y	0.05	0.18		
DRIFT O86	0.05			
BPM _y	0.1			
DRIFT O87	0.1			
QUAD Q45	0.3	-2.32101118		
DRIFT O88	0.1			
Steering _x	0.05	0.18		
DRIFT O88	0.05			
BPM _x	0.1			
DRIFT O89	0.1			
QUAD Q46	0.3	2.33513532		
DRIFT O90	0.1			
Steering _y	0.05	0.18		
DRIFT O90	0.05			
BPM _y	0.1			
DRIFT O91	0.1			
QUAD Q47	0.3	-2.32101118		
DRIFT O92	0.1			
Steering _x	0.05	0.18		
DRIFT O92	0.05			
BPM _x	0.1			
DRIFT O93	0.1			
QUAD Q48	0.3	2.33513532		
DRIFT O94	0.1			
Steering _y	0.05	0.18		
DRIFT O94	0.05			
BPM _y	0.1			
DRIFT O95	0.1			
QUAD Q49	0.3	-2.32101118		
DRIFT O96	0.1			
Steering _x	0.05	0.18		
DRIFT O96	0.05			
BPM _x	0.1			
DRIFT O97	0.1			
QUAD Q50	0.3	2.33513532		
DRIFT O98	0.1			
Steering _y	0.05	0.18		
DRIFT O98	0.05			
BPM _y	0.1			
DRIFT O99	0.1			
QUAD Q51	0.3	-2.32101118		
DRIFT O100	0.1			
Steering _x	0.05	0.18		

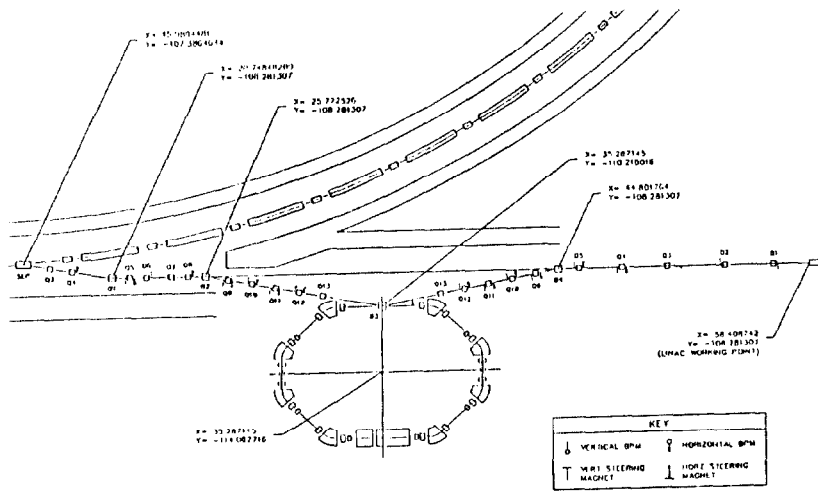


Figure 1. Low Energy Transport Line

FIG

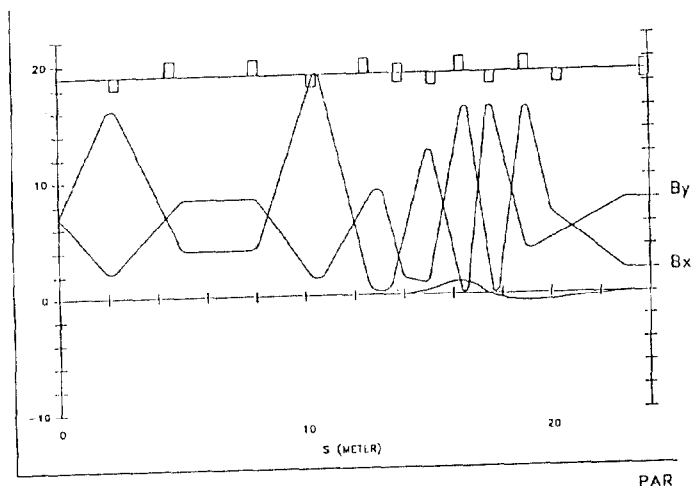


Figure 2. Matching Between Linac and Accumulator

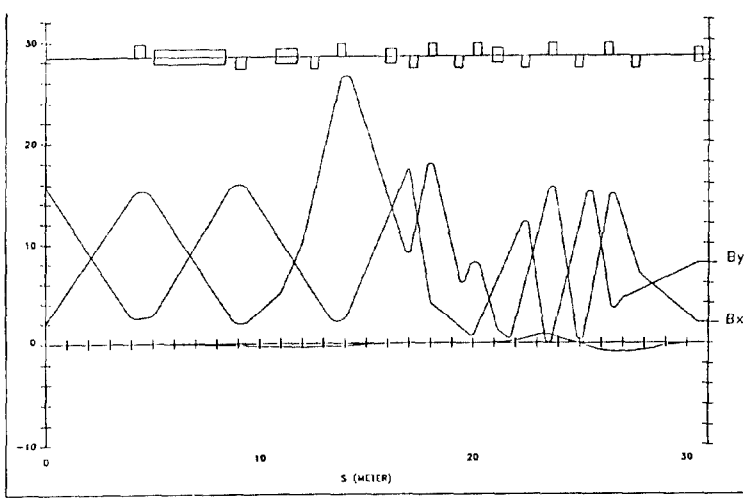


Figure 3. Booster - PAR (PTOB)