# Phase Space Distribution of Particles Near an Isolated Difference Resonance

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## Abstract

We have studied the phase space distribution of beam particles near an isolated difference resonance. The numerical simulation has shown that the distribution can quickly settle down to a final state if its initial state is Gaussian. The final state can be treated as a stationary state as long as the high order fluctuation can be neglected. From the Liouville equation, the emittances of beam particles are calculated approximately. There is a good agreement between analytical and numerical results.

# 1 Introduction

In the system with two degrees of freedom and time dependence, an isolated difference resonance does not lead to an instability, i.e., the motion is always confined in both xand y directions.<sup>1,2</sup> For a beam of particles, therefore, the emittances in two directions are bounded. Due to the coupling, however, the energy could be transferred from one direction to the other. As a result, an initially very small emittance in one direction could grow to a large value. Even though this growth may be acceptable as far as the stability is concerned, it could influence the particle distribution of the beam.

Consider an isolated difference resonance of the form

$$(2p)\nu_x - (2q)\nu_y = n + \gamma \tag{1}$$

where 2p and 2q are positive integers with 2p+2q > 2,  $n \ge 0$  an integer, and  $|\gamma| \ll 1$ .  $\nu_x$  and  $\nu_y$  are the horizontal and vertical tunes. In the single resonance approximation, the Hamiltonian in terms of the action-angle variables  $(I, \phi)$  can be written as

$$H = \nu_x I_x + \nu_y I_y - \epsilon I_x^p I_y^q \cos(2p\phi_x - 2q\phi_y + n\theta).$$
(2)

Using the canonical transformation

$$S(\phi_x, J_x, \phi_y, J_y) = (\phi_x - \nu_x^0 \theta) J_x + (\phi_y - \nu_y^0 \theta) J_y, \quad (3)$$

where  $\nu_{x,y}^0$  are the tunes of the exact resonance,  $(2p)\nu_x^0 - (2q)\nu_y^0 = n$  and  $\nu_{x,y} = \nu_{x,y}^0 + \gamma_{x,y}$ , we obtain a "time" independent Hamiltonian,

$$K = \gamma_x I_x + \gamma_y I_y - \epsilon I_x^p I_y^q \cos(2p\psi_x - 2q\psi_y), \qquad (4)$$

with  $\psi_{x,y} \equiv \phi_{x,y} - \nu_{x,y}^0 \theta$ . Since the dependence of K on angle variables is only through  $2p\psi_x - 2q\psi_y$ ,  $I_x/(2p) + I_y/(2q)$  is another constant of motion besides K.

The behavior of a beam can be described by the phase space distribution of particles  $f(I_x, \psi_x, I_y, \psi_y, \theta)$ , of which the time evolution is governed by the Liouville equation<sup>3</sup>,

$$\frac{\partial f}{\partial \theta} = \{K, f\} \tag{5}$$

where  $\{ \}$  is the Poisson bracket. For the Hamiltonian (4), this equation becomes

$$Lf = \epsilon \left\{ I_x^p I_y^q \sin(2p\psi_x - 2q\psi_y) (2p\frac{\partial}{\partial I_x} - 2q\frac{\partial}{\partial I_y}) + \cos(2p\psi_x - 2q\psi_y) (pI_x^{p-1}I_y^q\frac{\partial}{\partial \psi_x} + qI_x^p I_y^{q-1}\frac{\partial}{\partial \psi_y}) \right\} f (6)$$

where

$$L = \frac{\partial}{\partial \theta} + \gamma_x \frac{\partial}{\partial \psi_x} + \gamma_y \frac{\partial}{\partial \psi_y} \tag{7}$$

is an integrable operator. Since the Liouville operator  $\mathcal{L} = i\{K, \}$  has only real eigenvalues,<sup>3</sup> the solution of the Liouville equation will not settle into a unique equilibrium state. The final state of the Liouville equation depends on the initial distribution. It is easy to see that the angle independent stationary state of Eq.(6) is  $f = f(I_x/2p + I_y/2q)$  which is an arbitrary function of  $I_x/2p + I_y/2q$ . Since  $I_x/2p + I_y/2q$  is a constant of motion, the mean actions, which correspond to the emittances in two directions, satisfy

$$\langle I_x \rangle / 2p + \langle I_y \rangle / 2q = \text{constant}$$
 (8)

In the following, we present a coupled sextupole resonance: 2p = 1, 2q = 2 and n = 2. The treatments is, however, applicable to any p, q and n values.

# 2 Numerical simulation

To understand the evolution of particle distribution, we have tracked numerically an ensemble of particles in a test lattice with four sextupoles placed symmetrically. Define  $\xi_x \equiv \beta_0^{-\frac{1}{2}}x$ ,  $\xi_y \equiv \beta_0^{-\frac{1}{2}}y$ ,  $\eta_x \equiv \beta_0^{-\frac{1}{2}}dx/d\theta$ , and  $\eta_x \equiv \beta_0^{-\frac{1}{2}}dy/d\theta$ . At each sextupole,  $\xi_{x,y}$  are unchanged but

$$\Delta \eta_{x} = -s\beta_{0}^{\frac{3}{2}}(\xi_{x}^{2} - \xi_{y}^{2})$$
  
$$\Delta \eta_{y} = 2s\beta_{0}^{\frac{3}{2}}\xi_{x}\xi_{y}$$
(9)

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Figure 1: The evolution of the emittances from the numerical tracking of 1000 particles, (a) and (b), and from the equations of the moments, (c) and (d). The initial state is a Gaussian distribution with  $\sigma_x = \sigma_y = 0.5 \times 10^{-3} mm$ , and  $s_0 = 0.05m^{-2}$ ,  $\beta_0 = 100m$ . In each curve the upper branch is  $\langle I_y \rangle / \sigma_y$  and the lower one  $\langle I_x \rangle / \sigma_x$ . (a) is on the resonance with  $\nu_x = 1.65$  and  $\nu_y = 1.825$ . (b) is far away from the resonance with  $\nu_x = 1.70$  and  $\nu_y = 1.65$ . (c) and (d) have the same conditions as (a), but (c) is calculated from the map (20) and (d) is calculated from the modified version of the map (21) in which Eq.(24) instead of Eq.(13) is used.

where  $s = s_0$  at  $\theta = m\pi$  and  $s = -s_0$  at  $\theta = (m + 1/2)\pi$ for  $m \ge 0$ . Between sextupoles, it is a linear rotation

$$\begin{bmatrix} c_{x,y} & s_{x,y} \\ -s_{x,y} & c_{x,y} \end{bmatrix} \cdot \begin{bmatrix} \xi_{x,y} \\ \eta_{x,y} \end{bmatrix} \longrightarrow \begin{bmatrix} \xi_{x,y} \\ \eta_{x,y} \end{bmatrix}$$
(10)

where  $c_{x,y} = \cos(2\pi\nu_{x,y}/4)$  and  $s_{x,y} = \sin(2\pi\nu_{x,y}/4)$ . The Hamiltonian of this system can be written as

$$H = \frac{1}{2}\nu_x(\xi_x^2 + \eta_x^2) + \frac{1}{2}\nu_y(\xi_y^2 + \eta_y^2) + \frac{1}{3}s_0\beta_0^{\frac{3}{2}}b(\theta)(\xi_x^3 - 3\xi_x\xi_y^2)$$
(11)

where  $b(\theta) = \delta(\theta) - \delta(\theta - \frac{\pi}{2}) + \delta(\theta - \pi) - \delta(\theta - \frac{3\pi}{2})$ . In the single resonance approximation, this Hamiltonian can be easily reduced to the Hamiltonian (2) with  $2I_{x,y} = \xi_{x,y}^2 + \eta_{x,y}^2$  and 2p = 1, 2q = 2, n = 2. The initial particle distribution of the beam is assumed to be Gaussian

$$f(\xi_x, \eta_x, \xi_y, \eta_y, 0) \sim \exp(-\frac{\xi_x^2 + \eta_x^2}{2\sigma_x} - \frac{\xi_y^2 + \eta_y^2}{2\sigma_y}).$$
(12)

When the operating point is very close to the resonance  $(\gamma_{x,y} \ll 1)$ , it has been found out that the distribution function quickly settles down to a final state. Except for the small fluctuation, the mean actions (emittances) in the final state achieve the stationary values. The curve (a) in Fig.1 is an example of "on-the-resonance" case, i.e.,  $\gamma_{x,y} =$ 



Figure 2: Relative fluctuation of  $I_{x,y}$  of curve (a) in Fig.1.  $D_{11} = (\langle I_x I_y \rangle - \langle I_x \rangle \langle I_y \rangle) / \langle I_x \rangle \langle I_y \rangle, D_{02} = (\langle I_x^2 \rangle - 2\langle I_x \rangle^2) / \langle I_x \rangle^2$ , and  $D_{20} = (\langle I_y^2 \rangle - 2\langle I_y \rangle^2) / \langle I_y \rangle^2$ .

0. To examine the final distribution, we computed the deviation of the second order moments of the actions from the relation

$$\langle \Delta I_{\alpha} \Delta I_{\beta} \rangle = \langle I_{\alpha} I_{\beta} \rangle - \langle I_{\alpha} \rangle \langle I_{\beta} \rangle = \delta_{\alpha\beta} \langle I_{\alpha} \rangle \langle I_{\beta} \rangle \qquad (13)$$

of the Gaussian distribution where  $\delta_{\alpha\beta}$  is the Kronecker  $\delta$ -symbol. It is shown in Fig.2 that this deviation is very small except in the transient period. Thus the final state could be treated as a stationary Gaussian distribution as long as the high order fluctuation can be neglected. When the operating point is far away from the resonance ( $\gamma_{x,y} \gg 1$ ), the motion of two directions is decoupled so that the particle distribution remains unchanged as shown by the curve (b) in Fig.1.

#### **3** Equations of the moments

Using equations of the moments, we can find the emittances approximately, but because of the sinusoidal dependence of the angle variables, it is impossible to obtain the equations of the moments directly from Eq.(6). To avoid this difficulty, we define

$$E_{ij} \equiv \int I_x^i I_y^j f dI_x dI_y \quad . \tag{14}$$

The (i, j) order moment is then

$$\langle I_x^i I_y^j \rangle = \int E_{ij} d\psi_x d\psi_y \quad . \tag{15}$$

Multiplying Eq.(6) by  $I_x^i I_y^j$  and integrating it over  $I_x$  and  $I_y$ , we obtain a system of infinite numbers of equations to be satisfied by  $E_{ij}$ . Generally, the equation for  $E_{ij}$  involves higher order terms  $E_{i+\frac{1}{2}j}$  and  $E_{i-\frac{1}{2}j+1}$ . The first three equations, which are relevant to the evolution of  $\langle I_x \rangle$ , are

$$LE_{10} = \epsilon \left\{ \left[ 2\sin(\Delta\psi) + \cos(\Delta\psi) \frac{\partial}{\partial\psi_y} \right] E_{\frac{3}{2}0} \right\}$$

$$+\frac{1}{2}\left[-3sin(\Delta\psi) + cos(\Delta\psi)\frac{\partial}{\partial\psi_x}\right]E_{\frac{1}{2}1}\right\}$$
(16)  
$$E_{1}=\int\left[2sin(\Delta\psi) + cos(\Delta\psi)\frac{\partial}{\partial\psi_x}\right]E_{\frac{1}{2}1}$$

$$LE_{\frac{3}{2}0} = \epsilon \left\{ \left[ 2sin(\Delta\psi) + cos(\Delta\psi) \frac{\partial}{\partial\psi_y} \right] E_{20} + \frac{1}{2} \left[ -4sin(\Delta\psi) + cos(\Delta\psi) \frac{\partial}{\partial\psi_x} \right] E_{11} \right\}$$
(17)

$$LE_{\frac{1}{2}1} = \epsilon \left\{ \left[ 4sin(\Delta\psi) + cos(\Delta\psi)\frac{\partial}{\partial\psi_y} \right] E_{11} + \frac{1}{2} \left[ -2sin(\Delta\psi) + cos(\Delta\psi)\frac{\partial}{\partial\psi_x} \right] E_{02} \right\}$$
(18)

where  $\Delta \psi = \psi_x - 2\psi_y$ . To solve these equations, one must truncate this chain of equations at a certain order. For a small beam size ( $\sigma_{x,y}$  small), the higher order terms of  $E_{ij}$ are much smaller than the lower order one, and the truncation is justified. The numerical simulation has shown that, for an initial Gaussian distribution, the final state is approximately Gaussian also. As a consequence, Eq.(13) can be used to truncate the chain. It is still not easy, however, to solve the set of nonlinear partial differential equations (16)-(18). One further simplification can be accomplished by finding the return map for the moments by integrating Eqs.(16)-(18) over one turn. To order  $\epsilon$ , we use the unperturbed values of  $E_{ij}$  in the right-hand sides of Eqs.(17) and (18), i.e.,  $\partial E_{i,j}/\partial \psi_{x,y} = 0$  for i+j=2. Then Eqs.(17) and (18) can be easily solved. Substituting the solutions of Eqs.(17) and (18) into Eq.(16) we obtain the change in  $\langle I_x \rangle$ , to order  $\epsilon^2$ ,

$$-\epsilon^2 (4\langle I_x I_y \rangle - \langle I_y^2 \rangle) \frac{1 - \cos(2\pi (2\gamma_y - \gamma_x))}{2(2\gamma_y - \gamma_x)^2} .$$
(19)

Combining Eqs.(8), (13) and (19), we find the return map for the emittances, to order  $\epsilon^2$ ,

$$x_{n+1} = x_n - \epsilon^2 y_n (2x_n - y_n) \frac{1 - \cos(2\pi(2\gamma_y - \gamma_x))}{(2\gamma_y - \gamma_x)^2}$$
$$y_{n+1} = y_n + 2\epsilon^2 y_n (2x_n - y_n) \frac{1 - \cos(2\pi(2\gamma_y - \gamma_x))}{(2\gamma_y - \gamma_x)^2}$$
(20)

where  $x_n = \langle I_x \rangle |_{\theta=2\pi n}$  and  $y_n = \langle I_y \rangle |_{\theta=2\pi n}$ . For a given initial Gaussian distribution, the evolution of the emittances can be calculated from this map approximately. The fixed point which corresponds to the stationary state is

$$2\langle I_x \rangle - \langle I_y \rangle = 0 \quad . \tag{21}$$

If  $\langle I_{x,y} \rangle = \sigma_{x,y}$  initially, the stationary state is found from Eqs.(8) and (21) as

$$\langle I_x \rangle = \frac{1}{4} (2\sigma_x + \sigma_y) ,$$
  
$$\langle I_y \rangle = \frac{1}{2} (2\sigma_x + \sigma_y) . \qquad (22)$$

Near the resonance, i.e.  $|2\gamma_y - \gamma_x| << 1$ , this stationary state is locally stable. It implies that for an initial Gaussian distribution with  $\langle I_{x,y} \rangle |_{t=0}$  not too far away from the stationary values, the emittances in the final state will achieve this stationary value. The curve (c) in Fig.1 is the evolution of  $\langle I_{x,y} \rangle$  calculated from the map (20) of  $2\gamma_y - \gamma_x = 0$ . Outside the transient period, the result is in a good agreement with the numerical simulation, curve (a). From Fig.2 it can be seen that, in the transient period, the particle distribution deviates substantially from Gaussian showing that the approximation used to obtain the map (20) is invalid. The small discrepancy between the stationary state of the map (20) and the final state of the tracking is a reflection of a small deviation of the final distribution from Gaussian. Fig.2 shows that, in the final state,

$$\langle I_y^2 \rangle - 2 \langle I_y \rangle^2 \simeq 0.2 \langle I_y \rangle^2$$
 (23)

for this special case. Using Eq.(23) instead of Eq.(13), we find the stationary state to be

$$2\langle I_x \rangle - 1.1 \langle I_y \rangle = 0. \tag{24}$$

The curve (d) in Fig.1 is calculated from this modified map. It has a better agreement with the tracking result.

Far away from the resonance, i.e.  $|2\gamma_y - \gamma_x| \gg 1$ , the map (20) is reduced to a linear map:  $x_n = x_{n-1}$  and  $y_n = y_{n-1}$ . As shown in the tracking (curve (b) in Fig.1), the motions in two directions are completely decoupled and the particle distributions in two directions remain unchanged.

In the above calculation, the approximations we have adopted are equivalent to neglecting high order fluctuations. It is not easy to evaluate these fluctuations although it is possible in principle. An alternative way is to expand the distribution function. We rewrite the distribution function as

$$f(I_x, \psi_x, I_y, \psi_y, \theta) = e^{-g(I_x, \psi_x, I_y, \psi_y, \theta)} .$$
<sup>(25)</sup>

For the Gaussian distribution,  $g = c + I_x/\sigma_x + I_y/\sigma_y$ . It is expected that f is not too far away from a Gaussian distribution provided that the coupling constant  $\epsilon$  and the beam size are sufficiently small. If this is true, g may be expanded in the form

$$g(I_x, \psi_x, I_y, \psi_y, \theta) = \sum_{i,j=0}^{\infty} A_{ij} I_x^{\frac{1}{2}} I_y^j$$
(26)

where  $A_{ij} = A_{ij}(\psi_x, \psi_y, \theta)$ , and

$$E_{\frac{1}{2}j} = -\frac{\partial}{\partial A_{ij}} \int e^{-g} dI_x dI_y \quad . \tag{27}$$

Eq.(6) could then be solved approximately by truncating the series for g.

## 4 References

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