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POLE FACE SHAPE DESIGN IN HIGH-ENERGY ACCELERATORS

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Abstract

An analytic method for designing pole face shape is presented, which gets the desired value of the field index in a given region, withaprescribed error. The method has three stages, corresponding to the successive computation of :

- the ideal pole face shape and ideal equipotential set (previously developed by the author);
- the equipotential set, taking into account fringing field effects, by means of conformal mapping ;
- the necessary corrections at the edges of the ideal pole face by means of conformal mapping, for obtaining the desired field distribution.

As an example, the pole face shape for a 300-GeV synchrotron with n=5040 is computed.

The method applies to every magnetic device having a radially constant field index.

Introduction

In a previous work, the author developed a method for designing the pole face shape for high-energy particle accelerators. I This method is based on the concept of an ideal pole face, which has an infinite radial extension, is made out of a magne-tic material of infinite permeability and which lacks remanence and saturation. The ideal pole face generates a magnetic field distribution in the median plane given by

$$B_{z}(r,\theta,\theta) = B_{0}\left(\frac{r}{r_{0}}\right)^{-n}$$
(1)

where (r, θ, z) are the cylindrical coordinates, $B_z(r, \theta, 0)$ - the magnetic induction in the median plane, r - the radius of the central orbit, B^0 - the magnetic induction at r_0 , n^0 - the field index.

This expression determines unequivocally the magnetic field distribution in the whole volume of the air gap, particularly the main parameters of this distribu-tion : the magnetic scalar potential, the magnetic induction, the equipotential set, and the potential network.^{2,2}

According to the previous method, the correction of the ideal pole face at the edges, in order to obtain the genuine pole face, is made by a step-by-step procedure, computing in every case the potential network and trying to making it coincide with the ideal one.

According to the method presented here, the desired field index is computed by means of an equipotential line.⁴ First, two ideal equipotential lines are compuby means of an equipotential line.⁴ First, two ideal equipotential lines are compu-ted : the lo% equipotential - used as a reference for determining the field index -and the loo% - the ideal pole face. Second, limits are set at the radial extension of the ideal pole face, and the new reference equipotential, taking into account fringing field effects, is computed by means of conformal mapping. Here, an idea proposed by Rogowski is followed, which consists in using an equipotential line in the field of a simple boundary shape to represent an actual boundary of a complica-ted shape.⁹ In this way, the limited ideal pole face is represented, in a good ap -proximation, by the 80% equipotential line of another equipotential set, the loo% line of which is composed of straight segments. Third, this loo% equipotential is corrected for edge effects, and the resulting 80% equipotential line represents the genuine corrected pole face. genuine corrected pole face.

The new method is applied to an actual case, being used for the computation of a pole face shape, giving the desired field index with a relative error less than 5.10⁻⁴.

Theoretical considerations

Ideal equipotential set

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Starting from eq.(1), the ideal equipotential set equations were derived 3 , where n is a constant, taking into account the cylindrical symmetry :

$$= Z_{o} \sum_{v=0}^{\infty} A_{2v+1} b^{2v+1} \left(\frac{Z_{0}}{r_{0}}\right)^{2v} \xi_{o}^{2v+1} \left(\frac{r}{r_{0}}\right)^{2v (n-1) + n}$$
(2)

where $2z_0$ is the total height of the gap at radius r_0 ,

$$\xi_{0} = \sum_{\nu=0}^{\infty} \frac{(-1)^{\nu}}{(2\nu+1)!} \prod_{\ell=0}^{\nu-1} (\pi+2\ell)^{2} \left(\frac{Z_{0}}{T_{0}}\right)^{2\nu}$$
(3)

and the coefficients A_{2V+1} are given by

$$A_{1} = 1 ,$$

$$A_{3} = \frac{n^{2}}{3!} ,$$

$$A_{5} = 3 \left(\frac{n^{2}}{3!}\right)^{2} - \frac{n^{2}}{5!} (n+2)^{2} ,$$
(4)

By definition, the ideal pole face is the equipotential of the order loo%(b=1). Inserting this condition into eq.(2), we obtain :

$$z = z_{0} \sum_{v=0}^{\infty} A_{2v+1} b^{2v+1} \left(\frac{z_{0}}{r_{0}}\right)^{2v} \xi^{2v+1} \left(\frac{r}{r_{0}}\right)^{2v (n-1)+n}$$
(5)

Field index computation by means of an equipotential line

Starting from eq.(1), one obtains

$$n = -\left[r/B_{z}\left(r,\theta,0\right)\right]\left[\partial B_{z}\left(r,\theta,0\right)/\partial r\right]$$
⁽⁶⁾

The field index may be computed by means of an equipotential line, with the formula $T_{i} = \frac{r_{o}}{r_{o}} \frac{Z_{2} - Z_{1}}{Z_{i} - Z_{i}}$

$$= \frac{1}{h} \frac{1}{Z_2 + Z_1}$$
(7)
a are the ordinates of two points on a reference equipotential line.

where z₁ and z₂ are the ordinates of two points on a reference equipotential line, and 2h is the difference between their abscissae. This method for computing the field index introduces two errors : an error of method and one of determination. The error of method comes from the use of the approximate eq.(7) instead of the exact one (6). It has the form :

$$\left(\frac{\Delta n}{n}\right)_{m} = 2 \frac{\sum_{u=0}^{\infty} \sum_{v=0}^{\infty} \frac{n(v-u)-(v+u)}{(2u+1)!} A_{2v+1} b^{2v+1} \xi_{0}^{2v+1} \left(\frac{z_{0}}{r_{0}}\right)^{2v} \prod_{j=0}^{2u-1} \left[2v(n-1)+n-j\right] \left(\frac{h}{r_{0}}\right)^{2u}}{\sum_{u=0}^{\infty} \sum_{v=0}^{\infty} \frac{1}{(2u)!} A_{2v+1} b^{2v+1} \xi_{0}^{2v+1} \left(\frac{z_{0}}{r_{0}}\right)^{2v} \prod_{j=0}^{2u-1} \left[2v(n-1)+n-j\right] \left(\frac{h}{r_{0}}\right)^{2u}}$$
error of determination is:
$$\left(\frac{\Delta n}{n}\right)_{d} = \frac{\Delta r_{0}}{r_{0}} + \frac{\Delta h}{h} + \left(\frac{r_{0}}{nh} - \frac{nh}{r_{0}}\right) \frac{\Delta z}{z}$$
(9)

The eq.(8) may be used for correcting the computed field index values. From eqs.(7) and (8) we obtain the correct field index value $2^{\mu-1}$

$$\Pi = \frac{r_{0}}{h} \frac{Z_{2} - Z_{1}}{Z_{2} + Z_{1}} - 2 \frac{\sum_{u=0}^{\infty} \sum_{v=0}^{\infty} \frac{\pi (v - u) - (v + u)}{(2u + 1)!} A_{2v+1} b^{2v+1} \xi_{0}^{2v+1} (\frac{Z_{0}}{r_{0}})^{2v} \prod_{j=0}^{2u} \left[zv(n-1) + n - j \right] (\frac{h}{r_{0}})^{2u}}{\sum_{u=0}^{\infty} \sum_{v=0}^{\infty} \frac{1}{(2u)!} A_{2v+1} b^{2v+1} \xi_{0}^{2v+1} (\frac{Z_{0}}{r_{0}})^{2v} \prod_{j=0}^{2u-1} \left[zv(n-1) + n - j \right] (\frac{h}{r_{0}})^{2u}} (10)$$

Edge effect determination and correction

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The determination and correction for fringing field effects at the two edges of a pole piece, will be treated sepparately for each edge. After that, the two corrected pole piece edges are joined in the central region by the ideal pole face. We consider an edge of an air gap, between two pole pieces, each of them bounded by two semi-infinite planes, the inner planes - pole faces - having an angle 2 c between them, and the outer ones being vertical.

Following the idea of Rogowski, these pole pieces will be used as a simple boundary to generate a field distribution fairly identical with the ideal one. The equipotential line of the vth order, obtained by means of the Schwarz - Christoffel differential equation, is given by :

$$\chi = -\cot g \, \alpha + \frac{g}{\sin \alpha} = \frac{\int_{l=0}^{\infty} \frac{\int_{l=0}^{\infty} (\frac{3}{2} - \frac{\alpha}{\pi} - i)}{l! (l+\alpha)} e^{\mu \left(l + \frac{\alpha}{\pi}\right)} \cos v \left(l + \frac{\alpha}{\pi}\right)}{\int_{l=0}^{\infty} (-1)^{l} \frac{l^{2}}{l^{2} (\frac{3}{2} - \frac{\alpha}{\pi} - i)}}, \quad (11)$$

$$Z = \frac{g}{\sin \alpha} \frac{\sum_{l=0}^{i=\ell} \left(\frac{3}{2} - \frac{\alpha}{\pi} - i\right)}{\sum_{l=0}^{\ell} \left(\frac{1}{2} - \frac{\alpha}{\pi} - i\right)} u \left(l + \frac{\alpha}{\pi}\right)}{\sum_{l=0}^{\infty} \left(-1\right)^{\ell} \frac{\prod_{l=0}^{i=\ell} \left(\frac{3}{2} - \frac{\alpha}{\pi} - i\right)}{\ell! \left(l + \alpha\right)}}, \quad (12)$$

where x is the abscissa counted from the outer vertical surface of the pole piece and g is the vertical distance between the vertex and the median plane. Eqs. (11) and

and g is the vertical distance between the vertex and the median plane. Eqs.(11) at (12) are written for the edge with greater aperture. In order to correct for the edge effect, we consider an infinite thin exten-sion of the outer vertical surface of the pole pieces, protruding to the median plane. In this case, using again the Schwarz - Christoffel differential equation, we obtain the equation of the same equipotential line : $\frac{\int_{-\infty}^{-\infty} d_{-1}}{\int_{-\infty}^{\infty} \mu(t+\frac{\omega}{2})} = t \leq 0$

$$\begin{aligned} \chi &= -\cot g \, \alpha + \frac{g}{\sin \alpha} \, \frac{\sum\limits_{\ell=0}^{\infty} \frac{\prod\left(\frac{3}{2} - \frac{\pi}{\pi} - i\right)}{\ell!\left(\ell + \frac{\alpha}{\pi}\right)} \, \ell}{\sum\limits_{\ell=0}^{\ell=\ell} \left(-1\right)^{\ell} \frac{\prod\left(\frac{3}{2} - \frac{\alpha}{\pi} - i\right)}{\ell!\left(\ell + \frac{\alpha}{\pi}\right)} \left[1 + \left(a - 1\right) \frac{\frac{1}{2} - \frac{\alpha}{\pi} - \ell}{\frac{1}{2} - \frac{\alpha}{\pi}}\right] \cos v \left(\ell + \frac{\alpha}{\pi}\right)}{\sum\limits_{\ell=0}^{\ell=\ell} \left(-1\right)^{\ell} \frac{\prod\left(\frac{3}{2} - \frac{\alpha}{\pi} - i\right)}{\ell!\left(\ell + \frac{\alpha}{\pi}\right)} \left[1 + \left(a - 1\right) \frac{\frac{1}{2} - \frac{\alpha}{\pi} - \ell}{\frac{1}{2} - \frac{\alpha}{\pi}}\right]}{\sum\limits_{\ell=0}^{\ell=\ell} \frac{\prod\left(\frac{3}{2} - \frac{\alpha}{\pi} - i\right)}{\ell!\left(\ell + \frac{\alpha}{\pi}\right)} e^{u \left(\ell + \frac{\alpha}{\pi}\right)} \left[1 + \left(a - 1\right) \frac{\frac{1}{2} - \frac{\alpha}{\pi} - \ell}{\frac{1}{2} - \frac{\alpha}{\pi}}\right] \sin v \left(\ell + \frac{\alpha}{\pi}\right)}{\sum\limits_{\ell=0}^{\ell=\ell} \left(-1\right) \frac{\prod\limits_{\ell=0}^{\ell=\ell} \left(\frac{3}{2} - \frac{\alpha}{\pi} - i\right)}{\ell!\left(\ell + \frac{\alpha}{\pi}\right)} \left[1 + \left(a - 1\right) \frac{\frac{1}{2} - \frac{\alpha}{\pi} - \ell}{\frac{1}{2} - \frac{\alpha}{\pi}}\right]}{\left(\frac{1}{2} - \frac{\alpha}{\pi}\right)} \right] \tag{14}$$

where the coefficient a is choosen according to the length of the vertical extension. Practical application

Let us consider, as a example, a strong focusing 300-GeV synchrotron with the following basic parameters : $\frac{n}{-6}$ m⁻¹

$$\begin{array}{c} \rho = 840 \text{ m} \\ \rho = 840 \text{ m} \\ 2z_{o} = 70 \text{ mm} \\ 12z_{o} = 70 \text{ mm} \\ 1deal equipotential lines \\ \hline Starting from eq.(5) \text{ the ideal pole face equation is, within an error} \\ \Delta z < 5.10^{-6} \text{ mm in the region 839,900} < r < 840,100 \text{ mm} \\ z = 34.74331700 \left(\frac{r}{840000}\right)^{5040} + 2.51631542 \cdot 10^{-1} \left(\frac{r}{840000}\right)^{15118} + \\ + 4.92021786 \cdot 10^{-3} \left(\frac{r}{840000}\right)^{25196} + 1.27254936.10^{-4} \left(\frac{r}{840000}\right)^{35274} + 3.76306312 \cdot 10^{-6} \left(\frac{r}{840000}\right)^{45352} \\ + 3.76306312 \cdot 10^{-6} \left(\frac{r}{840000}\right)^{15} \end{array}$$

The reference ideal equipotential line, obtained for b=0.1 from eq.(2) is, within an error $\Delta_Z < 5.10^{-7}$ mm and in the same region, 25/9/

-8 (7 25196 (840000) mm(16) $Z = 3.47433170 \left(\frac{r}{840000}\right)^{5040} + 2.51531542 \cdot 10^{-4} \left(\frac{r}{840000}\right)^{15118} + 4.92021786 \cdot 10^{-4}$

The field index distribution, given in table 1 is obtained by means of eq.(lo), where the values for z_1 and z_2 are computed from eq.(l6) and h = 5 mm. In order to obtain a relative error $(\Delta n)_1 \leq 5 \cdot 10^{-4}$, we must consider $\Delta r \leq 5 \cdot 10^{-5}$ mm, as shown by eq.(9).

eq.(9). The values listed in table 1 show that the ideal pole face and equipotential lines satisfy the condition for an accurate field index distribution.

Table 1

x	п	$\frac{\Delta n}{n}.10^4$	x	л	$\frac{\Delta n}{n}.10^4$	x	п	$\frac{\Delta n}{n} \cdot 10^4$
-70 -65 -50 -55 -50 -45 -40 -35 -30 -25	5039.50 5040.42 5040.40 5039.35 5040.50 5037.25 5038.86 5042.04 5040.53 5037.60	$\begin{array}{r} -1 \\ + 0.8 \\ + 0.8 \\ - 1.3 \\ + 1 \\ - 5.5 \\ - 2.3 \\ - 4 \\ + 1 \\ - 4.8 \end{array}$	-20 -15 -10 -5 0 +5 +10 +15 +20 +25	5038.55 5040.44 5040.25 5040.70 5039.10 5040.22 5041.44 5040.37 5039.26 5040	$\begin{array}{r} -2.9 \\ + 0.9 \\ + 0.5 \\ + 1.4 \\ - 1.4 \\ + 0.4 \\ + 2.9 \\ + 1.3 \\ - 1.5 \\ 0 \end{array}$	+ 30 + 35 + 40 + 45 + 50 + 55 + 60 + 65 + 70	5040.32 5038.27 5039.52 5040.04 5039.52 5040 5040.90 5040.90 5039.65	+ 0.6 - 3.4 - 1 - 0.1 - 1 0 + 1.8 + 1.8 - 0.7

Edge effect determination and correction

Choosing a value for $\alpha = 0.27577861$ rad, we obtain from eqs.(11) and (12),

$$x = -3.53370114 \ g + 0.23851107g \sum_{\ell=0}^{\infty} \frac{\prod_{i=0}^{\ell} \left(\frac{3}{2} - \frac{\alpha}{\pi} - i\right) u \left(\ell + \frac{\alpha}{\pi}\right)}{\ell! \left(\ell + \frac{\alpha}{\pi}\right)} e^{\cos v \left(\ell + \frac{\alpha}{\pi}\right)} ,$$
 (17)

$$z = 0.23851107 g \sum_{\ell=0}^{\infty} \frac{\int_{i=0}^{10} \left(\frac{3}{2} - \frac{\alpha}{\pi} - i\right)}{\ell! \left(\ell + \frac{\alpha}{\pi}\right)} e^{-\frac{\alpha}{2} \left(\ell + \frac{\alpha}{\pi}\right)} e^{-\frac{\alpha}{2} \left(\ell + \frac{\alpha}{\pi}\right)}, \quad (18)$$

representing the equipotential lines modified by the edge effect. We need a value for g so as the corresponding 80% equipotential line, computed with eqs.(17) and (18), be coincident in the largest possible region with the ideal pole face. For g = 61.831837 mm, we find that the two curves are fairly coincident in the region 840 cost of 840 cost mm

in the region 840,000 < r < 840,055 mm. The reference equipotential line, computed from eqs.(17) and (18), - in this case for 8% -, is shifted with respect to the reference ideal equipotential of 10%, computed from eq.(16). In order to make them coincide in the largest possible region, a coefficient a=1.4 is choosen. The corrected equipotential set is obtained from eqs.(13) and (14) $\frac{1-\ell}{2}$

The corrected reference 8% equipotential obtained from eqs.(19) and (20) coincide with the reference ideal 10% equipotential in the region

840,000 < r < 840,050, the differences being smaller than 10^{-3} mm. With the same eqs. (19) and (20), the 80% equipotential line is computed; it represents the corrected shape of the pole face.

The same method works also for the smaller aperture edge. Joining the results, we obtain the coordinates of the corrected pole face, as listed in table 2.

We note that in the region 839,970 < r < 840,020, the corrected pole face coincides with the ideal pole face.

The above computations were checked by means of an electrolytic tank. Within the errors of the experimental set-up, which were of + 0.1 ... 0.2 mm, a good agre-ement was found between the experimental equipotential lines, including the edge effect, and the ideal and corrected equipotential lines.

Table 2

r-r _o	Z	r-ro	Z	r-ro	Z
-70 -66.4842 -63.5528 -60.1041 -56.1888 -51.8901	2 6 24.9427 23.9309 23.7916 24.1424 24.7895	-42.3492 - 37.1588 -31.7018 -20 -10 0	26.6134 27.7015 28.8776 30.9929 32.9340 35	+ 21.42 77 + 21.2901 + 37.44 13 + 45.8451 + 54.3985 + 62.5121	39.8597 41.6846 43.6108 45.6399 47.7602 4 9 .7861
-47.2656	25. 63 20	+ 10 + 20	37.1998 39.5428	+ 75	58

A final check, of the high accuracy required, may be done only by computing the field index by means of the potential network.

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