# Application of Differential Evolution Algorithm in Future Circular Colliders

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# Outline

- Introduction
- Differential Evolution Algorithm
- Application in CEPC & SuperKEKB
- Summary

# Multi-objective genetic algorithm (MOGA)

- Application in storage ring based light source is very popular and successful
  - APS/DLS, ELEGANT, M. Borland, in 48<sup>th</sup> ICFA Beam Dynamics Workshop on Future Light Sources
  - NSLSII, L. Yang, Y. Li, W. Guo and S. Krinsky, PRST-AB, 14, 054001 (2011)
  - SLS, BMAD, M. Ehrlichman , arXiv: 1603.02459
  - HEPS, Accelerator Toolbox, Y. Jiao and G. Xu, in this proceeding

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# Different Algorithm

- Particle Swarm, SPEAR3, X. Huang, J. Safranek, Nucl. Instr. Meth. In Phys. Research A. 757, 48, 2014
- Differential Evolution, J. Qiang et al., IPAC'13
- Downhill Simplex, SuperKEKB, FCC, K. Oide et al.
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#### Excitation

• K. Oide, "A design of beam optics for FCC-ee", Sep. 2015 @IHEP





\* The dynamic aperture was optimized with element-by-element radiation damping, automatic tapering, and crab waist.

## Why we did the job?

- We need to optimize the DA of CEPC
- We want to try the direct DA optimization in collider, just as the community has done in light source
- Different optimization algorithm is worth to be used
- SAD(http://acc-physics.kek.jp/sad/) is used for the DA determination. It is a parallel code, but the scalability is not very good. A MPI-based parallel code to call SAD will be much more efficient.

# Differential Evolution Algorithm (single objective)

- The "DE community" has been growing since the early DE years of 1994 1996
- DE is a very simple population based, stochastic function minimizer which is very powerful at the same time.
- There are a few strategies, we choose 'rand-to-best'. Attempts a balance between robustness and fast convergence.

 $v(i,j) = \begin{cases} x(i,j) + F \times [x(b,j) - x(i,j)] + F \times [x(r1,j) - x(r2,j)], & If rand(j) < CR \\ x(i,j), & Otherwise \end{cases}$ 

 Different problems often require different settings for NP, F and CR





#### Parallel Computation



# CEPC (PreCDR)

- Beam energy: 120GeV
- Circumference: 54 km
- SR power: 51.7 MW/beam
- 8\*arcs, 2\*lps
- Luminosity: 2e34/IP
- Emittance X/Y: 6.12/0.018 nmrad
- $\beta_x^* / \beta_y^* = 0.8 \text{m} / 1.2 \text{mm}$
- FODO cell: 47.2m, 60/60 degrees
- Damping time: 78/78/39 turns
- Dynamic Aperture:  $20\sigma_x \times 40\sigma_y \times 0.02$



# Case of CEPC

- Before optimization:
  One SF/SD family in arc
- Initial IR optimization (by Y. Wang, Mar 2015)
- $\beta_x^* / \beta_y^* = 0.8 \text{m}/3 \text{mm}$
- Without pretzel scheme
- No solenoid and compensation



# CEPC: Dynamic Aperture Optimization

- DA Objective:  $\frac{x^2}{20^2} + \frac{z^2}{16^2} = 1$ 
  - z for energy deviation in unit of  $\sigma_p$
  - x for transverse amplitude in unit of  $\sigma$
- Variables: 240 sextupole familiy in arc
  - Sextupoles interleaved with -/ map is one pair
- Options:
  - DAPWIDTH=15
  - Turns = 100
  - Synchrotron oscillation on



#### CEPC: Dynamic Aperture Optimization (2)



СΓ

#### Multi-objective Optimization

- Most problems in nature have several (possibly conflicting) objectives to be satisfied.
- Many of these problems are frequently treated as single-objective optimization problems by transforming all but one objective into constraints.
- The term *optimize* means finding such a solution which would give the values of all the objective functions acceptable to the decision maker.



Giuseppe Narzisi, "Multi-Objective Optimization", 2008

#### MODE: Multi-Objective optimization by Differential Evolution

The parallel algorithm is referencing to J. Qiang(IPAC'13)

- 1. Initialize the population of parameter vectors
- 2. Generate the offspring population using the above differential evolution algorithm
- 3. Find the non-dominated population, which are treated as the best solutions in DE to generate offspring
- 4. Sorting all the population, select the best NP solution as the parents
- 5. Return to step 2, if stopping condition not met

# Multi-Objective Optimization of CEPC

- Objectives:
  - $\nu_x \in (0.05, 0.31), \nu_y \in (0.10, 0.31),$  for  $\delta_p \in (-0.02, 0.02),$  with  $\nu_{x0} = 0.08, \nu_{y0} = 0.12$
  - $\frac{x^2}{20^2} + \frac{z^2}{16^2} = 1$ , for z=Range[-15,15,1]
  - Options: DAPWIDTH=30, turns=200





#### Multi-Objective Optimization of CEPC

The dynamic aperture required in X-Y space not satisfying



x [σ<sub>x</sub>]

# Dynamic Aperture with Damping

Synchrotron oscillation

Synchrotron oscillation Radiation damping



### Sawtooth effect without FFS





#### Orbit sawtooth amplitude 0.6mm



Courtesy of Huiping Geng@IHEP

# Dynamic Aperture with Damping & Fluctuation

![](_page_18_Figure_1.jpeg)

#### Y. Ohnishi, "Optics Issues", 18<sup>th</sup> KEKB Review, March 3-5, 2014 dynamic aperture is a serious issue

![](_page_19_Figure_1.jpeg)

Transverse aperture is reduced significantly.

![](_page_19_Figure_3.jpeg)

# DA Optimization of LER

- Objectives:
  - $v_x \in (0.53, 0.66), v_y \in (0.55, 0.66),$ for  $\delta_p \in (-0.019, 0.019)$ •  $\frac{x^2}{50^2} + \frac{z^2}{26^2} = 1$ , for z=Range[-24, 24, 3],  $\epsilon_{x,0} = 1.89$  nmrad,  $\delta_{p,0} = 7.7e-4$
- Variables: 68
  - 2 Octupoles
  - 54 sextupole pairs
  - 12 skew sextupole pairs

Momentum aperture is increased.

![](_page_20_Figure_8.jpeg)

#### LER: beam-beam and lattice nonlinearity

![](_page_21_Figure_1.jpeg)

• Skew-sext resonance reduce the beam-beam performance

D. Zhou, "Beam Dynamics Issuses in SuperKEKB", The 20<sup>th</sup> KEKB Accelerator Review Committee, Feb, 2015.

D. Zhou and et al, "Interplay of Beam-Beam Lattice Nonlinearity and Space Charge Effects in the SuperKEKB Collider", IPAC'15

#### LER: beam-beam and lattice nonlinearity

![](_page_22_Figure_1.jpeg)

- Skew-sext resonance reduce the beam-beam performance

D. Zhou, "Beam Dynamics Issuses in SuperKEKB", The 20<sup>th</sup> KEKB Accelerator Review Committee, Feb, 2015.

D. Zhou and et al, "Interplay of Beam-Beam Lattice Nonlinearity and Space Charge Effects in the SuperKEKB Collider", IPAC'15

#### LER: beam-beam and lattice nonlinearity

![](_page_23_Figure_1.jpeg)

- Skew-sext resonance reduce the beam-beam performance
- Skew-sext map cause loss in DA and lifetime

D. Zhou, "Beam Dynamics Issuses in SuperKEKB", The 20<sup>th</sup> KEKB Accelerator Review Committee, Feb, 2015.

D. Zhou and et al, "Interplay of Beam-Beam Lattice Nonlinearity and Space Charge Effects in the SuperKEKB Collider", IPAC'15

# Optimization of LER

- Objectives:
  - $v_x \in (0.53, 0.66), v_y \in (0.55, 0.66),$
  - $\frac{x^2}{50^2} + \frac{z^2}{26^2} = 1$ , for z=Range[-24,24,4],
  - Suppression of skew sextupole resonance:
    - $\frac{\langle y \rangle}{\sigma_y}$  for a particle with initial coordinate (5 $\sigma_x$ ,0,0,0,0,0)
    - $\frac{|y-\langle y\rangle|}{\sigma_y}$  for a particle with initial coordinate (5 $\sigma_x$ ,0,0,0,0,0)
- Variables: 80
  - 2 Octupoles
  - 54 sextupole pairs
  - 24 skew sextupole(symmetry of skew sextupole pair is broken)

![](_page_24_Figure_11.jpeg)

#### Optimization of LER (2)

![](_page_25_Figure_1.jpeg)

Difference resonance

# Optimization of LER (3)

Suppression of skew sextupole resonance

![](_page_26_Figure_2.jpeg)

#### Speed-up Method

- Brute-force dynamic aperture tracking is very time consuming
- The objective is first eased, for example only track 100 turns instead of 1000 turns.
- Some constraints must be satisfied and may be much faster. Referencing to Ehrilichman's work[arXiv: 1603.02459], the multiobjectives are classified into two kinds. The time consuming cost function be calculated only when the necessary constraints (or objective) be satisfied.

# Summary

- The multi-objective optimization has been used in light source machine (not only storage ring based) for a few years.
- We did a few multi-objective optimization for future colliders. It shows it could help us.
- The MODE is just a tool, no physics. Physics exist in the definition of objective function. We should continue to find smart objective functions to save time.