



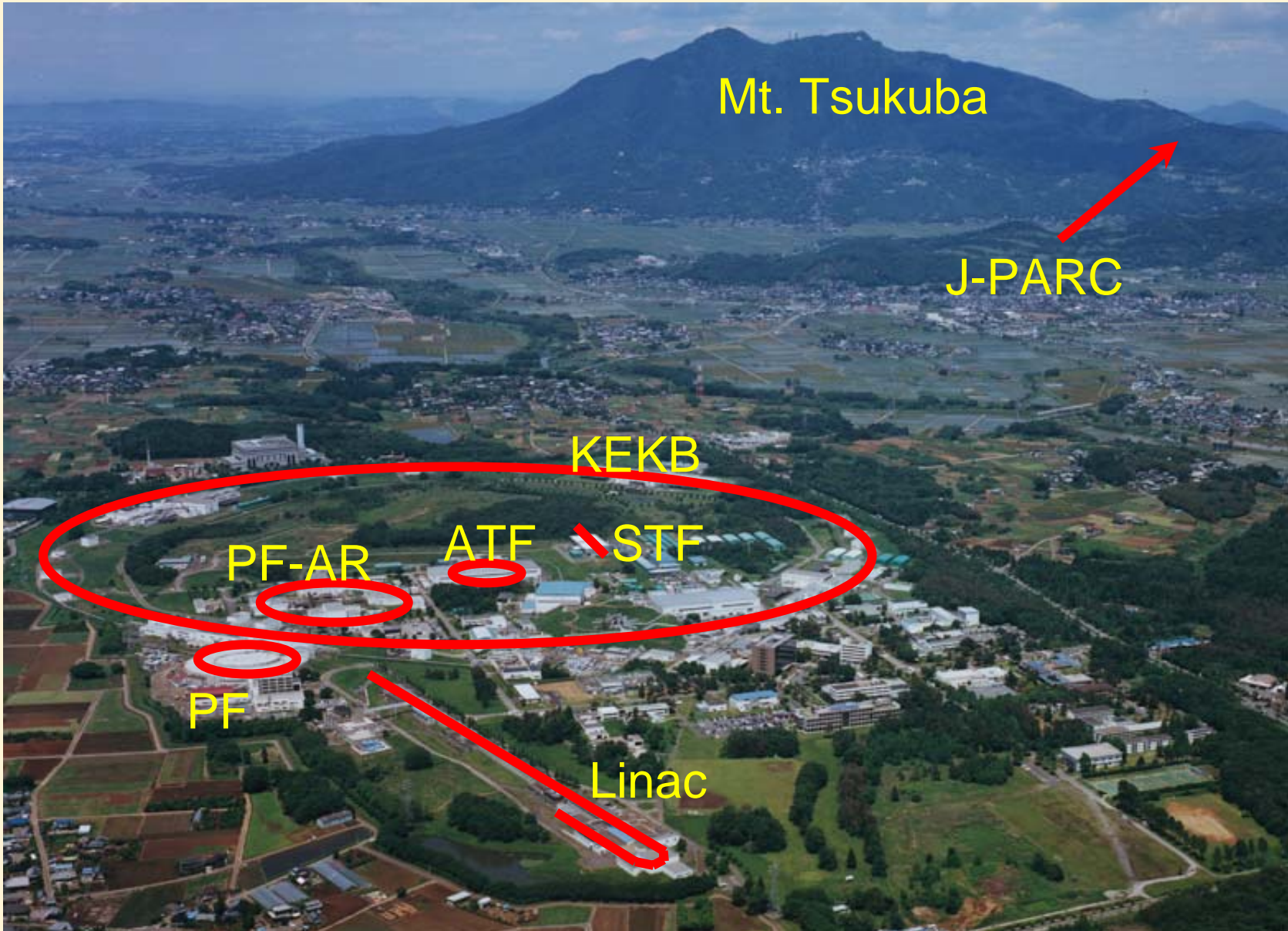
Control System of the KEKB Accelerator Complex

Evolution in several aspects

Kazuro Furukawa, KEK

KEKB Control Group

Linac Control Group





KEKB and Linac

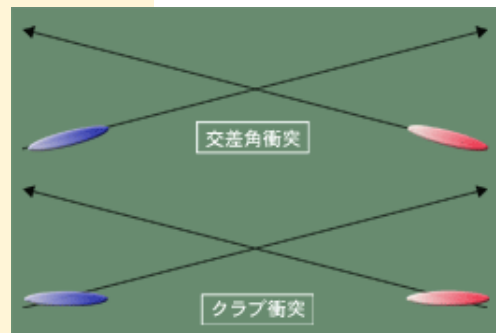
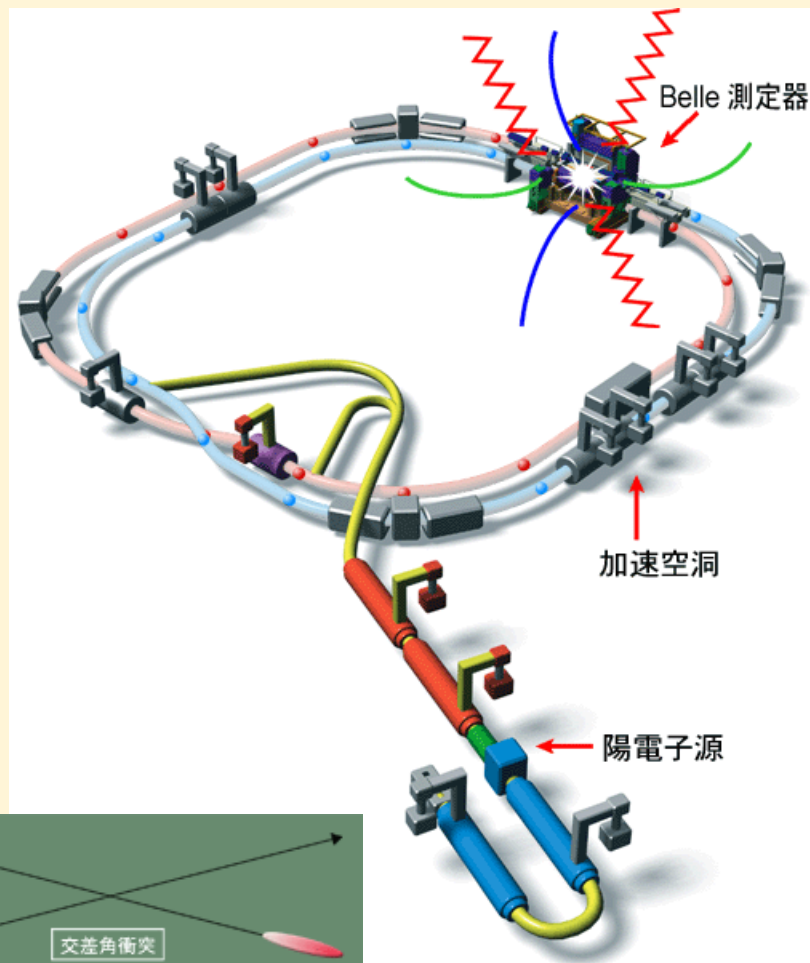
◆ KEKB B-factory: Electron/Positron Asymmetric Collider for CP-violation Study

❖ ~3km Dual-rings: Electron(8GeV - 1.4A) / Positron(3.5GeV - 1.8A)

- ❏ Stable and Robust Operation
- ❏ Many Active Operation Parameters
- ❏ Importance of Controls

◆ Linac:

- ❖ ~600m, 50Hz
- ❖ 8GeV 2nC Electron, 3.5GeV 1.2nC Positron
- ❏ Beam switchings for PF and PF-AR rings



Increase of Luminosity with Crab Cavities



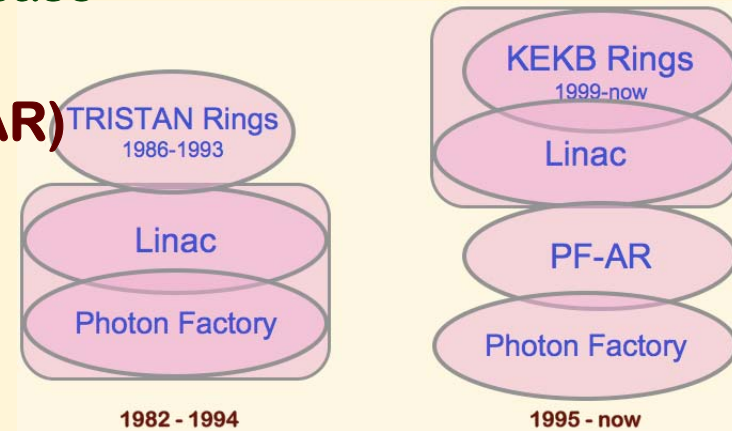
KEKB and Linac Control Systems

◆ Linac

- ❖ Controls Upgrade (1990~)1993
 - ✧ De-facto (and International) Standards, IP-only Networks
- ❖ No long Shutdown for KEKB upgrade
 - ✧ 3.5-times Energy increase, 10-times current increase
- ❖ Division changed at the end of Upgrade
- ❖ Three indirect User Facilities (KEKB, PF, PF-AR)
- ❖ Fewer resources

◆ KEKB

- ❖ 5-year Shutdown after TRISTAN 1994-1998
 - ✧ Precision requirements were much different for KEKB
- ❖ Complete transition of Controls
 - ✧ from Nodal at TRISTAN to EPICS+SAD at KEKB
- ❖ Basically Single-user (Belle)





Communication Network at Linac

◆ Fiber-optic Networks (1982~)

- ✧ Because of High-power modulators for rf systems
- ❖ ~30 Loops to connect many equipment controllers
- ✧ However, the fiber-optic Technology was not mature enough yet
 - ◆ Often Failed and Loop Topology made it difficult to identify the trouble

◆ All IP network (1993~)

- ❖ Still all Fiber-optic
 - ✧ Faster Ethernet enables shorter packets and less failures
- ❖ Inherited at J-PARC Controls as well

◆ Gradual Transition of Technologies

- ❖ From FDDI + 10Base-FL to 1000Base-LX + 100Base-Fx

◆ Redundancy (1996~)

- ✧ At more than 40 Ethernet links
- ❖ Helped continuous operation in spite of a failure at night
 - ✧ Redundant Transceivers, then Rapid Spanning-tree and HSRP/VRRP



Communication Network at KEKB

◆ TRISTAN

- ❖ **Token Ring and CAMAC Serial highways**
 - ✧ Token ring between mini-computers
 - ✧ CAMAC serial highways to equipment controllers

◆ KEKB

- ❖ **IP Network for EPICS**
 - ✧ FDDI+10BaseT to GbE+100Base-Tx
 - ◆ Sometimes unnecessary excess broadcast
- ❖ **ARCNet for equipment controllers**
 - ✧ More than 200 network segments
- ❖ **MXI-2 for VXI-based frames**
 - ✧ 20 segments
- ❖ **Keep some CAMAC Serial highways**
 - ✧ About 50 Crates



Equipment Controllers at Linac

◆ 1982~(1997) (1st generation)

- ❖ 300 microprocessor-based controllers
 - ✧ Linked together with home-grown fiber-optic network

◆ 1993~now (upgrade of controls)

- ❖ 150 PLCs (programmable logic controller)
 - ✧ Linked via only Fiber-optic Ethernet/IP
 - ◆ Control communication with servers and program development

◆ 1995~now (upgrade for KEKB)

- ❖ 30 VXI for rf measurement
- ❖ 5 VME / 10 CAMAC for Timing
- ❖ 20 VME for Beam monitors

◆ 2006~ (upgrade of BPM readout)

- ❖ 24 Oscilloscopes with WindowsXP IOC for 100 BPMs
 - ✧ 10Gs/s, 50Hz acquisition, local processing with 20 calibration parameter/BPM



Equipment Controllers at KEKB

◆ TRISTAN

❖ Mostly CAMAC

✧ Equipment group responsibility: CAMAC module and outside

◆ KEKB

❖ 100 VME/IOC without Analog processing

❖ 200 VXI/MXI mainframes for 900 BPMs

❖ 50 CAMAC crates are kept for rf and vacuum

❖ ARCNet boards for Magnet ps. settings, and others

❖ GPIB for Magnet ps. readback, and others

❖ PLCs for Magnet interlocks, and others



EPICS Transition at Linac

◆ Home-grown RPC at Linac (1990~/1993~)

- ❖ Bad timing but no choice because of end of old mini-computer support

◆ No real transition to EPICS yet at Linac

- ❖ There are middleware and applications

◆ LynxOS Transition was developed (1994~1996)

- ❖ To cover both RPC and EPICS with pthread, posix
 - ✧ Mostly working, Failed to get funding for Hardware/Software upgrade

◆ Gateways to EPICS in several ways

- ❖ Software-only IOC and Gateway (Clients to both RPC/CA)
- ❖ Portable Channel Access Server of EPICS-3.12 (1995~)
- ❖ Soft-IOC with device support to Linac RPC (2002~)

◆ Real IOCs are increasing

- ❖ PLC(rf,vacuum,magnet) and Linux, Oscilloscope(bpm) with Windows, VME(IlrF and timing)
- ❖ RPC servers read EPICS IOCs, EPICS gateways read RPC servers



EPICS Transition at KEKB

- ◆ **Some candidates discussed after Nodal at TRISTAN**
 - ❖ **RPC/CORBA based control design**
 - ❖ **Reflective memory (hardware shared memory) design**
- ◆ **No other choice than EPICS for KEKB**
 - ❖ **No man-power for control system software**
 - ❖ **The choice at SSC**
 - ❖ **International collaboration was attractive**



Archiver/Logger

◆ Linac

- ❖ **Several archivers with different filters and stored in ascii**
- ❖ **Replaced with two EPICS archivers (2002)**
 - ✧ **Channel archiver, with Java viewer, and Web-based viewer**
 - ✧ **KEKBlog, SADscript-based viewer**
 - ◆ **Both ~400MB/day, Dynamic ADEL changes**

◆ KEKB

- ❖ **KEKBlog, since 1998**
 - ✧ **Once there was a plan to replace it with Channel Archiver**
 - ◆ **Data conversion, no much performance difference**
 - ✧ **Only ADEL-based filter**
 - ◆ **~2GB/day**
 - ✧ **SADscript-based viewer is one of the most used applications**
 - ◆ **With Data analysis capability, easy manipulations**



Scripting Languages

◆ Heavy use because of rapid prototyping

◆ Linac

- ❖ (1992~) Tcl/Tk as Test tools on Unix
- ❖ (1997~) Tcl/Tk as Main Operator Programming Tool
- ❖ (Now) Mixture of Tcl/Tk, SADscript/Tk, Python/Tk
 - ✧ SADscript has most accelerator design capability
 - ◆ Covers many features like MATLAB, Mathematica, XAL, MAD

◆ KEKB

- ✧ (Nodal interpreter and Fortran covered everything at TRISTAN)
- ❖ Python covers many areas which is not covered by medm
- ❖ SADscript is used by operators and physicists everyday
 - ✧ Realization of novel ideas in hours
 - ◆ Only some ideas are effective, so rapid prototyping is important

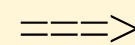
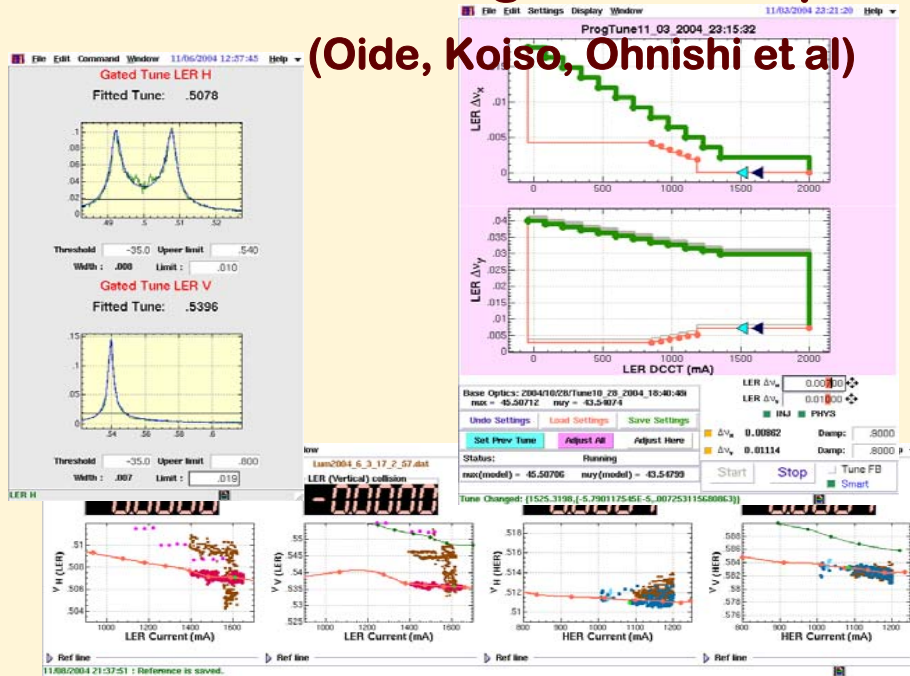
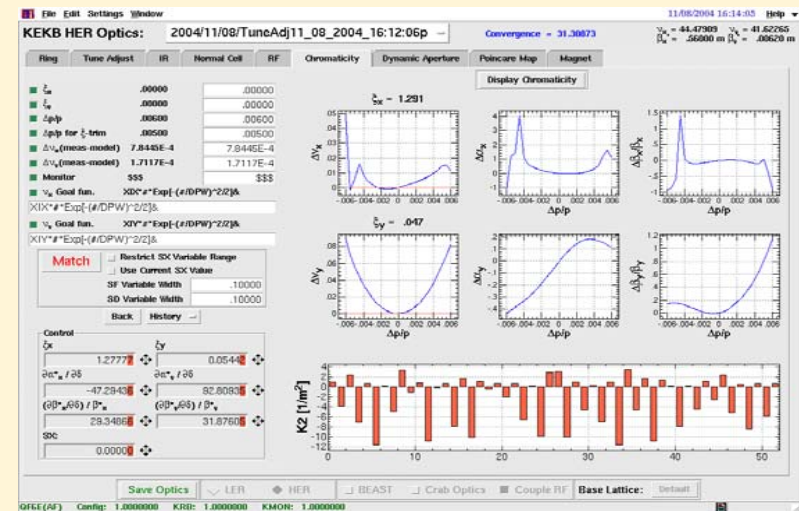
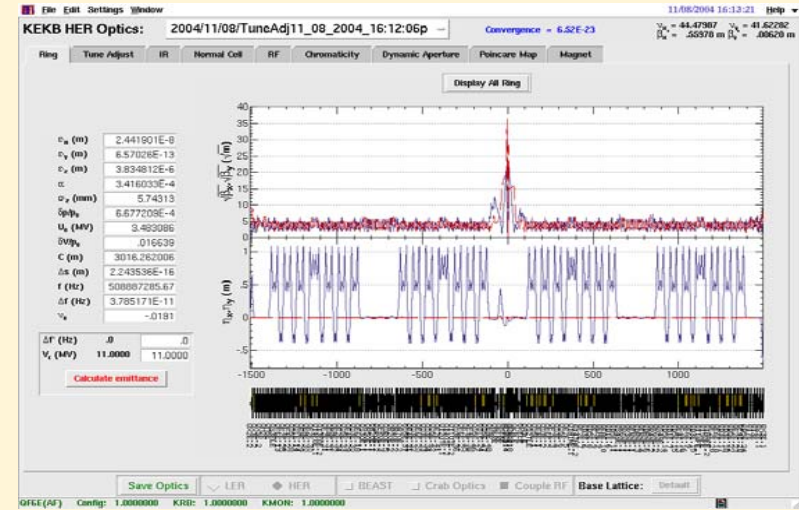


Virtual Accelerator in SADscript

◆ For Example in KEKB

- ❖ most Beam Optics Condition is maintained in the Optics Panel
- ❖ Other Panels Manipulate Parameters Communicating with the Optics Panel

(Oide, Koiso, Ohnishi et al)



Tune Measurement/Changer

Optics Panels



Near Future

◆ SADscript

- ❖ Will be maintained, but should look more at XAL - CSS

◆ EPICS

- ❖ Still many hopes waiting to be realized

◆ More integration between control systems

◆ PLC usage

- ❖ IEC61131-3 Standards

◆ FPGA usage

- ❖ More embedded controllers / instrumentations

◆ More reliability considerations

- ❖ Testing environments, Surveillance, Redundancy, etc.

◆ More operation side developments

Linac and KEKB groups will share the tasks



Summary

- ◆ **Linac had slow and gradual modernization**
 - ❖ No long Shutdown time, losing good timing
- ◆ **KEKB made big transition at the Construction**
 - ❖ 5-year Shutdown, Big help from EPICS community
 - ❖ Runs without much modification ever since
- ◆ **Control system design needed a balance between many aspects**
 - ❖ Large and Small group differences
- ◆ **EPICS and Scripting Languages brought a success to the both KEKB and Linac Beam Operations**
- ◆ **Linac and KEKB groups are ready to share more tasks for the future**



Thank you



Thank you



KEKB Control System (Hardware)

◆ GbE Fiber Optic Networks

- ❖ Single Broadcast Domain
- ❖ Central Control Room and 26 Local Control Rooms

◆ VME/IOC

- ❖ ~100 VME/IOC mostly with PowerPC CPU

◆ Field bus

- ❖ ~200 VXI thru MXI for BPM Instrumentations
- ❖ ~50 CAMAC for rf and Vacuum (inherited from TRISTAN)
- ❖ ~200 ArcNet network segments for Magnet Power Supplies, and other field Controllers
- ❖ GPIB for Instrumentations, RS232C, Modbus+ for PLCs

◆ Host Computers

- ❖ HP-UX/PA-Risc, Linux/x86 Controls Server
- ❖ 3 Tru64/Alpha with TruCluster
- ❖ Several Linux
- ❖ Many MacOSX
- ❖ (Solaris/Sparc for VxWorks)



KEKB Control System (Software)

- ◆ **EPICS 3.13.1 and 3.14.6,8**
- ◆ **VxWorks 5.3.1 mainly, and 5.5.1**
 - ❖ **Hope to upgrade EPICS/VxWorks Shortly**
- ◆ **IOC Development**
 - ❖ **CapFast, (VDCT) Perl, SADscript for Database Configuration**
 - ❖ **Oracle as a backend Database Management**
 - ❖ **Migration towards Postgresql**
- ◆ **Operational Application Development**
 - ❖ **MEDM(DM2k) for Startup**
 - ❖ **Python/Tk for Equipment Controls**
 - ❖ **SADScript/Tk for Beam Operation, etc**



Linac; History and Design Concept

◆ History

- ❖ 1978-1982: Construction of First Computer-controlled System with 8 mini-computers, >200 micro-computers, >30 optical loop networks
- ❖ 1989-1992: Design of the next system
- ❖ 1993-1997: Installation and expansion for KEKB

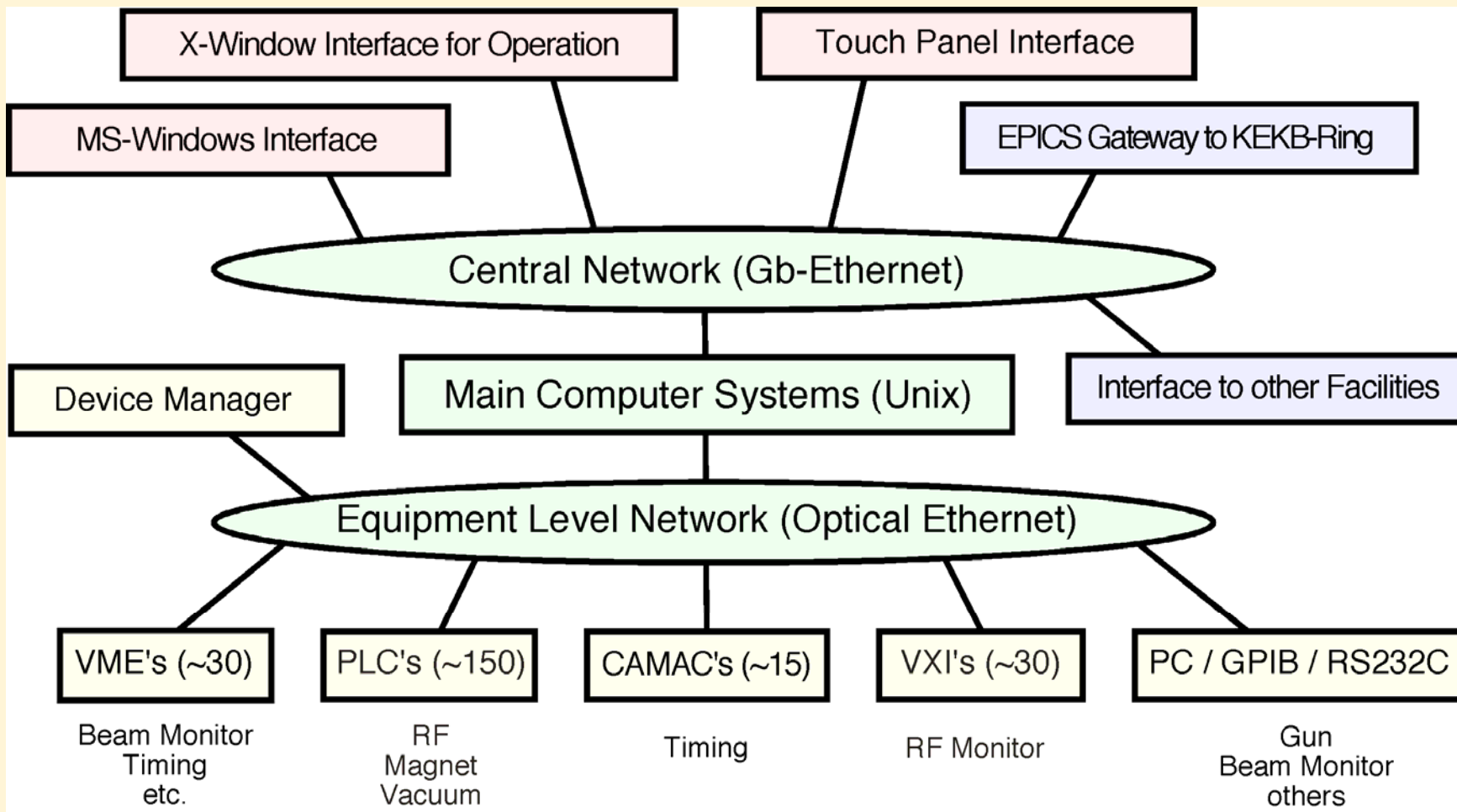
◆ Design Concept

- ❖ Use of International and/or de-facto Standards
- ❖ Use of Optical IP Networks for every Device controllers
 - ✧ No new field Networks, only IP Network (inherited by J-PARC as well)
- ❖ Both of above should make future upgrade easier
- ❖ (EPICS was not available widely at that time)



Linac; Physical Structure

◆ Multi-tier, Multi-hardware, Multi-client, ...





Linac; Software Architecture

- ◆ **Base control software structure for Multi-platform**
 - ❖ any Unix, OS9, LynxOS (Realtime), VMS, DOS, Windows, MacOS
 - ❖ TCP - UDP General Communication Library
 - ❖ Shared-Memory, Semaphore Library
 - ❖ Simple Home-grown RPC (Remote Procedure Call) Library
 - ❖ Memory-resident Hash Database Library
- ◆ **Control Server software**
 - ❖ Lower-layer servers (UDP-RPC) for control hardware
 - ❖ Upper-layer server (TCP-RPC) for accelerator equipment
 - ❖ Read-only Information on Distributed Shared Memory
 - ❖ Works redundantly on multiple servers
- ◆ **Client Applications**
 - ❖ Established applications in C language with RPC
 - ❖ Many of the beam operation software in scripting language,
 - ✧ **Tcl/Tk**
 - ✧ **SADscript/Tk**



Network with only IP/Ethernet

- ◆ **The policy chosen when we upgrade Linac in 1993**
 - ❖ **Make network management simpler**
 - ✧ **Faster switches, routing, network-booting, etc.**
 - ❖ **Avoid Hardware failure and analysis effort with old field network**
 - ✧ **Home-grown field networks need much dedicated man-power**
 - ❖ **Cost for optical Ethernet went down at around 1995**
 - ✧ **Linac has high-power modulator stations, noise source**
 - ❖ **Nowadays many facilities have this policy with GbE**
 - ✧ **J-PARC controls basically followed this**
 - ❖ **More and more intelligent network devices**
 - ✧ **ex. Oscilloscopes with Windows/3GHz-Pentium built-in**
 - ✧ **Even EPICS IOC, MATLAB, or others can be embedded**
 - ❖ **Network components can be replaced one-by-one**
 - ❖ **Security consideration will be more and more important**



EPICS

- ◆ **Now is a kind standard, but ...**
- ◆ **Object-oriented design support**
 - ❖ **Naming scheme, and/or design of new record**
 - ❖ **More software-engineering support favored**
 - ✧ **Several different efforts to provide better environment**
 - ◆ **Java IOC (M. Kraimer), Control system studio (M. Clausen), Data access (R. Lange)**
- ◆ **Security mechanisms**
 - ❖ **User, Host-based protection available**
 - ❖ **More security**
 - ✧ **Dynamic controls of security**
 - ✧ **Access logging**
- ◆ **Dynamic configuration of database**
 - ❖ **Dynamic creation / loading of records**
 - ❖ **Dynamic removal of records**
 - ✧ **Maybe some part of the codes can be shared with redundant-IOC project**



Magnet Controls

- ◆ It is typical controls and still many things to do
- ◆ Many magnets and many power supplies
 - ✧ No one-to-one correspondence
 - ✧ Which hardware interface to use
- ◆ Procedures
 - ✧ Interlock status, on/off, analog with some precision, etc
 - ✧ Energy, kick - field - current conversions
 - ✧ How to represent those conversion curves
 - ✧ Timing synchronous operation
 - ✧ for tune change, orbit correction, etc.
 - ✧ Standardization



Phronesis

- ◆ **Aristotle's view of wisdom.**
- ◆ **Contrary to Sophia; the ability to understand the universal truth**
- ◆ **Phronesis is the ability to find a way to achieve an overall goodness**



Thank you