



Implementing New Beam Line Elements into a Moment Method Beam Dynamics Code



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- General Potential Function
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 - Four-Term
- Beam Dynamics Comparison

Beam Dynamics Code

→ TEMF, TU Darmstadt

→ Moment approach

Particle density distribution fct.:

$$f(\vec{r}, \vec{p}, \tau)$$

Space coordinates: $\vec{r} = (x, y, z)$

Norm. Momentum: $\vec{p} = (p_x, p_y, p_z)$

Equivalent time: $\tau = c \cdot t$

→ Vlasov equation

Beam Dynamics Code

→ TEMF, TU Darmstadt

→ Moment approach

→ Vlasov equation

$$\frac{\partial f}{\partial \tau} + \frac{\partial f}{\partial \vec{r}} \cdot \frac{\vec{p}}{\gamma} + \frac{\partial f}{\partial \vec{p}} \cdot \frac{\vec{F}}{m_0 c^2} = 0$$

→ for “slow” varying \vec{F}

→ 6D numerically solving \neq fast

- Approach: Discrete set of characteristic moments for $f(\vec{r}, \vec{p}, \tau)$:

6D \rightarrow 1D time integration

- Moment definition:

$$\langle \mu \rangle = \int_{\Omega} \mu f(\vec{r}, \vec{p}, \tau) d\Omega \quad \Omega = \{\vec{r}, \vec{p}\}$$

- First order: $\mu \in \{x, y, z, p_x, p_y, p_z\}$
- Higher order: $\mu \in \{(x - \langle x \rangle)^{l_1} \cdot \dots \cdot (p_z - \langle p_z \rangle)^{l_6}, \dots\}$

V-Code

- Second order:

$$\begin{array}{ll} M_{xx} = \sigma_x^2 = \langle (x - \langle x \rangle)^2 \rangle & M_{xy} = \langle xy \rangle_{avc} = \langle (x - \langle x \rangle)(y - \langle y \rangle) \rangle \\ M_{yy} = \sigma_y^2 & M_{xz} = \langle xz \rangle_{avc} \\ M_{zz} = \sigma_z^2 & M_{yz} = \langle yz \rangle_{avc} \end{array}$$

$$\begin{array}{cccccc} M_{xx} & M_{xy} & M_{xz} & M_{yy} & M_{yz} & M_{zz} \\ M_{xp_x} & M_{xp_y} & M_{xp_z} & M_{yp_x} & M_{yp_y} & M_{yp_z} \\ M_{p_x p_x} & M_{p_x p_y} & M_{p_x p_z} & M_{p_y p_y} & M_{p_y p_z} & M_{p_z p_z} \end{array}$$

Time evolution:

$$\frac{\partial \langle \mu \rangle}{\partial \tau} = \frac{\partial}{\partial \tau} \int \mu f d\Omega = \int f \frac{\partial \mu}{\partial \tau} + \mu \frac{\partial f}{\partial \tau} d\Omega$$

V-Code

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$$\begin{array}{ll} M_{xx} = \sigma_x^2 = \langle (x - \langle x \rangle)^2 \rangle & M_{xy} = \langle xy \rangle_{avc} = \langle (x - \langle x \rangle)(y - \langle y \rangle) \rangle \\ M_{yy} = \sigma_y^2 & M_{xz} = \langle xz \rangle_{avc} \\ M_{zz} = \sigma_z^2 & M_{yz} = \langle yz \rangle_{avc} \end{array}$$

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Time evolution:

$$\begin{aligned} \frac{\partial \langle \mu \rangle}{\partial \tau} &= \left\langle \frac{\partial \mu}{\partial \langle \vec{r} \rangle} \right\rangle \left\langle \frac{\vec{p}}{\gamma} \right\rangle + \left\langle \frac{\partial \mu}{\partial \langle \vec{p} \rangle} \right\rangle \left\langle \frac{\vec{F}}{m_0 c^2} \right\rangle \\ &\quad + \left\langle \frac{\partial \mu}{\partial \vec{r}} \frac{\vec{p}}{\gamma} \right\rangle + \left\langle \frac{\partial \mu}{\partial \vec{p}} \frac{\vec{F}}{m_0 c^2} \right\rangle \end{aligned}$$

V-Code

- Second order:

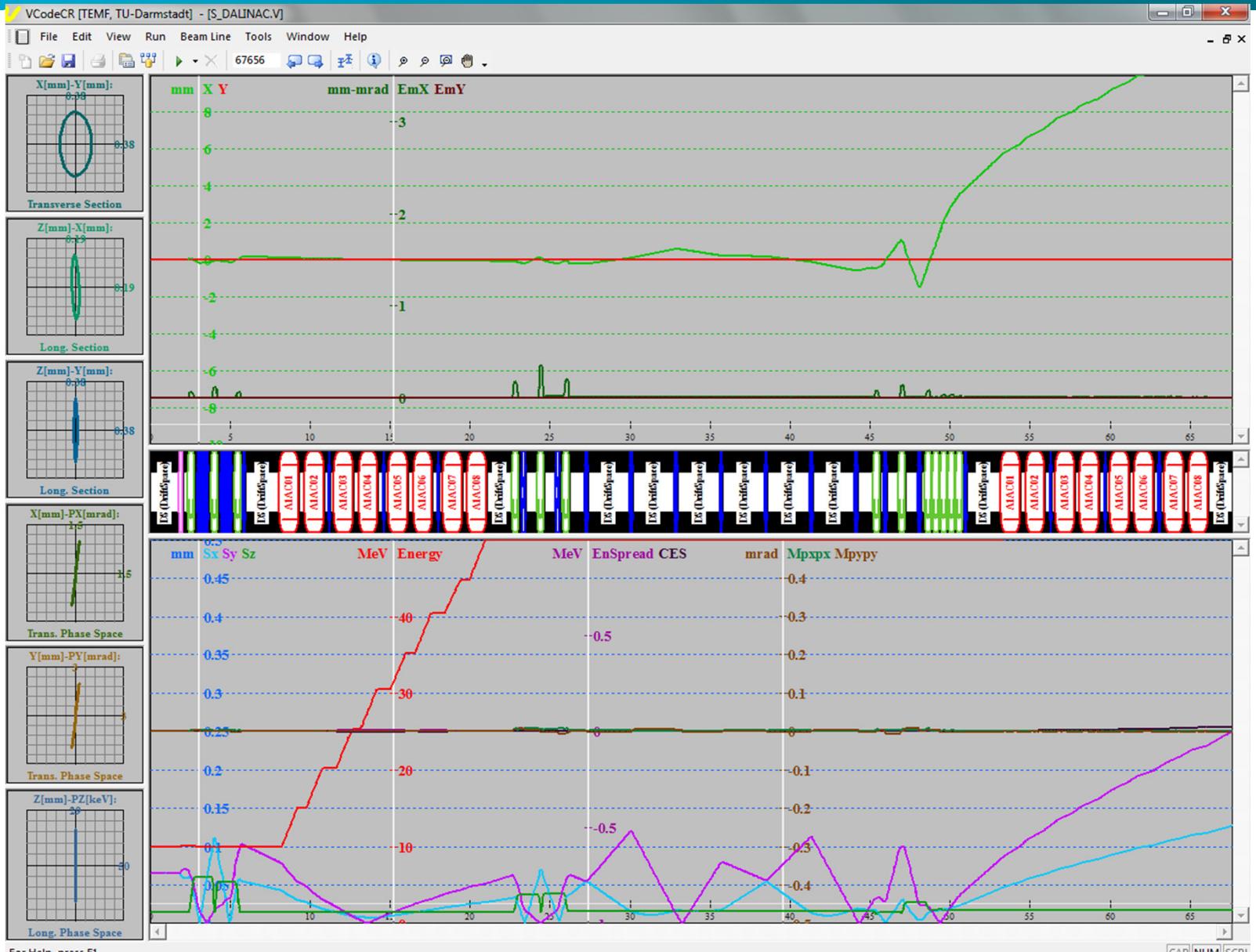
$$\begin{array}{ll}
 M_{xx} = \sigma_x^2 = \langle (x - \langle x \rangle)^2 \rangle & M_{xy} = \langle xy \rangle_{avc} = \langle (x - \langle x \rangle)(y - \langle y \rangle) \rangle \\
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 \end{array}$$

$$\begin{array}{ccccccccc}
 M_{xx} & M_{xy} & M_{xz} & M_{yy} & M_{yz} & M_{zz} \\
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Time evolution:

$$\begin{aligned}
 \frac{\partial \langle \mu \rangle}{\partial \tau} = & \left\langle \frac{\partial \mu}{\partial \langle \vec{r} \rangle} \right\rangle \left\langle \frac{\vec{p}}{\gamma} \right\rangle + \left\langle \frac{\partial \mu}{\partial \langle \vec{p} \rangle} \right\rangle \left\langle \frac{\vec{F}}{m_0 c^2} \right\rangle \\
 & + \left\langle \frac{\partial \mu}{\partial \vec{r}} \right\rangle \left\langle \frac{\vec{p}}{\gamma} \right\rangle + \left\langle \frac{\partial \mu}{\partial \vec{p}} \right\rangle \left\langle \frac{\vec{F}}{m_0 c^2} \right\rangle
 \end{aligned}$$

V-Code



Data input:

- Ensemble file



Data input:

- Ensemble file
- Field parameter file



V-Code

Data input:

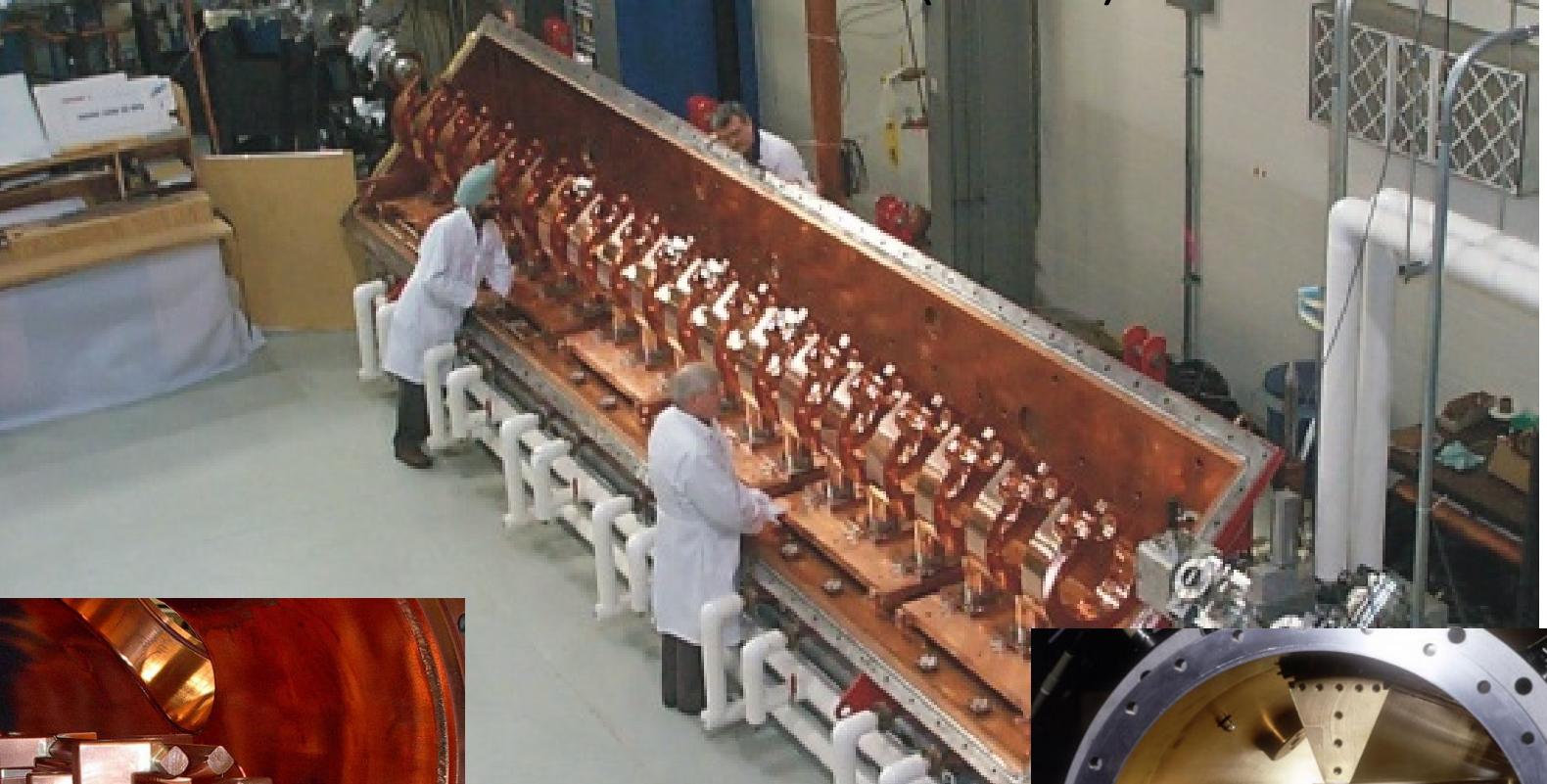
- Ensemble file
- Field parameter file
- Beam line file

We Th Fr Sa **Su** Mo Tu We Th Fr Sa **Su** Mo Tu We Th Fr Sa **Su** Mo Th

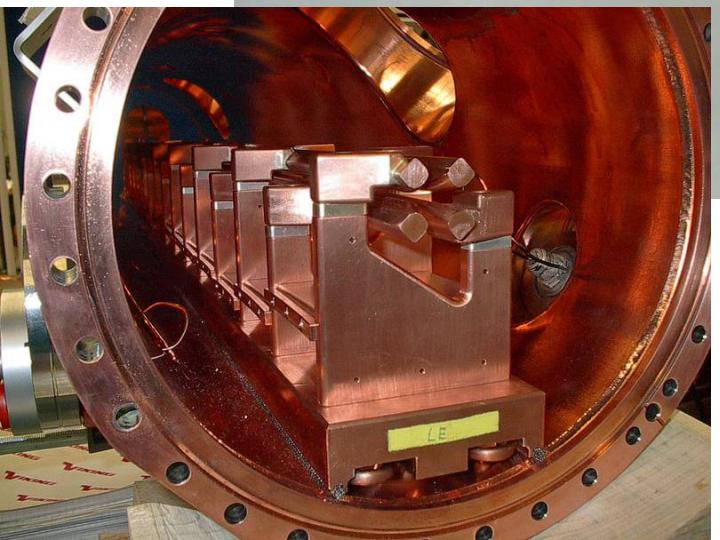


Radio Frequency Quadrupole

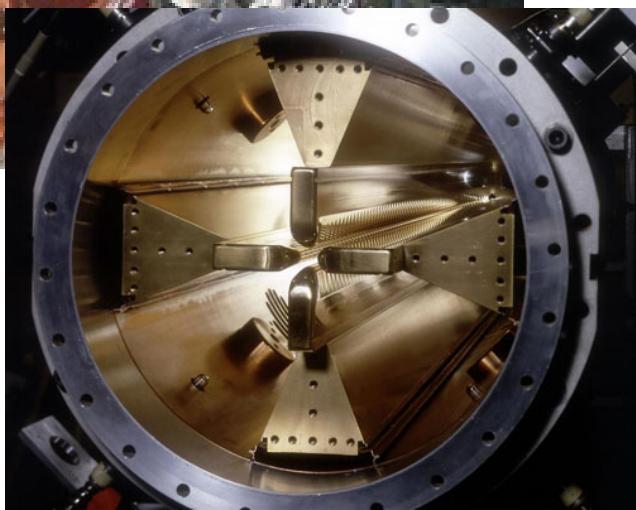
ISAC 35MHz RFQ (Triumf)



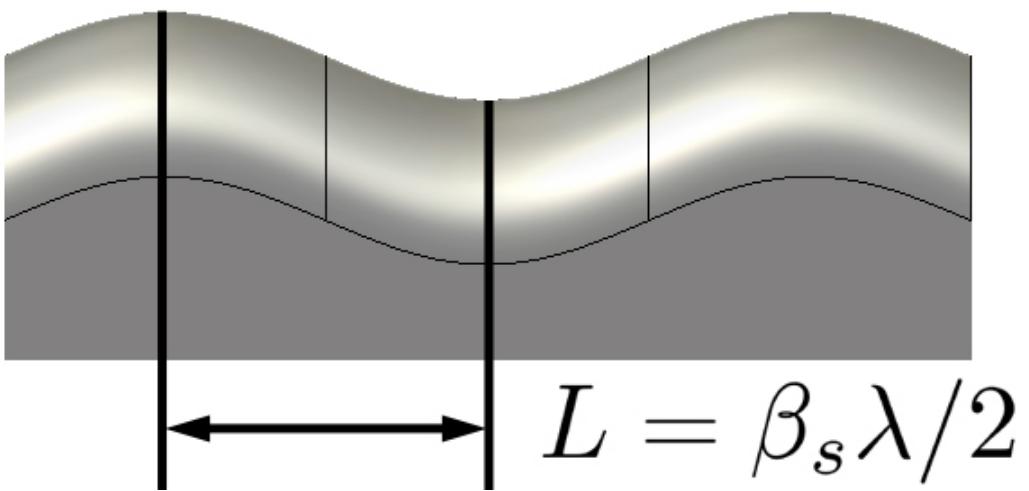
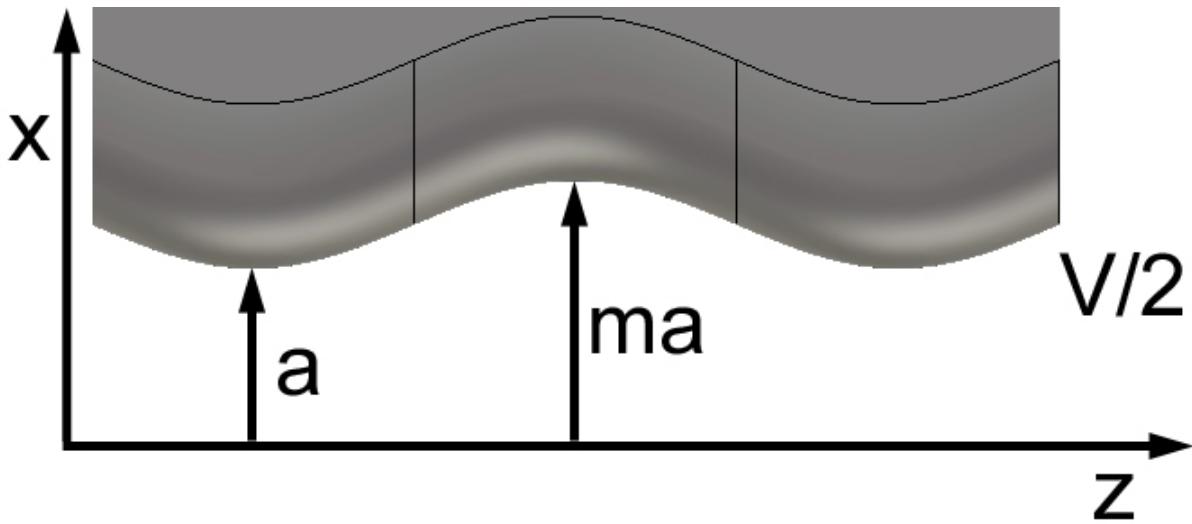
← 4 rod type



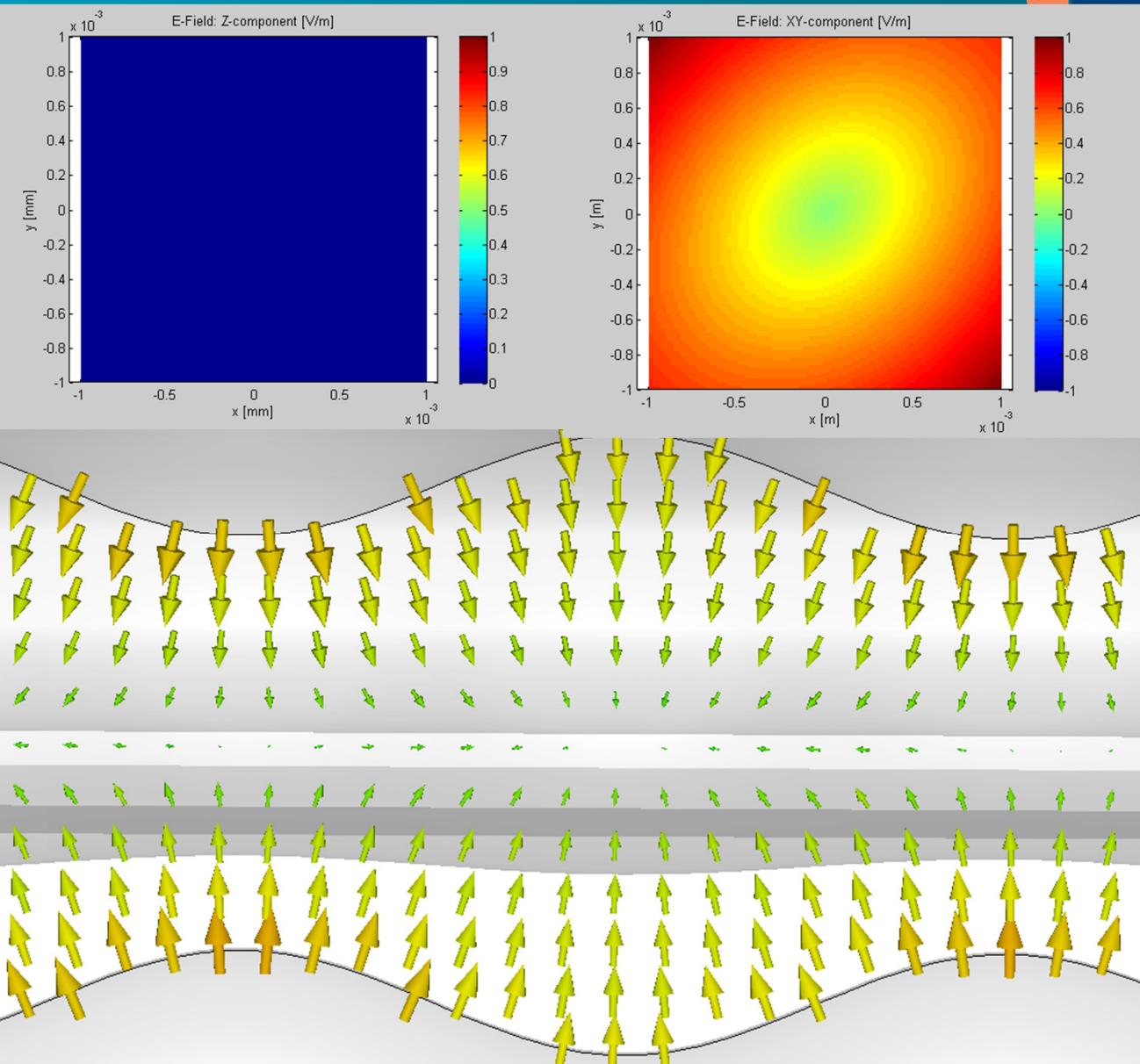
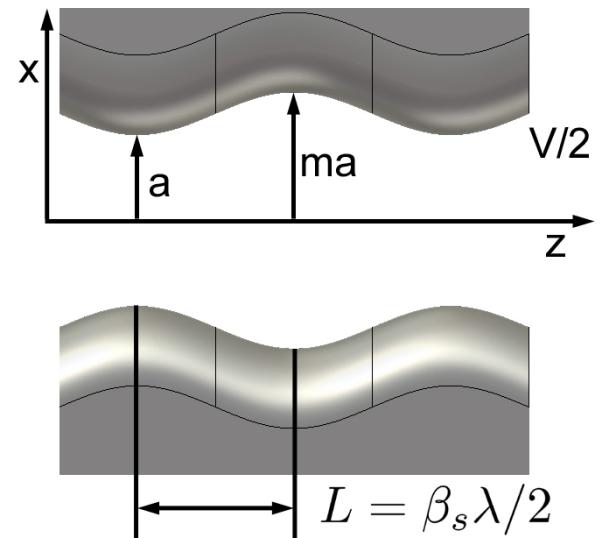
4 vane type →



Radio Frequency Quadrupole

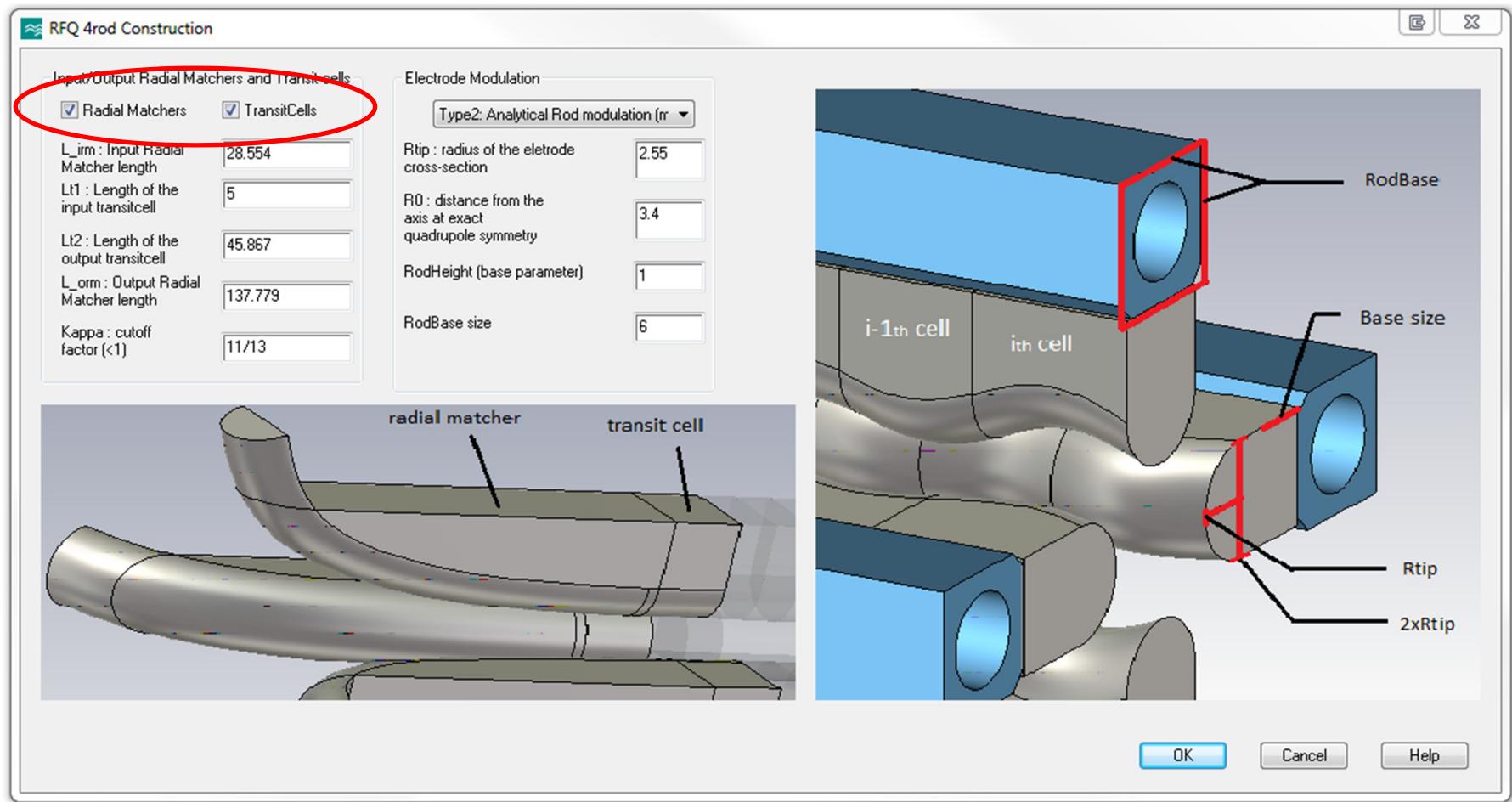


Radio Frequency Quadrupole



Radio Frequency Quadrupole

CST Studio Suite



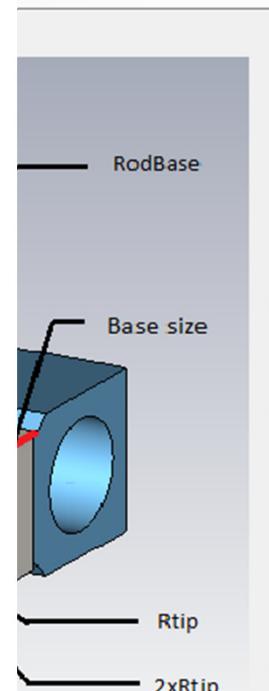
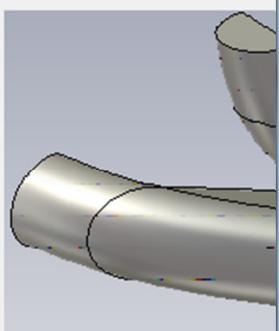
Radio Frequency Quadrupole

CST Studio Suite

RFQ 4rod Construction

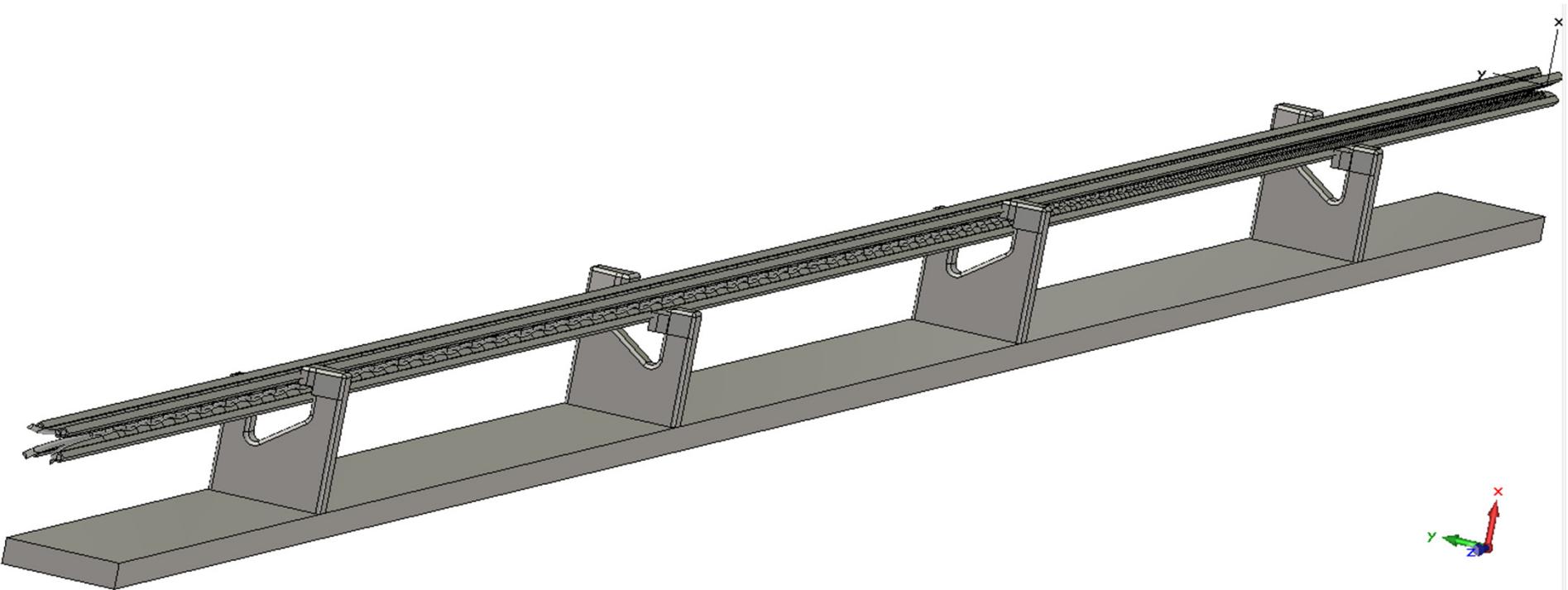
Input/output Radial Matchers and
 Radial Matchers Transverse
L_irm : Input Radial Matcher length
Lt1 : Length of the input transitcell
Lt2 : Length of the output transitcell
L_orm : Output Radial Matcher length
Kappa : cutoff factor (<1)

1.025 4.762
1.025 4.762
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1.025 4.763
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1.025 4.764
1.025 4.764
1.025 4.764
1.025 4.764
1.028 4.765
1.031 4.765
1.034 4.766
1.037 4.766
1.04 4.767
1.043 4.768
1.046 4.768
1.049 4.769



Cancel Help

Radio Frequency Quadrupole



Implementation

General potential function (Quasistatic):

$$U(r, \theta, z, t) = \sin(\omega t + \phi) \left[\sum_{p=0}^{\infty} A_{0,2p+1} r^{2(2p+1)} \cos(2(2p+1)\theta) + \sum_{n=1}^{\infty} \sum_{s=0}^{\infty} A_{n,s} I_{2s}(knr) \cos(2s\theta) \cos(knz) \right]$$

$$n+s = 2p+1$$

Implementation

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$$n+s = 2p+1$$

Laplace

$$\frac{\partial^2 V}{\partial r^2} + \frac{1}{r} \frac{\partial V}{\partial r} + \frac{1}{r^2} \frac{\partial^2 V}{\partial \theta^2} + \frac{\partial^2 V}{\partial z^2} = 0$$

Implementation

General potential function (Quasistatic):

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$$k = 2\pi/2L$$
$$2L = \beta_s \lambda$$
$$n+s = 2p+1$$

Implementation

General potential function (Quasistatic):

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$$n+s = 2p+1$$

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Implementation

Two-Term Potential Function:

$$U(r, \theta, z, t) = \sin(\omega t + \phi) \left[A_{0,1} r^2 \cos(2\theta) + A_{1,0} I_0(kr) \cos(2\theta) \cos(kz) \right]$$

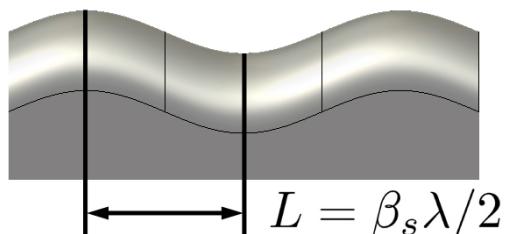
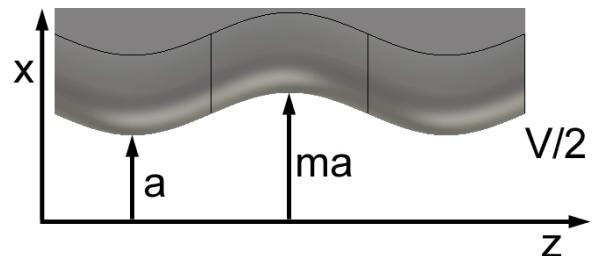
Collocation points:

- $U = V_0/2, r = a, \theta = 0, z = 0$
- $U = V_0/2, r = ma, \theta = \pi/2, z = 0$

Multipole coefficients:

$$A_{0,1} = \frac{V_0}{2a^2} \frac{I_0(ka) + I_0(kma)}{m^2 I_0(ka) + I_0(kma)} = \frac{V_0}{2a^2} X$$

$$A_{1,0} = \frac{V_0}{2} \frac{m^2 - 1}{m^2 I_0(ka) + I_0(kma)} = \frac{V_0}{2} B$$



Implementation

Two-Term Potential Function:

$$U(r, \theta, z, t) = \sin(\omega t + \phi) \left[A_{0,1} r^2 \cos(2\theta) + A_{1,0} J_0(kr) \cos(2\theta) \cos(kz) \right]$$

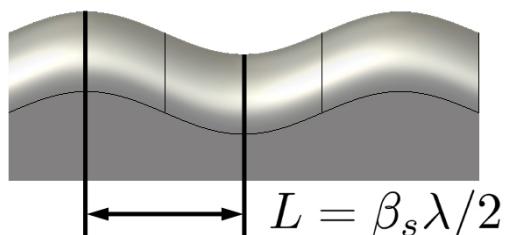
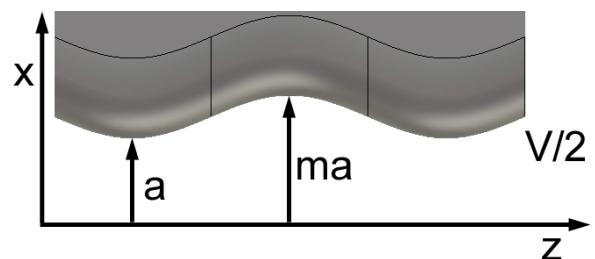
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Implementation

Two-Term Potential Function:

$$\rightarrow \vec{E} = -\nabla U$$

$$E_r = \sin(\omega t + \phi) \frac{V_0}{2} \left[X \frac{2r}{a^2} \cos(2\theta) + BkI_1(kr) \cos(kz) \right]$$

$$E_\theta = \sin(\omega t + \phi) \frac{V_0}{2} \left[-X \frac{r}{a^2} 2 \sin(2\theta) \right]$$

$$E_z = \sin(\omega t + \phi) \frac{V_0}{2} \left[-BkI_0(kr) \sin(kz) \right]$$

Implementation

Two-Term Potential Function:

$$\rightarrow \vec{E} = -\nabla U$$

Implementation:

$$\rightarrow I_n(kr) : \text{Taylor expansion}$$

$$\rightarrow E_{MAX} \sin(\omega t + \phi)$$

$$E_\theta: \frac{dE_\theta}{dr} \text{ at } \pi/4$$

E_z on axis

$$E_r: E_\theta, E_z \text{ and } \nabla \cdot \vec{E} = 0$$

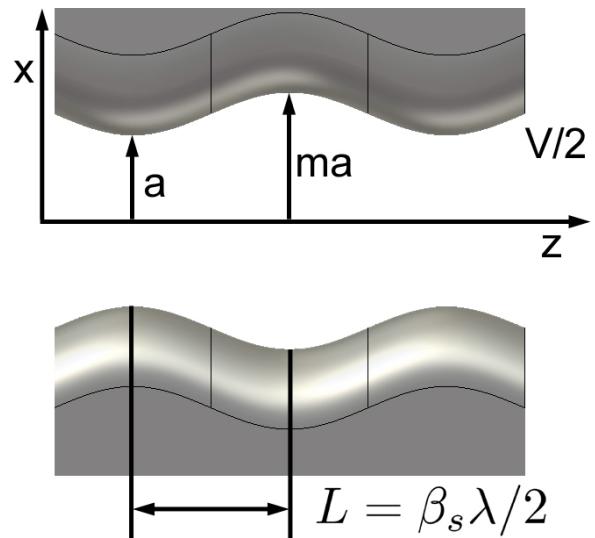
Implementation

Four-Term Potential Function:

$$U(r, \theta, z, t) = \sin(\omega t + \phi) \left[A_{0,1} r^2 \cos(2\theta) + A_{0,3} r^6 \cos(6\theta) + A_{1,0} I_0(kr) \cos(kz) + A_{1,2} I_4(kr) \cos(kz) \cos(4\theta) \right]$$

Collocation points:

	U	z	r	θ
1	$V_0/2$	0	a	0
2	$-V_0/2$	0	ma	$pi/2$
3	$V_0/2$	0	$\sqrt{(a + \rho)^2 + \rho^2}$	$\cos^{-1}(\frac{a+\rho}{r})$
4	$-V_0/2$	0	$\sqrt{(ma + \rho)^2 + \rho^2}$	$\cos^{-1}(\frac{ma+\rho}{r})$



Implementation

Four-Term Potential Function:

$$\rightarrow \vec{E} = -\nabla U$$

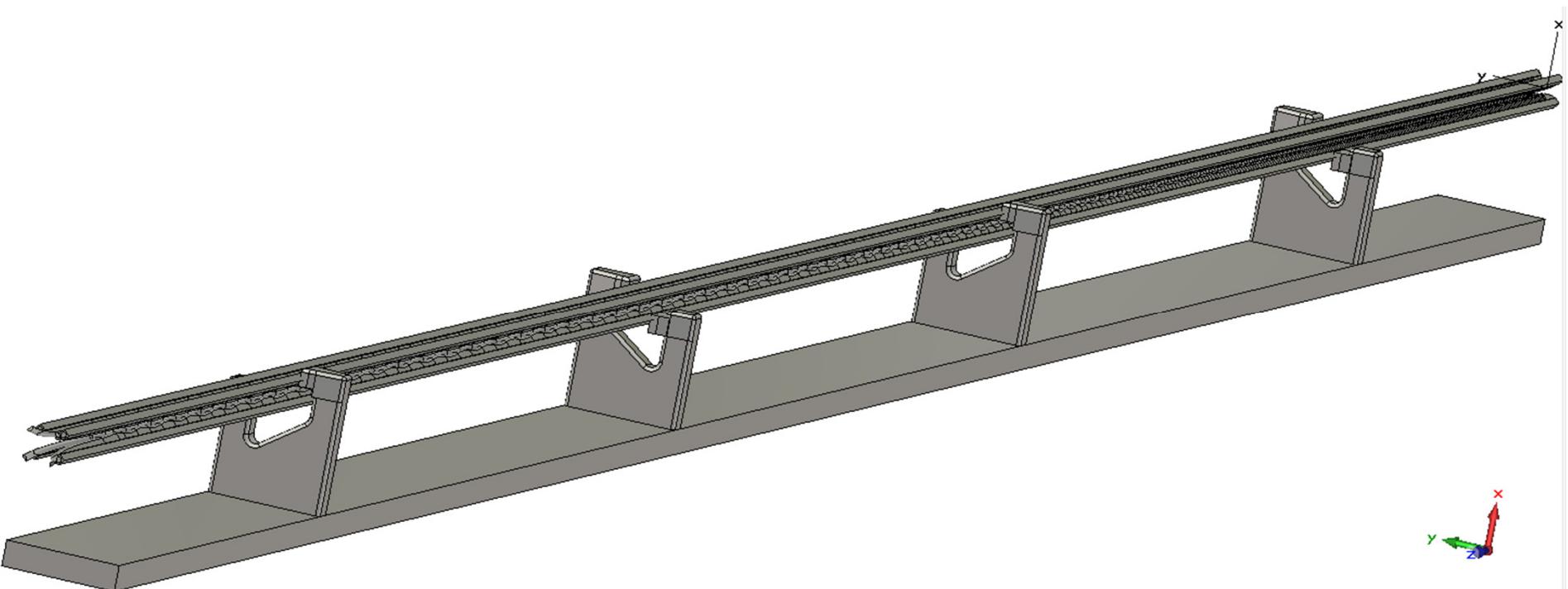
$$E_r = \sin(\omega t + \phi) \left[\begin{aligned} & 2A_{0,1}r \cos(2\theta) + 6A_{0,3}r^5 \cos(6\theta) \\ & + kA_{1,0}I_1(kr) \cos(kz) \\ & + kA_{1,2}I_5(kr) \cos(kz) \cos(4\theta) \end{aligned} \right]$$

$$E_z = \sin(\omega t + \phi) \left[\begin{aligned} & -kA_{1,0}I_0(kr) \sin(kz) \\ & -kA_{1,2}I_4(kr) \sin(kz) \cos(4\theta) \end{aligned} \right]$$

$$E_\theta = \sin(\omega t + \phi) \left[\begin{aligned} & -2A_{0,1}r \sin(2\theta) - 6A_{0,3}r^5 \sin(6\theta) \\ & - 4A_{1,2}I_4(kr) \cos(kz) \sin(4\theta) \end{aligned} \right]$$

3D Field Maps

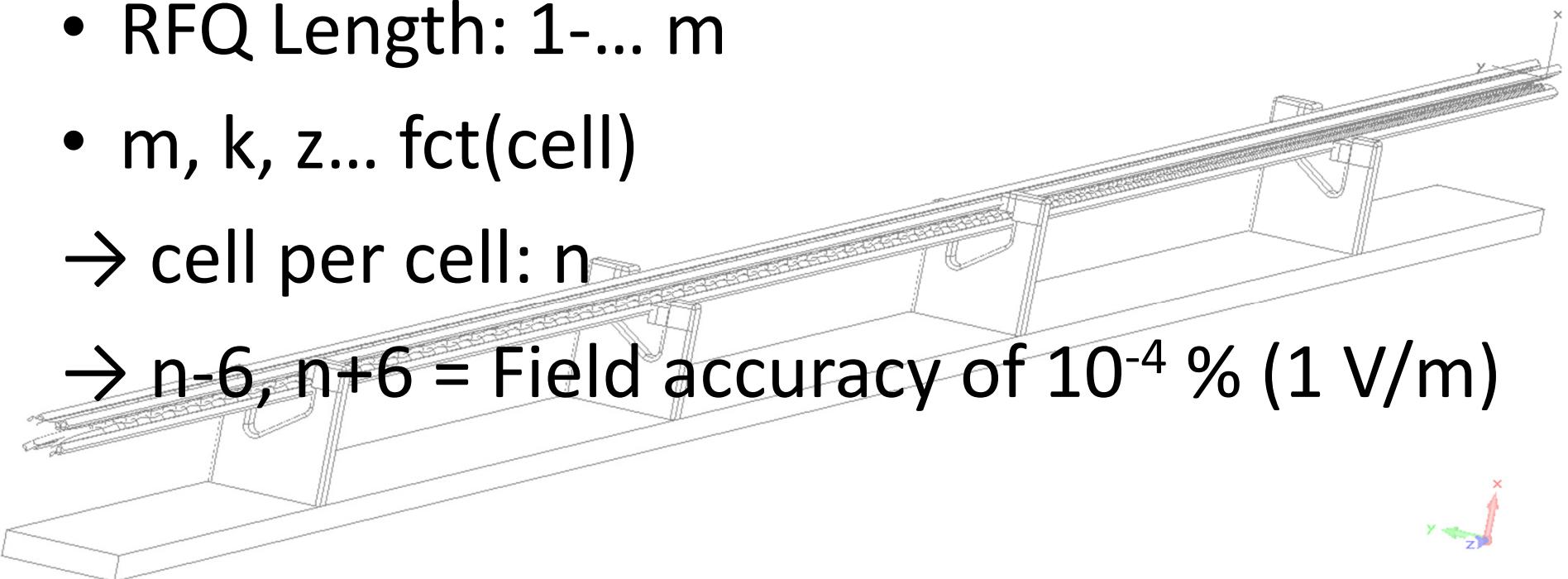
Four-Term Potential Function:



3D Field Maps

Four-Term Potential Function:

- RFQ Length: 1-... m
 - m, k, z... fct(cell)
- cell per cell: n
- $n-6, n+6 = \text{Field accuracy of } 10^{-4} \text{ \% (1 V/m)}$

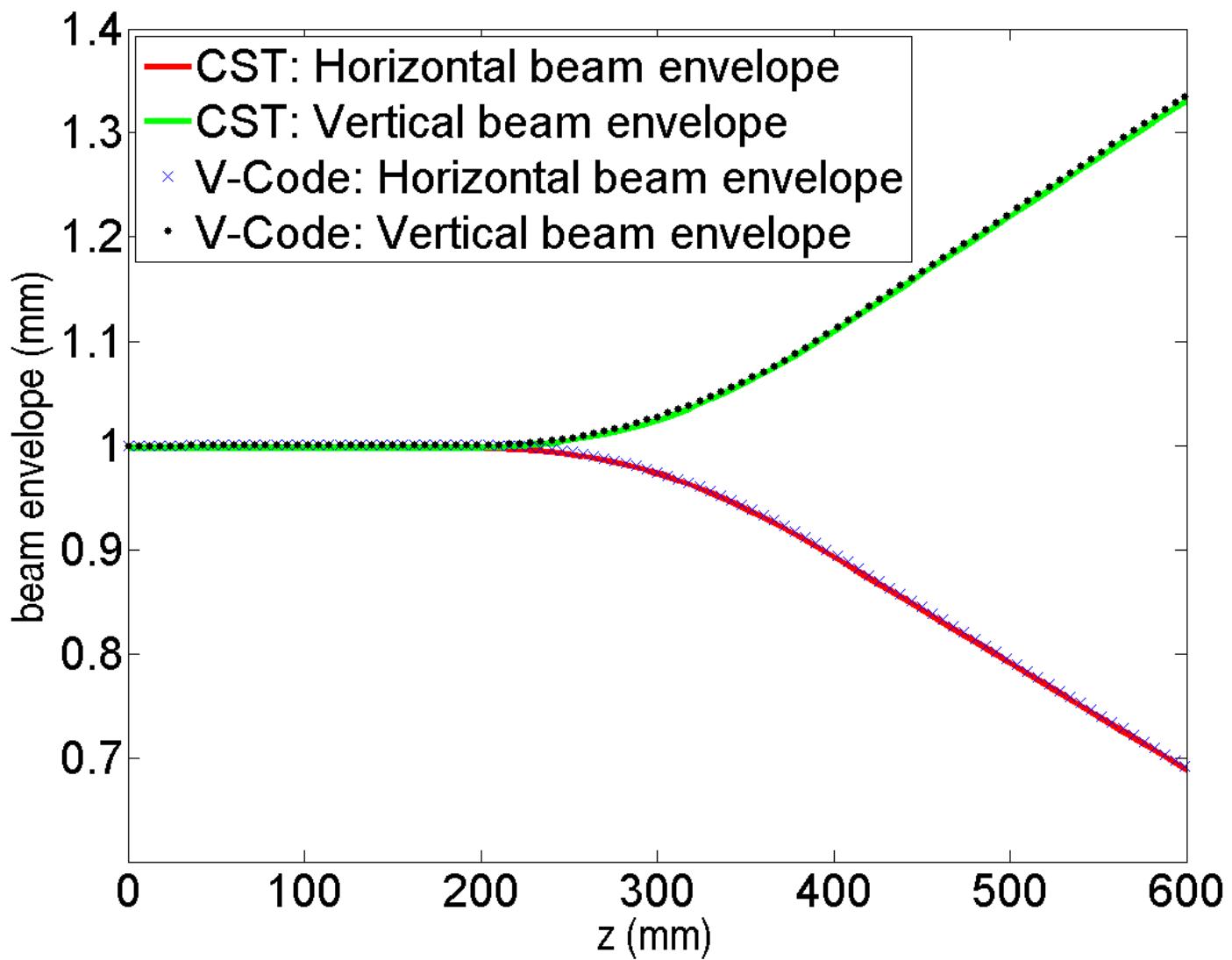


Beam Dynamics Comparison

Implementation verification:

- V-Code
- CST Particle Tracker
- Track
- Toutatis
- ...

Beam Dynamics Comparison



0-166 mm:
DT
166-434 mm:
Quad
434-600 mm:
DT
 $< 1\%$

Conclusions

RFQ implementation in V-Code:

- Quasistatic approach
- Two-term potential
- Cell-by-cell components
 - Accurate field parameters
 - Additional geometry parameter
- Beam dynamics comparison
- Four-term potential