

The TRIUMF Optimization Platform and Application to the E-linac Injector

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Outline

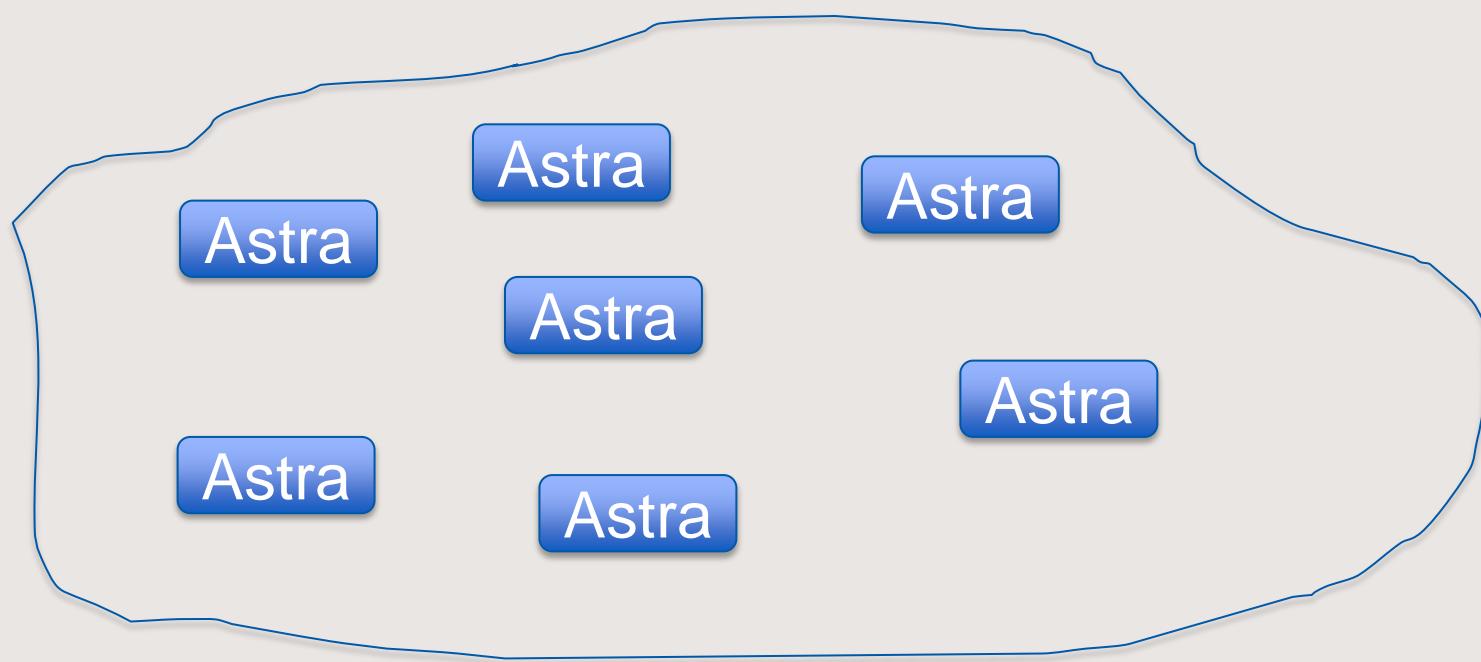
- Genetic optimization
- Genetic optimization for accelerators
- TRIUMF optimization software
 - Requirements
 - Design
- Apply to TRIUMF e-linac

Multi-Objective Global Optimization

- Multi-Objective Genetic Algorithms (MOGA)
 - Define *variables, constraints, objectives*
 - Initial population
 - Iterate:
 - Select parent individuals
 - Create child individuals (mutation, crossing)
 - Pareto dominance
- Benefits:
 - True global optimization (with caveates)

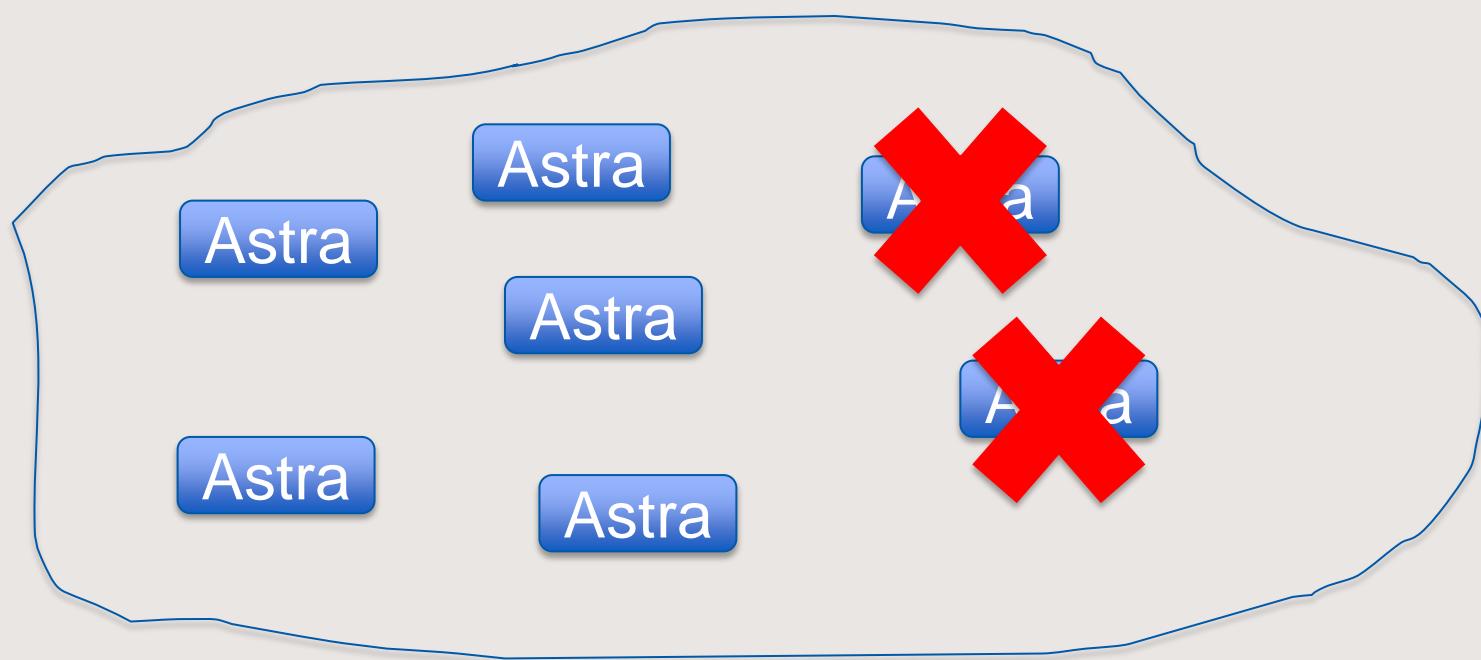
MOGA for Accelerator Design

- Wrapper (Astra, ELEGANT, etc)
- Run Astra many times
 - Different input parameters
 - Covers all search space



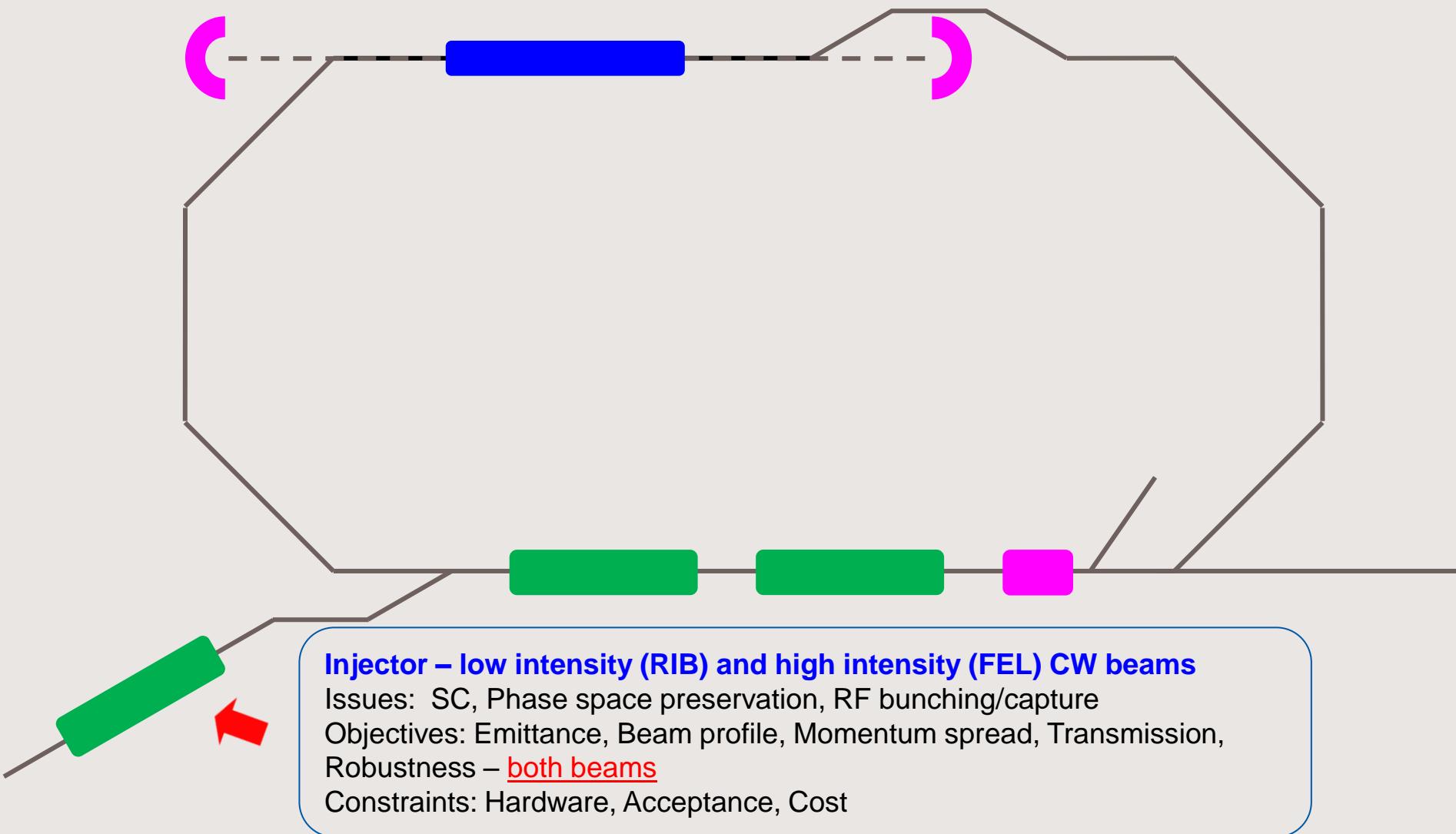
MOGA for Accelerator Design

- Extract constraints/objectives
 - Emittance, bunch length, etc.
- Discriminate toward solutions

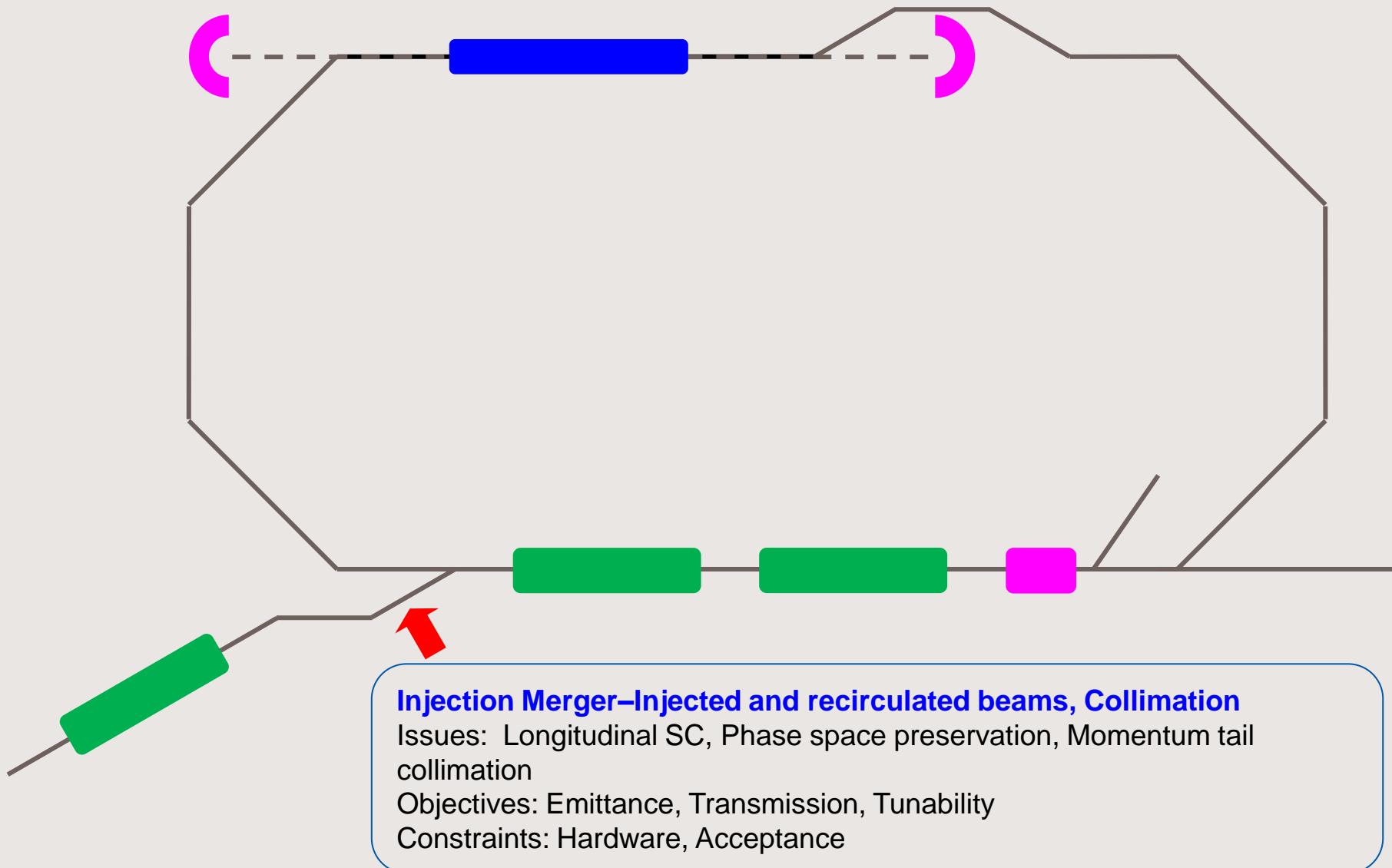


Motivation

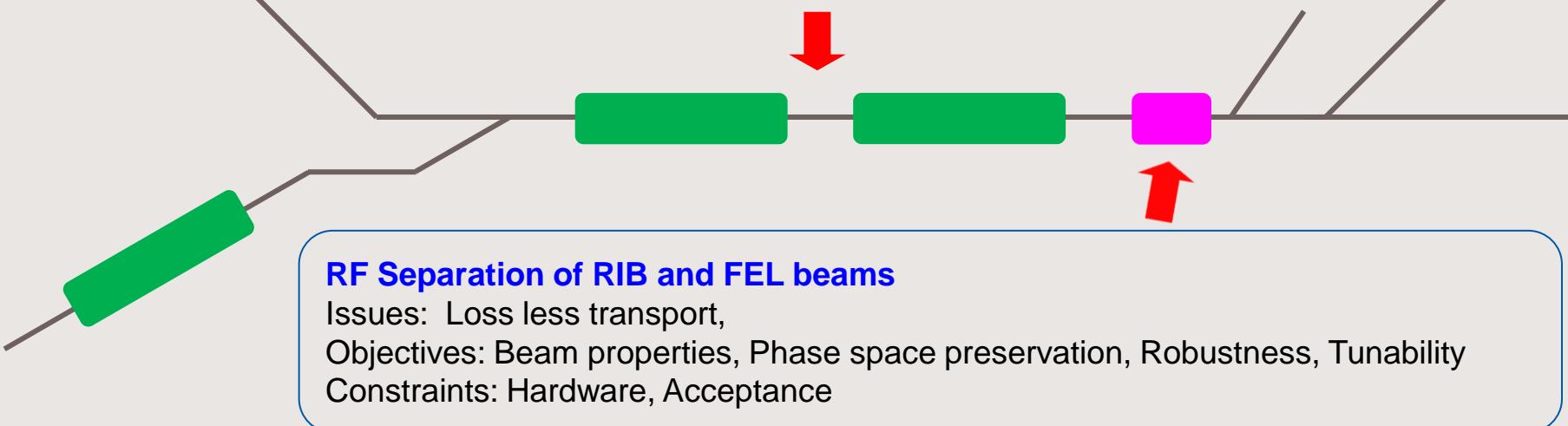
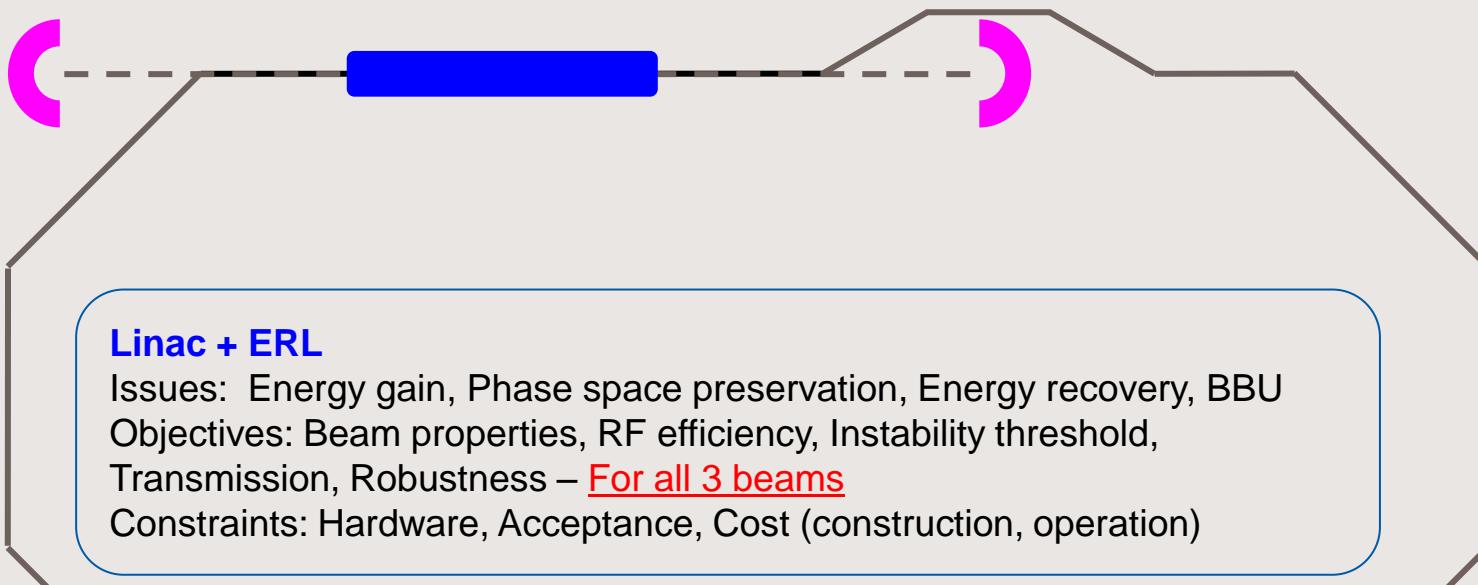
- Multi-engine simulations
 - Single beam in multiple distinct sections
 - Multiple beams through same section, different time-dependent effects
 - E-linac for FRIB/FEL
 - Expertise
- Single-engine MOGA is limited



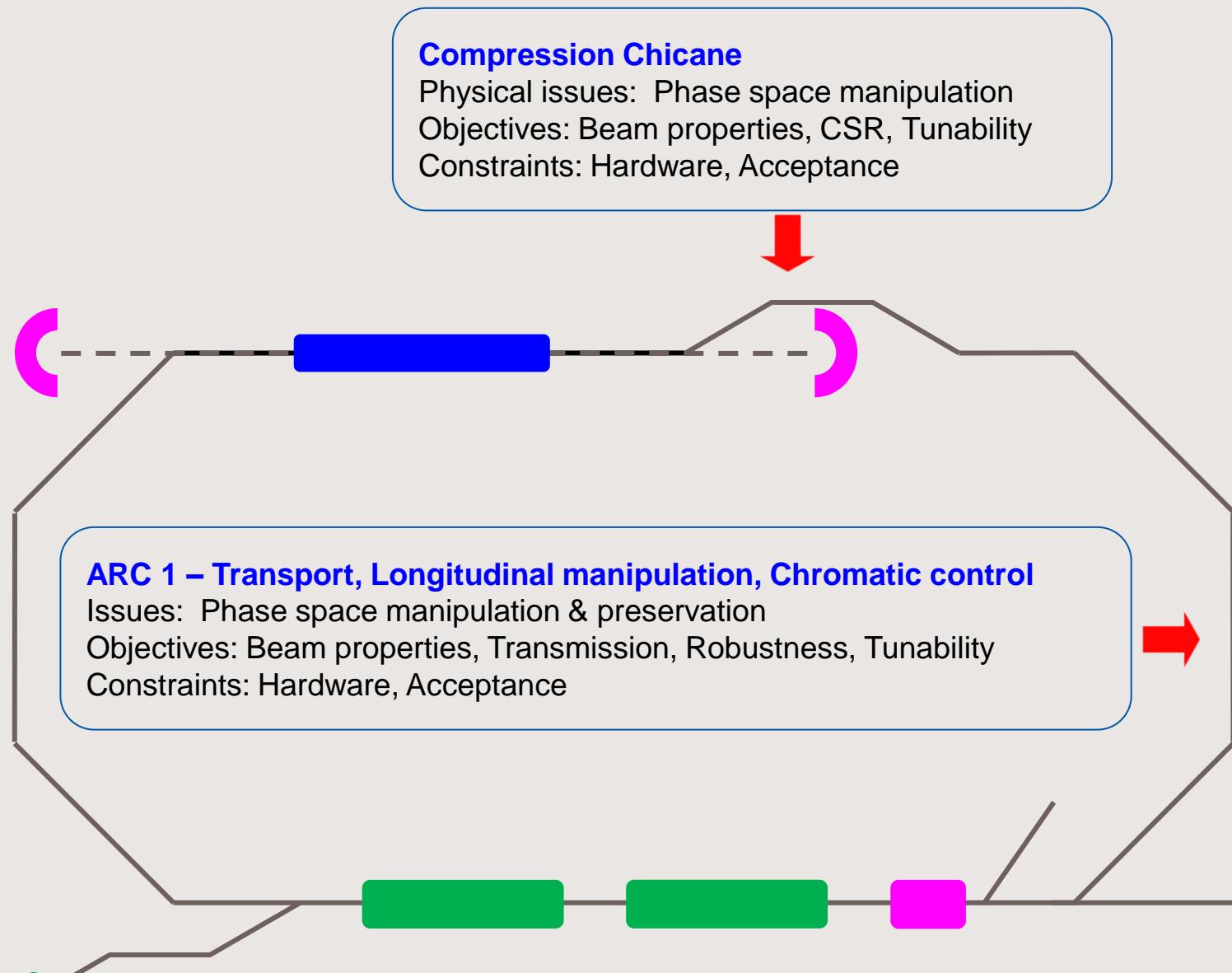
FRIB/FEL Issues



FRIB/FEL Issues



FRIB/FEL Issues



FRIB/FEL Issues

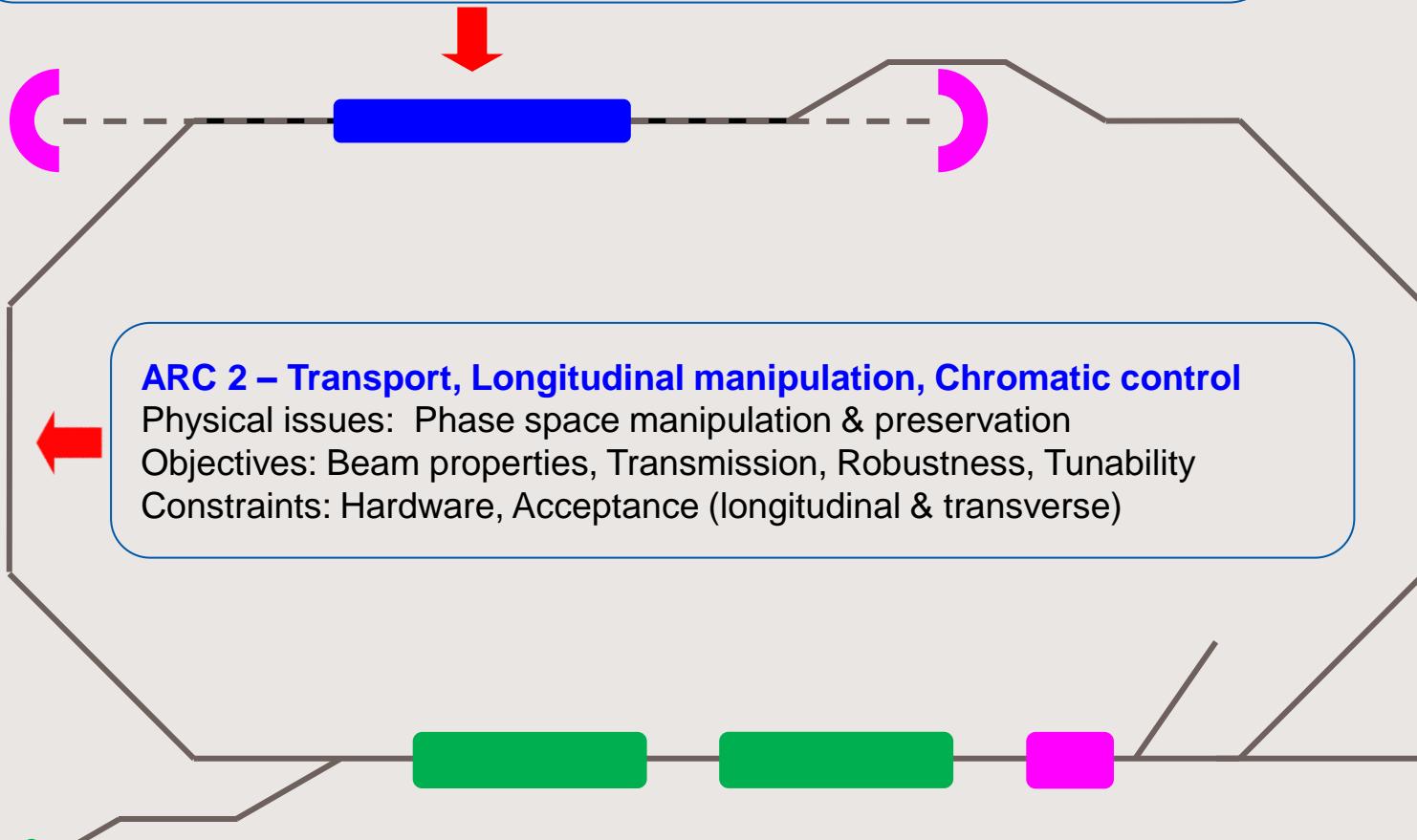
Wiggler

Physical issues: FEL- Beam interaction

Objectives: Beam properties, FEL efficiency and performance parameters,

Tunability

Constraints: Hardware, Acceptance (longitudinal & transverse)



ARC 2 – Transport, Longitudinal manipulation, Chromatic control

Physical issues: Phase space manipulation & preservation

Objectives: Beam properties, Transmission, Robustness, Tunability

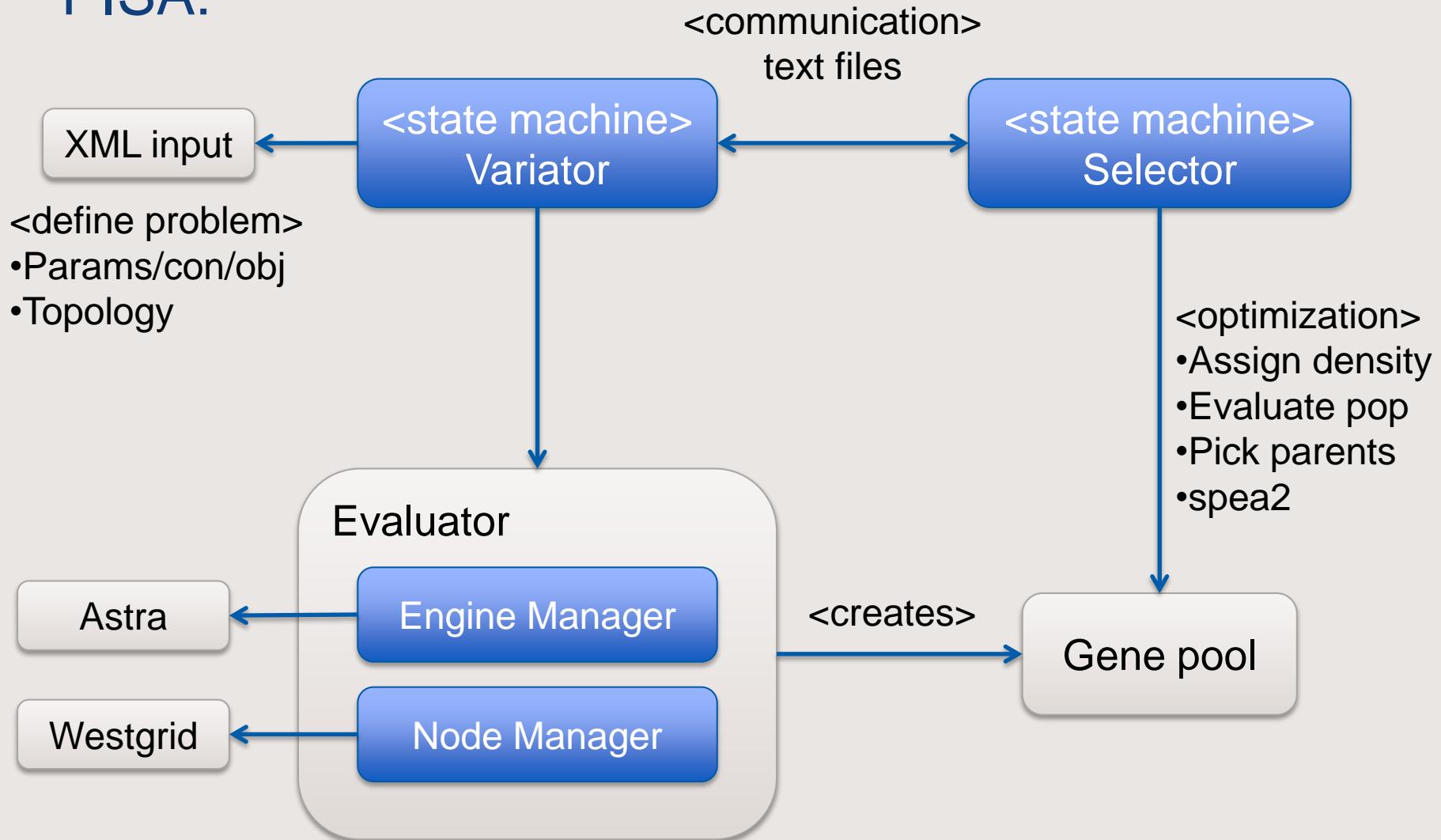
Constraints: Hardware, Acceptance (longitudinal & transverse)

Motivation

	Field map required	Space charge	Radiation field interaction	3D	Matrix/ tracking
Astra	1D	Yes		limited	
GPT	1D-3D	Yes		Yes	
MADX	No	Yes			Both
Elegant		No			Both
CSRTrack	Multipole	Yes	Yes		Tracking
Genesis			Yes		Tracking

- Software platform:
 - Multi-engine
 - Arbitrary problem topology
 - Engines can run sequential or parallel
 - Parallel-capable (qsub, qstat)
 - Flexible XML input format
 - Good error handling
 - C++/Linux, dash of python

PISA:



- Input XML:
 - Generic, suitable for all engines
 - Optimization parameters
 - Decision variables
 - Constraints
 - Objectives
 - Connecting variables
 - Topology (graph)
 - Engines execute in serial
 - Engines execute in parallel
 - Units
 - Designed to be intuitive, flexible

Format of Input Files

```
<ParamList>
    <Param name="B_S4"          min="0"           max="0.10"        unit="T"  />
    <Param name="s_S4"          min="4.2"         max="5.0"         unit="m"   />
    <Param name="K1_Q1"         min="0"           max="150"        unit="dimensionless" />
    <Param name="K1_Q2"         min="-150"        max="0"          unit="dimensionless" />
    <Param name="s_Q1"          min="5.65"        max="6.05"        unit="m"   />
    <Param name="ds_Q1Q2"       min="0.0"        max="0.5"         unit="m"  />
</ParamList>

<ConstraintList>
    <Constraint param="sigmax_2" direction="GT" bound="0.007" unit="m" />
    <Constraint param="sigmax_2" direction="LT" bound="0.015" unit="m" />
    <Constraint param="sigmay_2" direction="GT" bound="0.007" unit="m" />
    <Constraint param="sigmay_2" direction="LT" bound="0.015" unit="m" />
</ConstraintList>

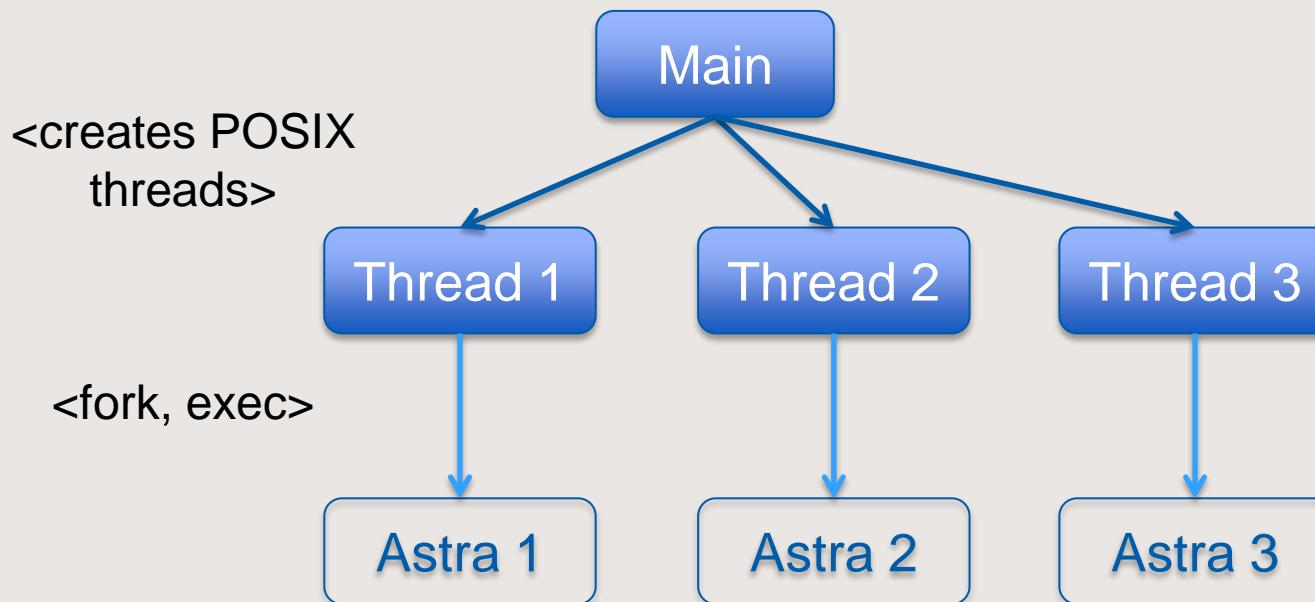
<ObjectiveList>
    <Objective direction="minimize" param="sigmax_n" />
    <Objective direction="minimize" param="sigmay_n" />
    <Objective direction="equals" value="0.01" param="sigmax_2" />
    <Objective direction="equals" value="0.01" param="sigmay_2" />
    <Objective direction="minimize" param="B_S4" />
    <Objective direction="minimize" param="K1_Q1" />
    <Objective direction="maximize" param="K1_Q2" comment="defocusing, so 0 is ma
</ObjectiveList>

<Topology>
    <Vertex name="a1" type="ASTRA" inputdir="2069X" prereqs="" timeout="600" />
    <Vertex name="mad" type="MADX" inputdir="mad" prereqs="a1" timeout="60" />
</Topology>
```

- Parameters/Constraints/Objectives:
 - Beam parameters at arbitrary locations
 - Derived parameters
 - Message parameters between engines
 - Need algebraic manipulation
- Custom python code:

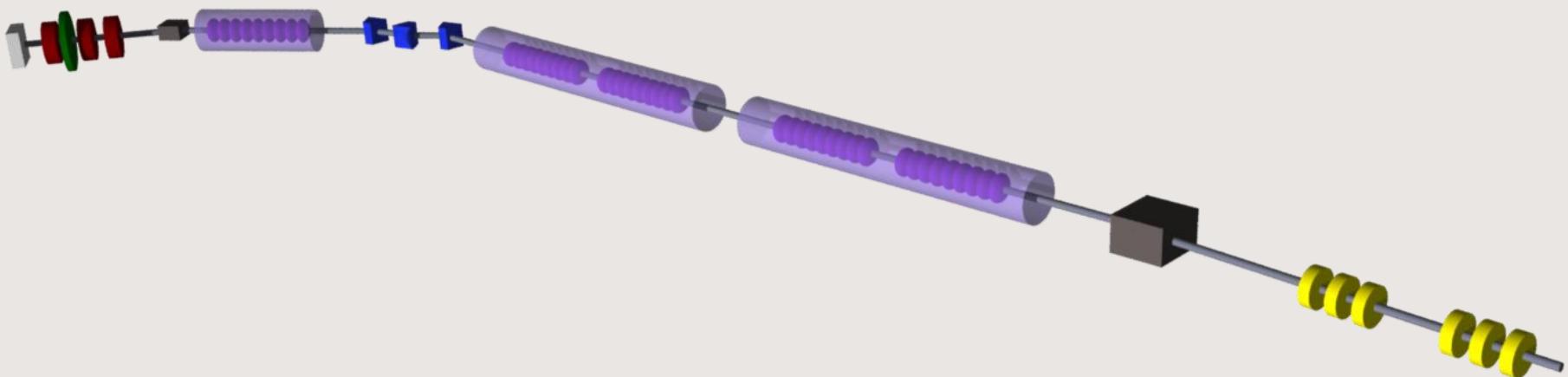
```
# neck, also transition between astra and mad
file1 = "%s/input.0559.001" % sys.path[0]
if os.path.isfile(file1):
    d1 = astra.ReadAstraFile(file1)
    common.SetValue("betx_n", astra.GetBetax(d1))
    common.SetValue("bety_n", astra.GetBetay(d1))
    common.SetValue("alfx_n", astra.GetAlphax(d1))
    common.SetValue("alfy_n", astra.GetAlphay(d1))
    common.SetValue("E_n", astra.GetE(d1))
    common.SetValue("emitx_n", astra.GetXemitrms(d1))
    common.SetValue("emity_n", astra.GetYemitrms(d1))
    common.SetValue("sigmax_n", astra.GetSigmaxrms(d1))
    common.SetValue("sigmay_n", astra.GetSigmayrms(d1))
```

- Exception handling:
 - Not all engines behave well
 - Kill if necessary (ssh does not work)
 - Thread problems, network problems: need to monitor



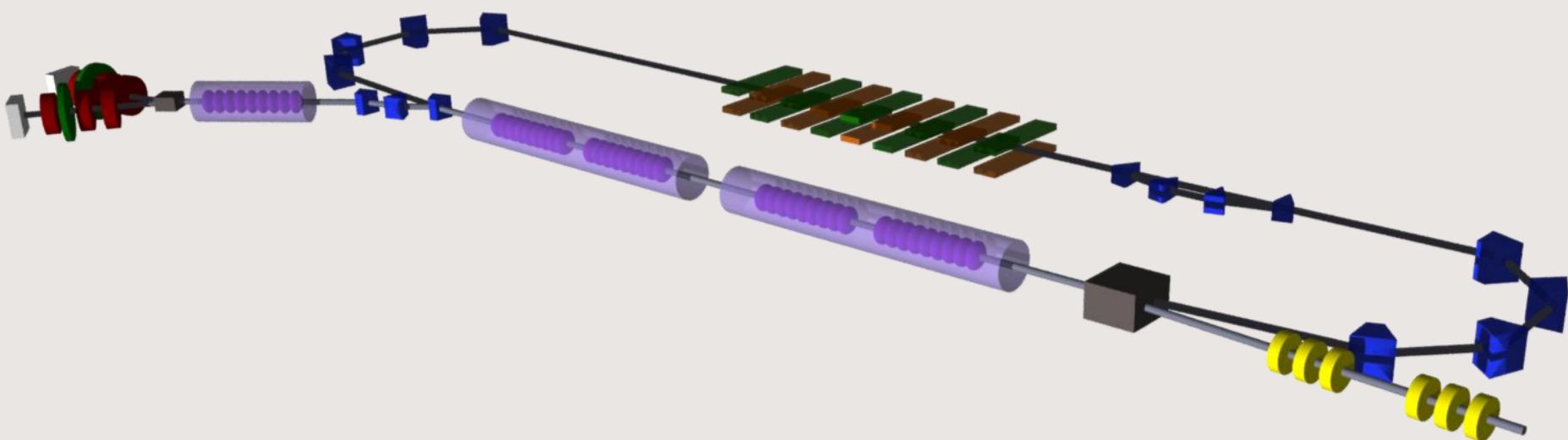
TRIUMF Ariel Overview

- 50 MeV, 0.5 MW, CW
- 5 SCRF cavities



TRIUMF Ariel Overview

- Upgradeable to ERL
- Simultaneous photo-fission / light source



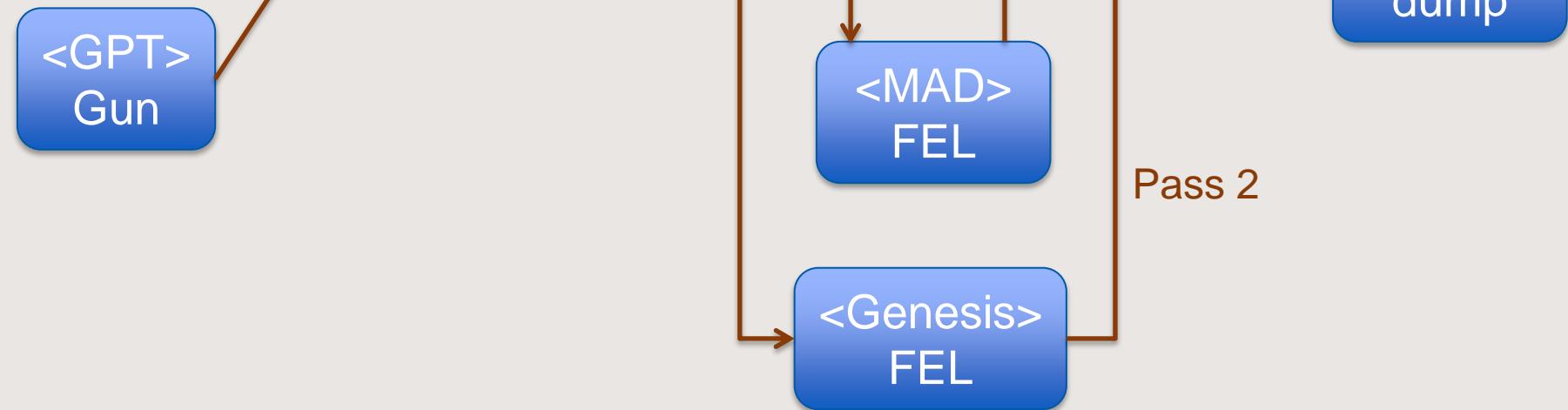
Goal: Start-to-End Optimization

In the future:

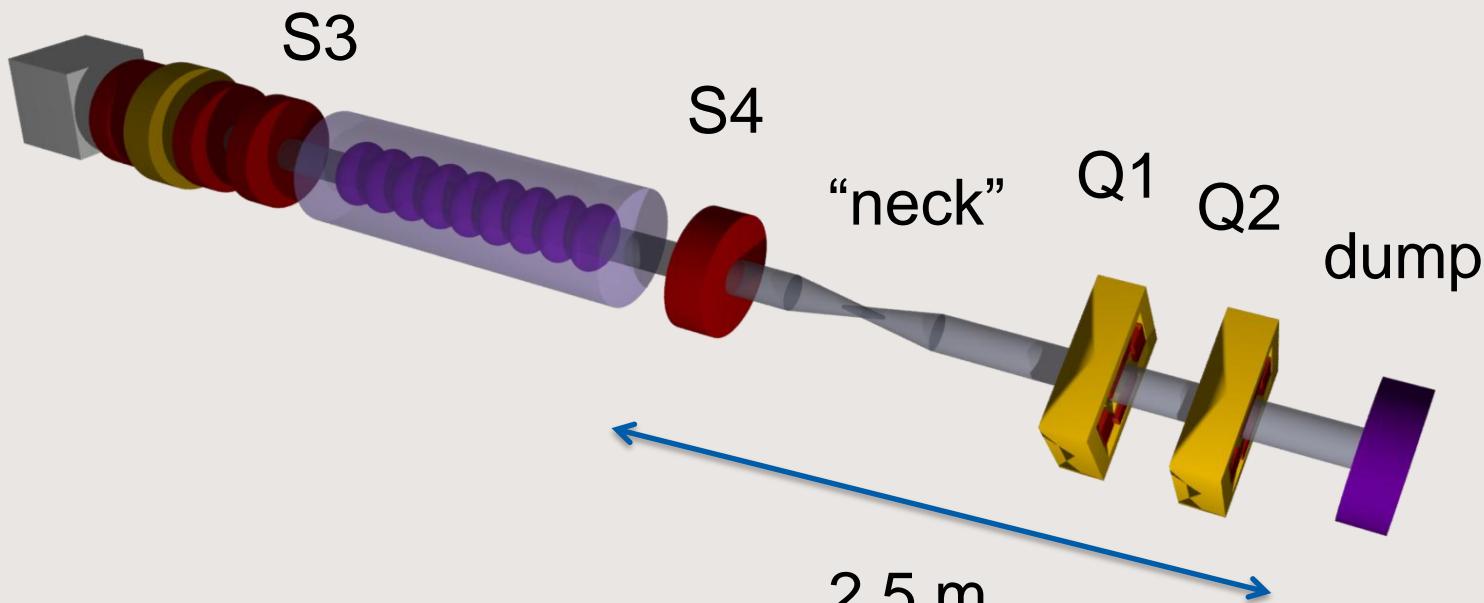
FRIB beam:



FEL beam:

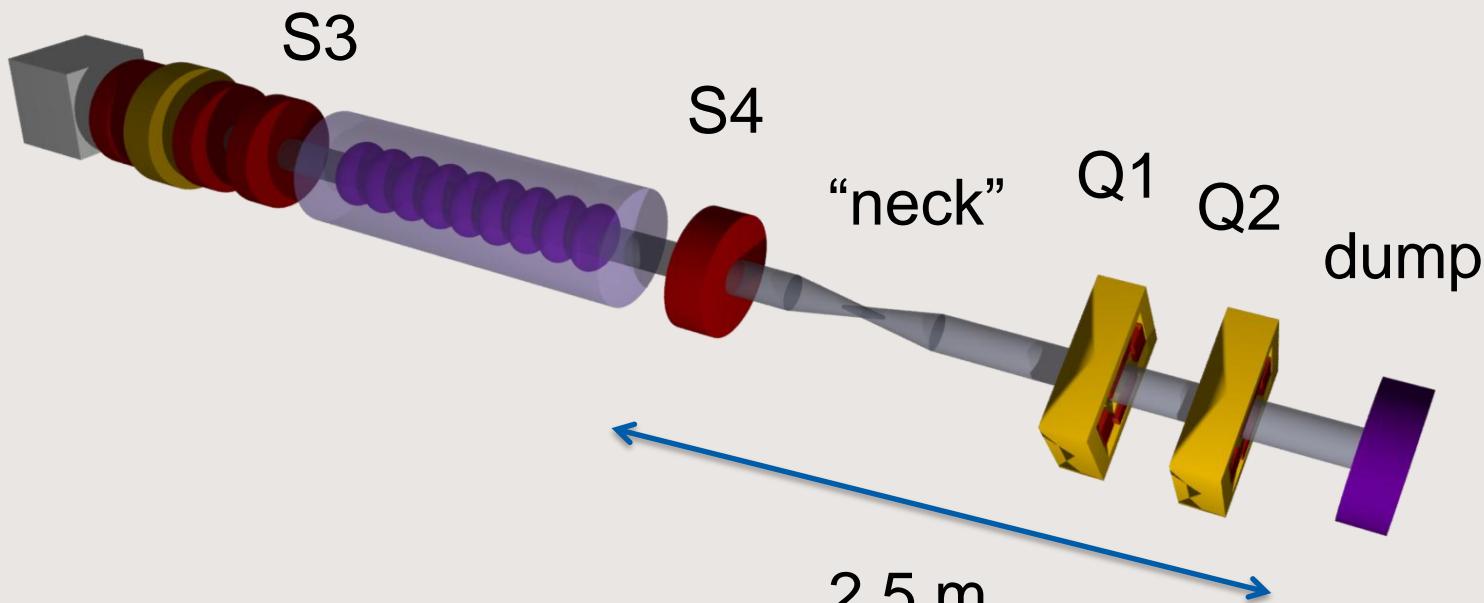


Injector Cryomodule to Dump



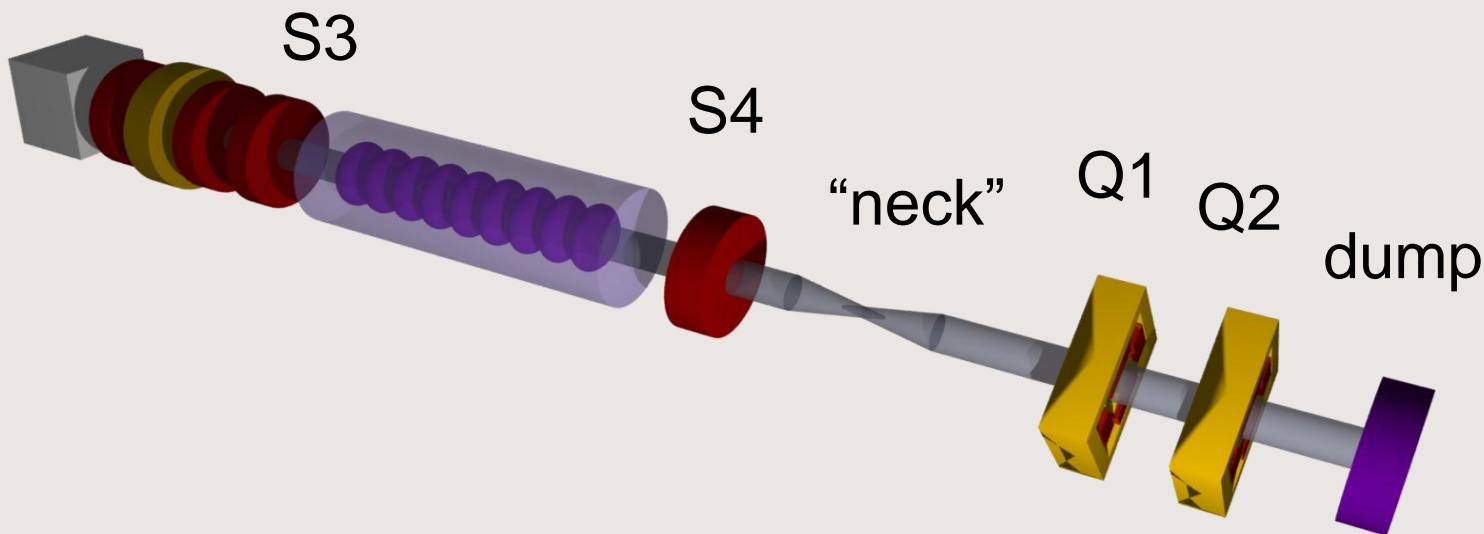
- **Injector transport:**
 - Scheduled for end of 2012
 - 300 keV beam from gun
 - Cryomodule -> 10 MeV
 - Terminate on dump

Injector Cryomodule to Dump



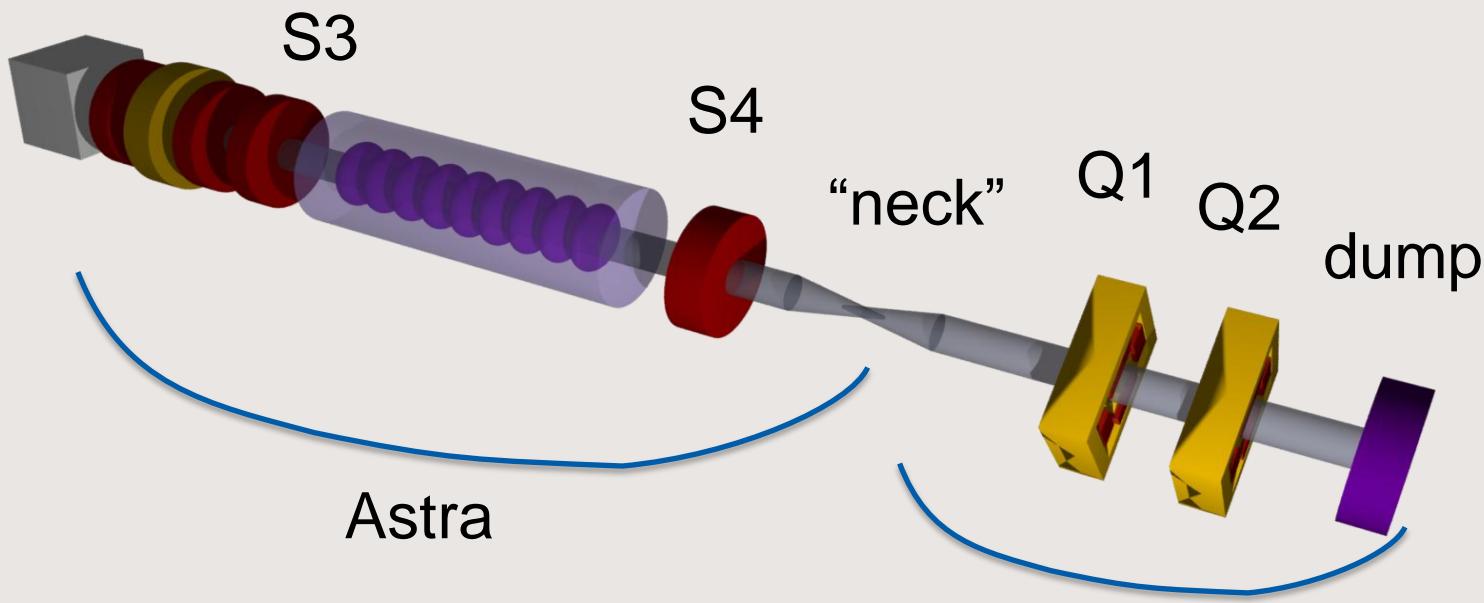
- **Objectives:**
 - Neck: squeeze beam
 - Dump: blow up beam (~1 cm)
 - Undemanding magnet settings
 - Length feasible?

Injector Cryomodule to Dump



- Parameters:
 - Solenoid 3 field
 - Solenoid 4 field, position
 - Quadrupole 1 field, position
 - Quadrupole 2 field, position

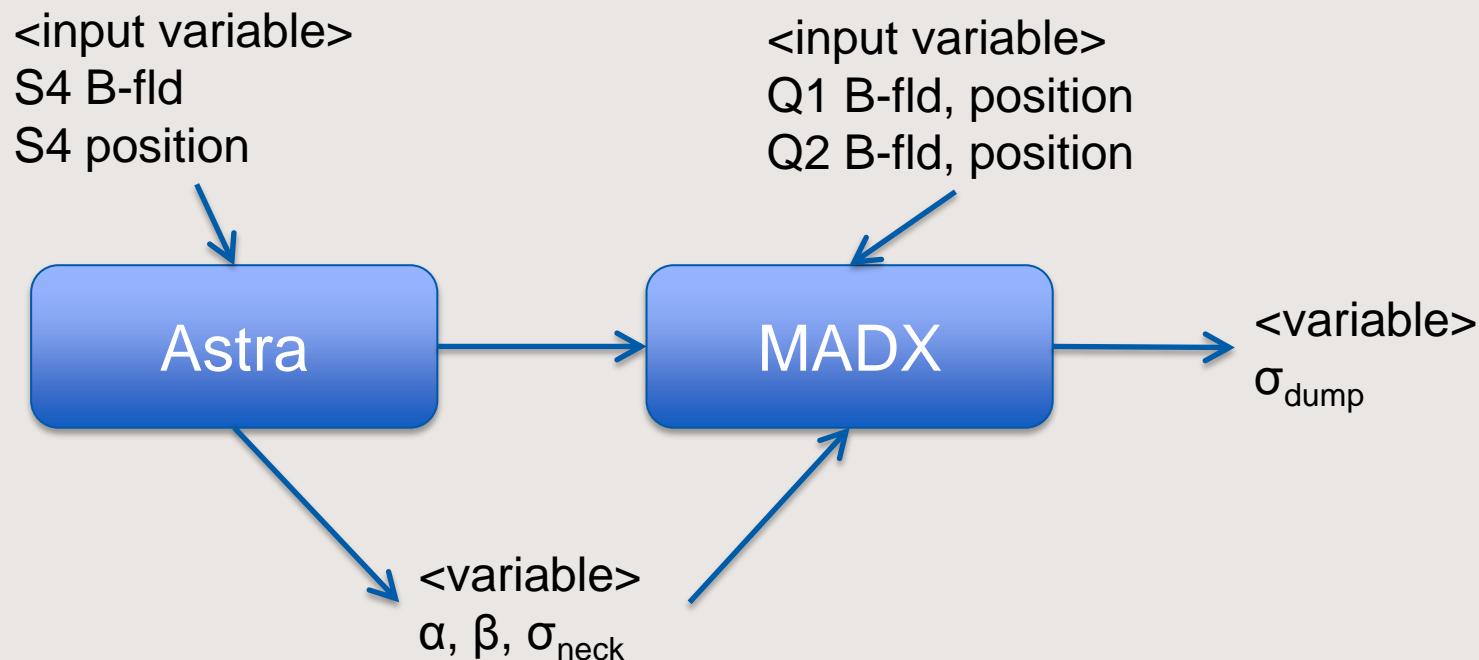
Injector Cryomodule to Dump



- Optimization setup:
 - Astra: gun-to-neck
 - MADX: neck-to-dump
 - Unit conversion, parameter passing taken care of

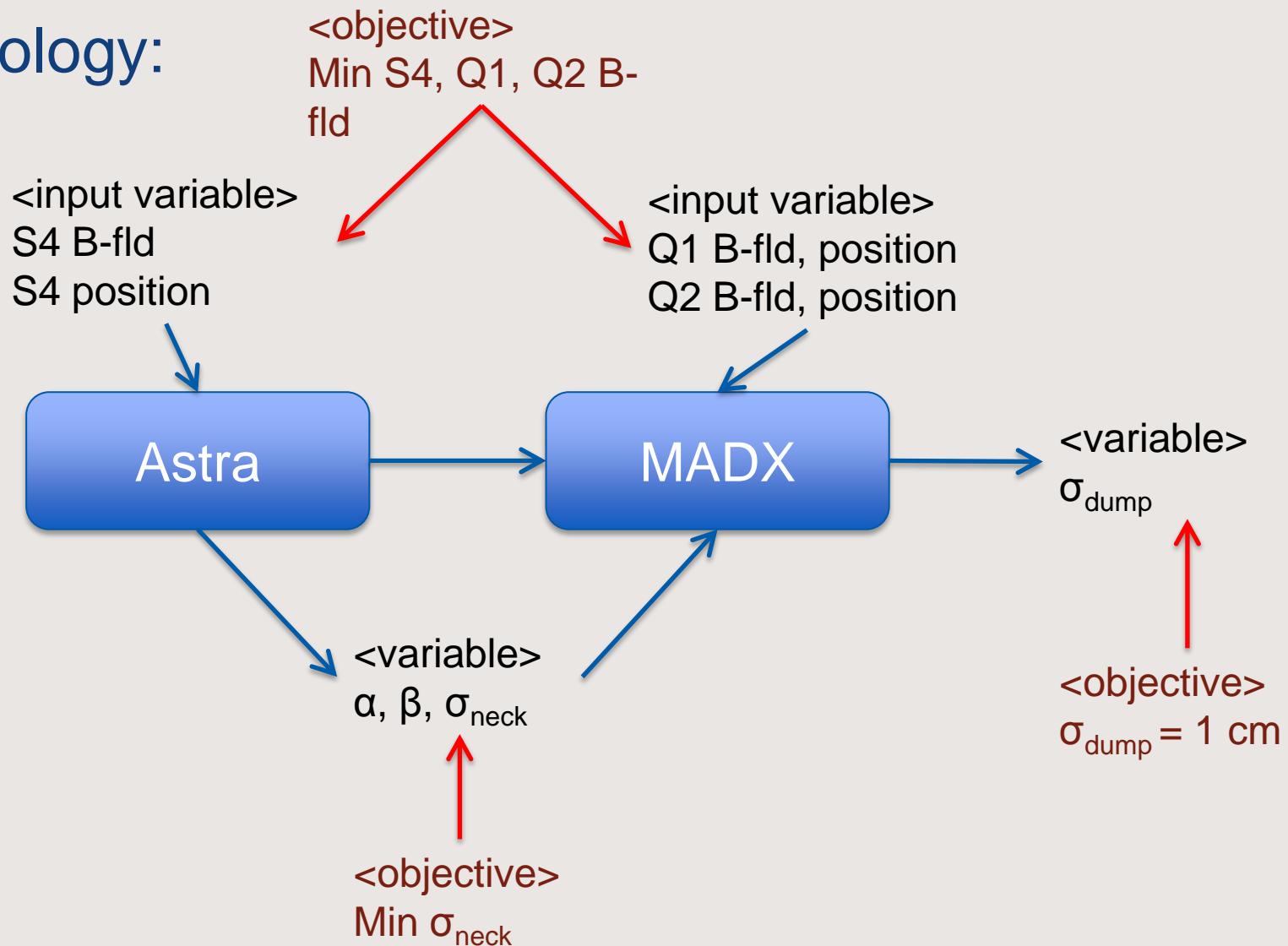
Injector Cryomodule to Dump

Topology:

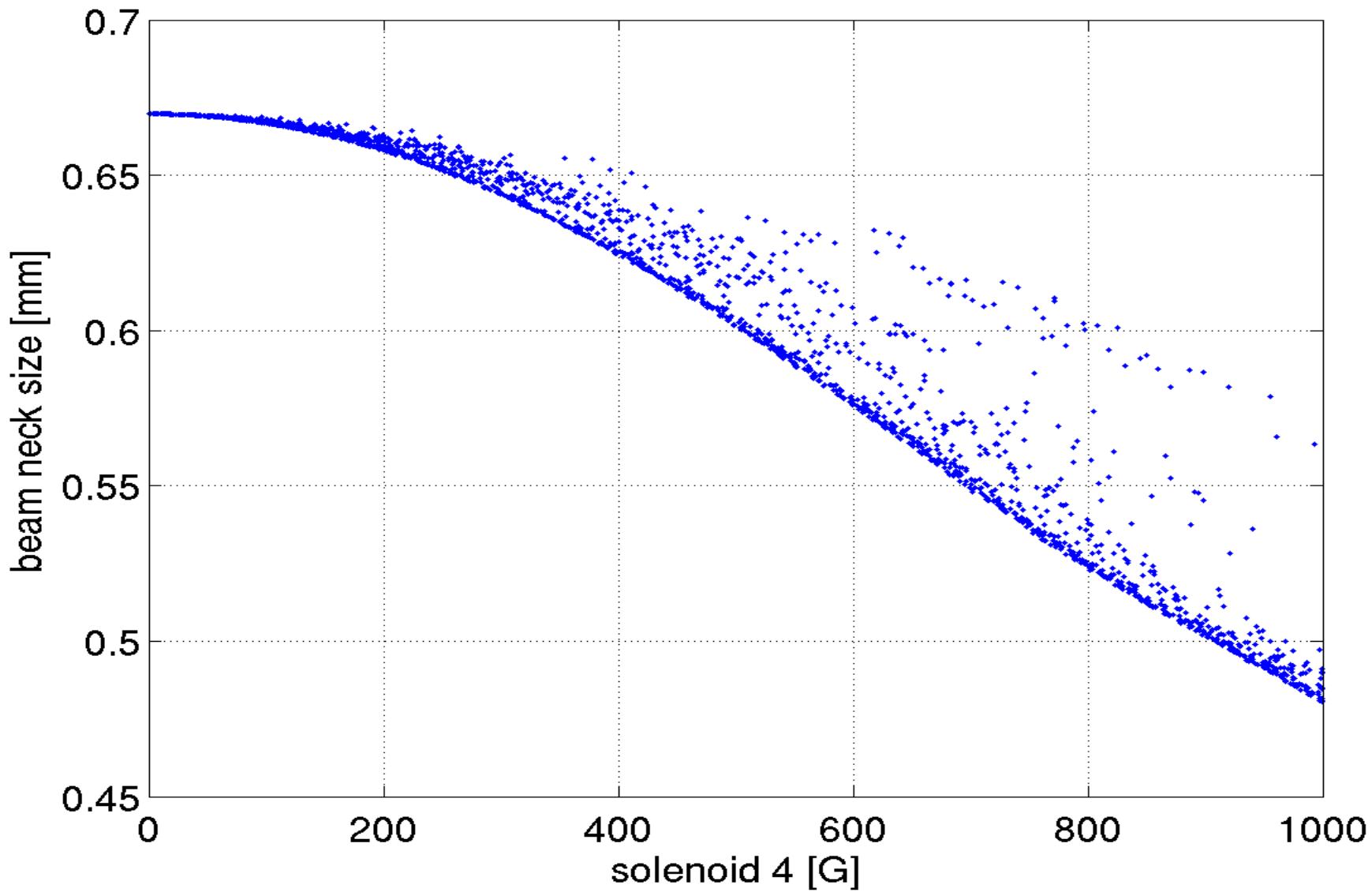


Injector Cryomodule to Dump

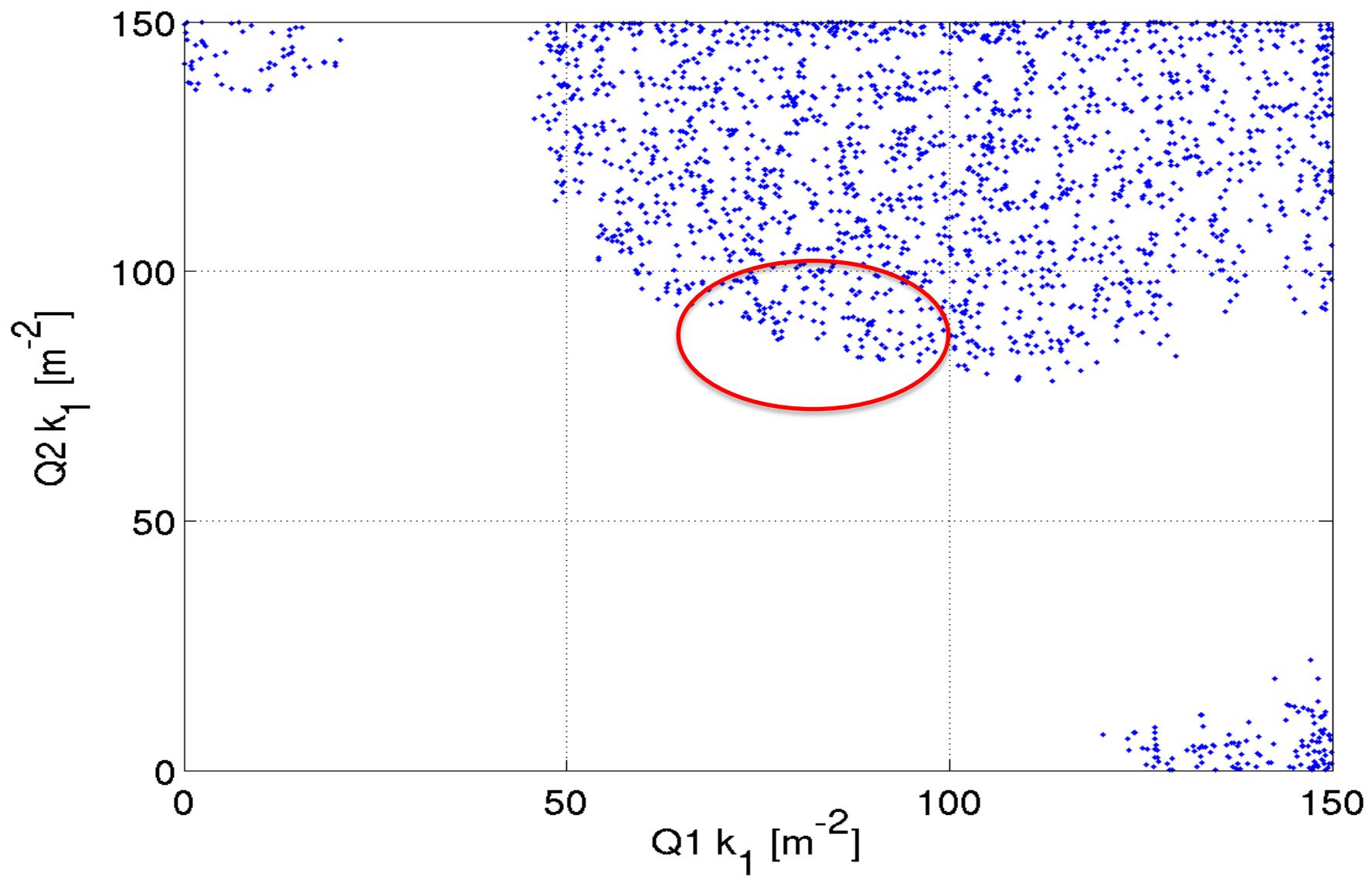
Topology:



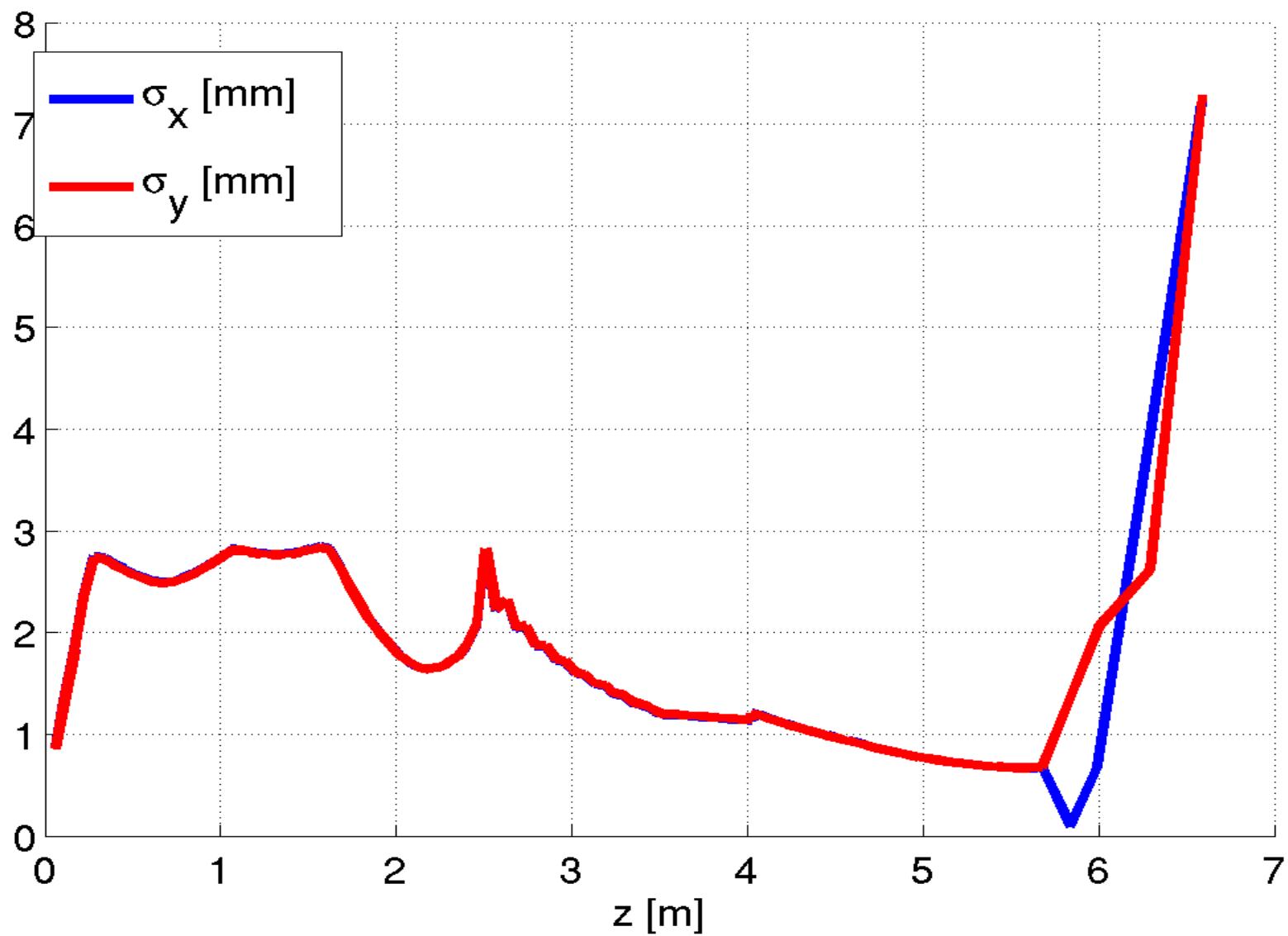
Results



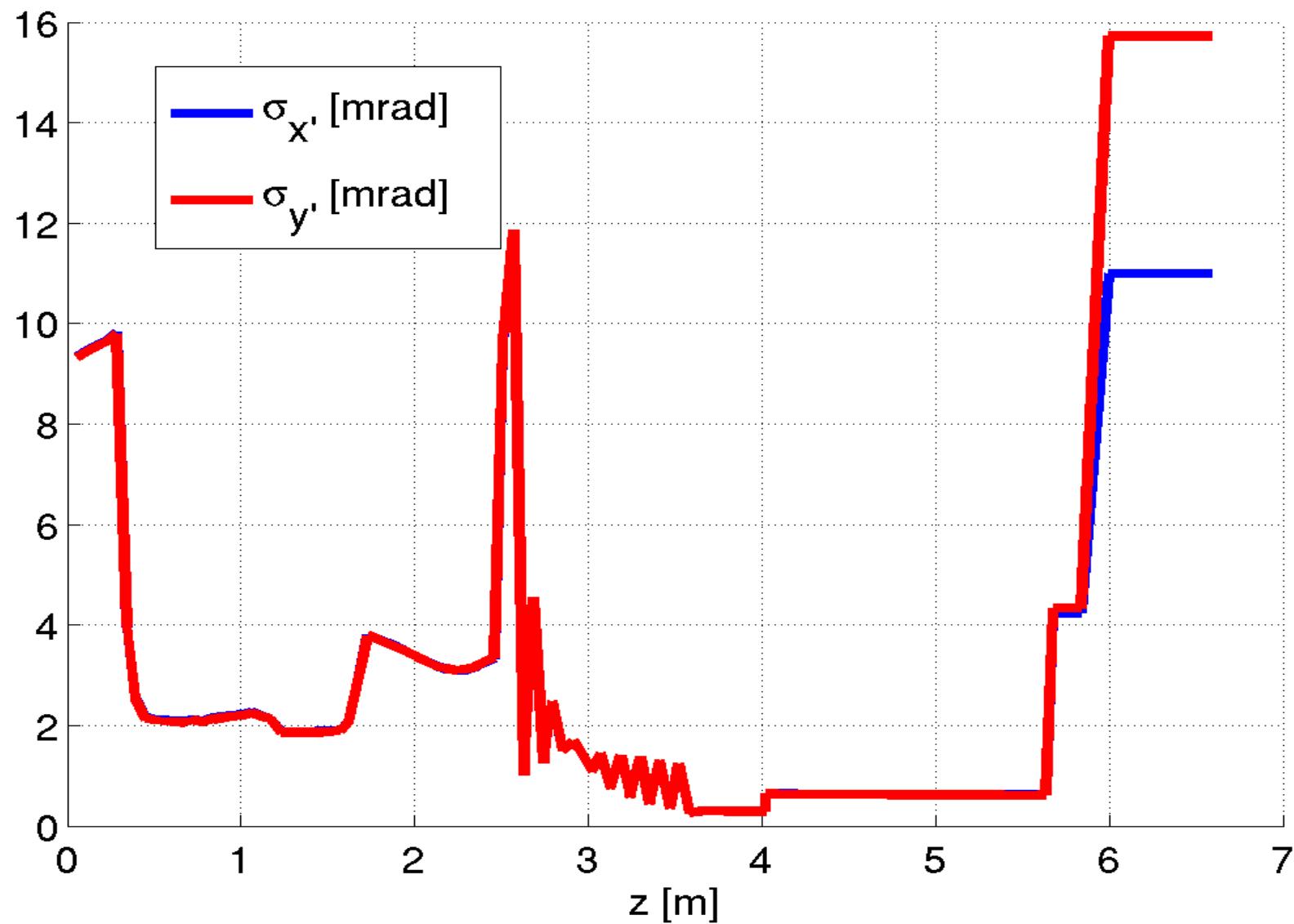
Results



Results



Results



Current Status

- Optimization platform tested, in-use
- Working on optimizing CSR in chicane
- Looking for more problems
- Improving features

References

- [1] PISA - www.tik.ee.ethz.ch/pisa/
- [2] I. Bazarov, APISA -
<http://www.lepp.cornell.edu/~ib38/apisa/>
- [3] G. Goh, YAPISA, TRIUMF
- [4] M. Borland, Elegant MOGA -
http://www.aps.anl.gov/Accelerator_Systems_Disvision/Accelerator_Operations_Physics/software.shtml
- [5] E-linac - <http://www.triumf.ca/ariel>