

# Eigenmode Computation For Ferrite-Loaded Cavity Resonators

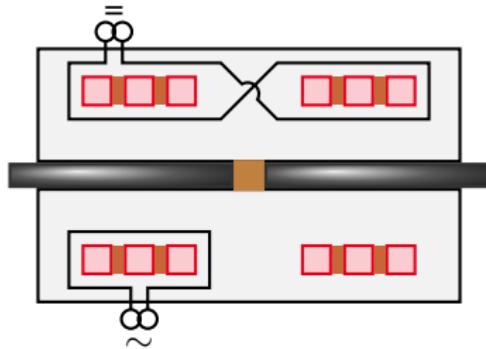
Klaus Klopfer\*, Wolfgang Ackermann, Thomas Weiland

*Institut für Theorie Elektromagnetischer Felder,*

*TU Darmstadt*



11<sup>th</sup> International Computational Accelerator Physics  
Conference (ICAP) 2012



THACC2

\*Supported by GSI, Darmstadt



# Contents

Motivation

Computational Model

- Fundamental Relations
- Implementation

Parallel Computing

Numerical Examples

- Biased Cylinder Resonator
- Biased Cavity With Ferrite Ring Cores

Summary

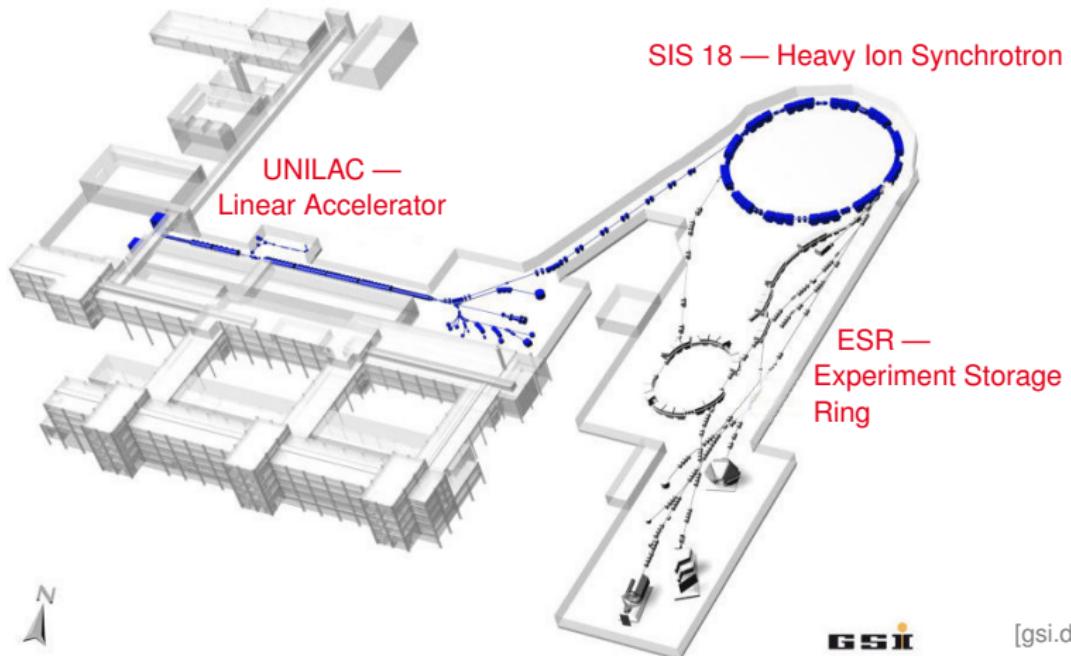


# Motivation

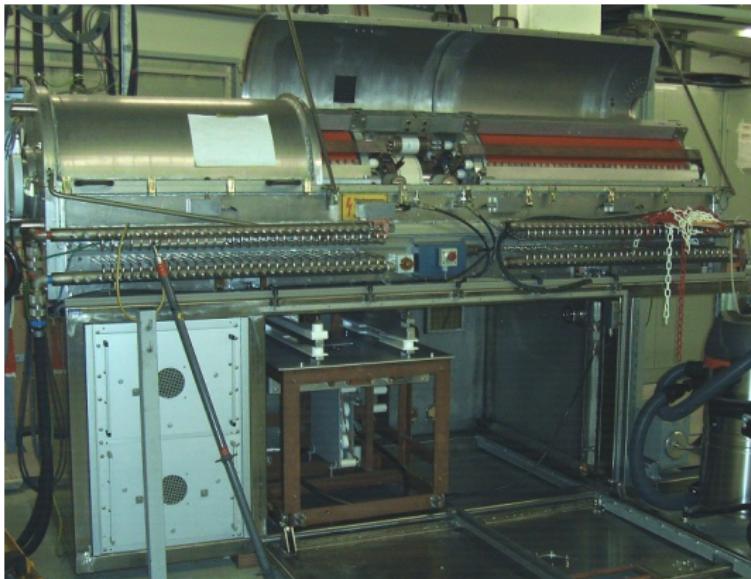


TECHNISCHE  
UNIVERSITÄT  
DARMSTADT

## GSI Helmholtzzentrum für Schwerionenforschung



## GSI SIS18 Ferrite Cavity



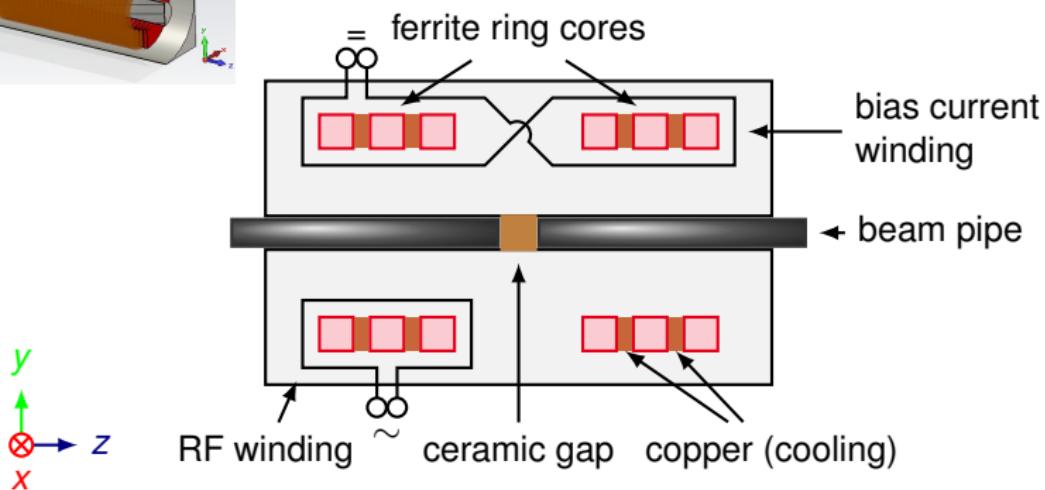
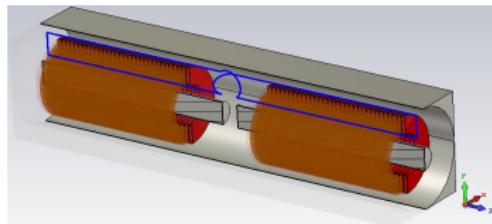
### Main benefits of ferrite cavities:

- ▶ reduction of wavelength  
⇒ more compact cavity
- ▶ modification of resonance frequency in a wide range  
SIS 18 cavity:  
 $\sim 0.6 \text{ MHz} - 5 \text{ MHz}$

# Motivation



## GSI SIS18 Ferrite Cavity: Main components

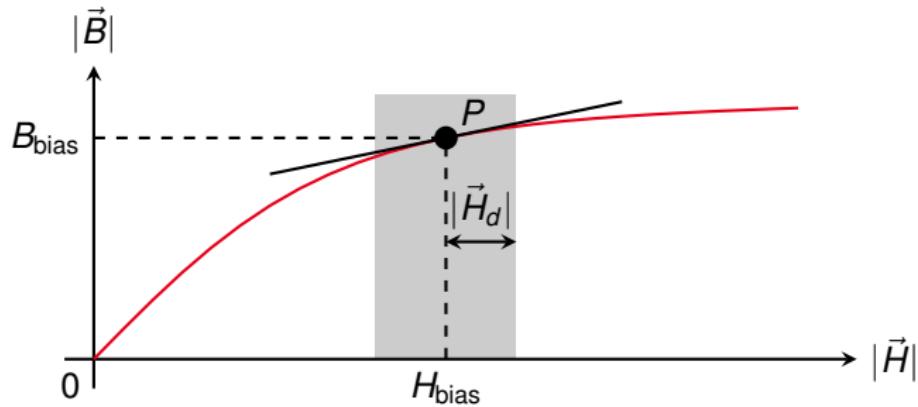


# Computational Model: Fundamental Relations

Assumptions:  $|\vec{H}_d| \ll |\vec{H}_{\text{bias}}|$ , effect of hysteresis negligible

$$\vec{B}(t) = \mu_0 \mu_{\text{bias}} \vec{H}_{\text{bias}} + \mu_0 \overset{\leftrightarrow}{\mu}_d \vec{H}_d(t) = \mu_0 \mu_{\text{bias}} \vec{H}_{\text{bias}} + \mu_0 \overset{\leftrightarrow}{\mu}_d \operatorname{Re} \left( \vec{H}_d \cdot e^{-i\omega t} \right)$$

- ▶ Linearization at working point

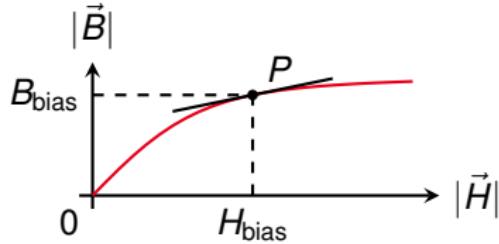


# Computational Model: Fundamental Relations

Assumptions:  $|\vec{H}_d| \ll |\vec{H}_{\text{bias}}|$ , effect of hysteresis negligible

$$\vec{B}(t) = \mu_0 \mu_{\text{bias}} \vec{H}_{\text{bias}} + \mu_0 \overset{\leftrightarrow}{\mu}_d \vec{H}_d(t) = \mu_0 \mu_{\text{bias}} \vec{H}_{\text{bias}} + \mu_0 \overset{\leftrightarrow}{\mu}_d \operatorname{Re} \left( \vec{H}_d \cdot e^{-i\omega t} \right)$$

- ▶ Linearization at working point



- ▶ **Modification of bias current**
  - ⇒ Modification of differential permeability
  - ⇒ Adjustment of eigenfrequency

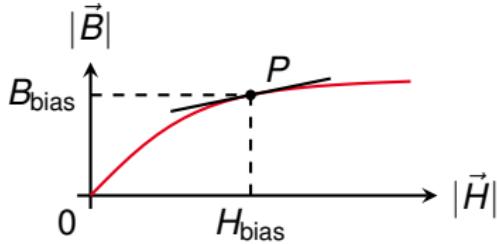


# Computational Model: Fundamental Relations

Assumptions:  $|\vec{H}_d| \ll |\vec{H}_{\text{bias}}|$ , effect of hysteresis negligible

$$\vec{B}(t) = \mu_0 \mu_{\text{bias}} \vec{H}_{\text{bias}} + \mu_0 \overset{\leftrightarrow}{\mu}_d \vec{H}_d(t) = \mu_0 \mu_{\text{bias}} \vec{H}_{\text{bias}} + \mu_0 \overset{\leftrightarrow}{\mu}_d \operatorname{Re} \left( \vec{H}_d \cdot e^{-i\omega t} \right)$$

- Linearization at working point



- Eigensolutions determined by:

$$\epsilon^{-1} \nabla \times \left( \mu_0^{-1} \overset{\leftrightarrow}{\mu}_d^{-1} \nabla \times \vec{E} \right) = \omega^2 \vec{E}$$

Boundary condition:  $\vec{n} \times \vec{E} = 0$  on cavity boundary

# Computational Model: Fundamental Relations

[D. Polder, Phil. Mag., 40 (1949)]

## Properties of the differential permeability tensor $\overset{\leftrightarrow}{\mu}_d$ :

- ▶ Fully occupied (3×3)-tensor, for  $\vec{H} = H_{\text{bias}} \cdot \vec{e}_z$  reduces to the Polder tensor

$$\overset{\leftrightarrow}{\mu}_d = \begin{pmatrix} \mu_1 & i\mu_2 & 0 \\ -i\mu_2 & \mu_1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \text{with} \quad \mu_{1,2} = \mu_{1,2}(\vec{H}_{\text{bias}}, \omega)$$

- ▶ If magnetic losses are included:  
 $\text{Im}(\mu_{1,2}) \neq 0 \Rightarrow$  Non-Hermitian

# Computational Model: Implementation



TECHNISCHE  
UNIVERSITÄT  
DARMSTADT

$$\epsilon^{-1} \nabla \times \left( \mu_0^{-1} \mu_d^{-1} \nabla \times \vec{E} \right) = \omega^2 \vec{E}$$



# Computational Model: Implementation

$$\epsilon^{-1} \nabla \times \left( \mu_0^{-1} \mu_d^{-1} \nabla \times \vec{E} \right) = \omega^2 \vec{E}$$

Discretization by Finite Integration Technique (FIT):

$$M_\epsilon^{-1} \tilde{\mathbf{C}} M_{d,\mu}^{-1} \mathbf{C} \hat{\mathbf{e}} = \omega^2 \hat{\mathbf{e}}$$



# Computational Model: Implementation

$$\epsilon^{-1} \nabla \times \left( \mu_0^{-1} \mu_d^{-1} \nabla \times \vec{E} \right) = \omega^2 \vec{E}$$

Discretization by Finite Integration Technique (FIT):

$$M_\epsilon^{-1} \tilde{\mathbf{C}} M_{d,\mu}^{-1} \mathbf{C} \hat{\mathbf{e}} = \omega^2 \hat{\mathbf{e}}$$

- ▶ permeability tensor  $M_{d,\mu}$ :
  - ▶ non-diagonal
  - ▶ dependend on  $\vec{H}_{\text{bias}}$  and  $\omega$

# Computational Model: Implementation



$$\epsilon^{-1} \nabla \times \left( \mu_0^{-1} \mu_d^{-1} \nabla \times \vec{E} \right) = \omega^2 \vec{E}$$

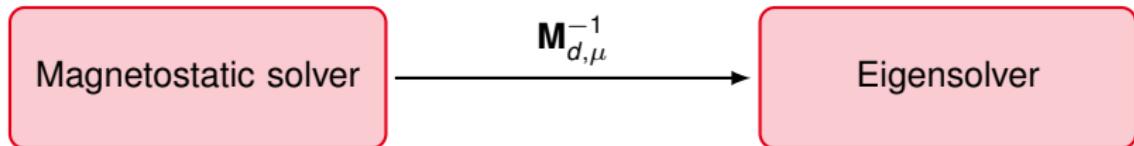
Discretization by Finite Integration Technique (FIT):

$$M_\epsilon^{-1} \tilde{\mathbf{C}} M_{d,\mu}^{-1} \mathbf{C} \hat{\mathbf{e}} = \omega^2 \hat{\mathbf{e}}$$

- ▶ permeability tensor  $M_{d,\mu}$ :
  - ▶ non-diagonal
  - ▶ dependend on  $\vec{H}_{\text{bias}}$  and  $\omega$
  - ▶ if magnetic losses included:
- ▶ requirements on eigensolver:
  - ⇒ nonlinear
  - ⇒ non-Hermitian

# Computational Model: Implementation

## Concept

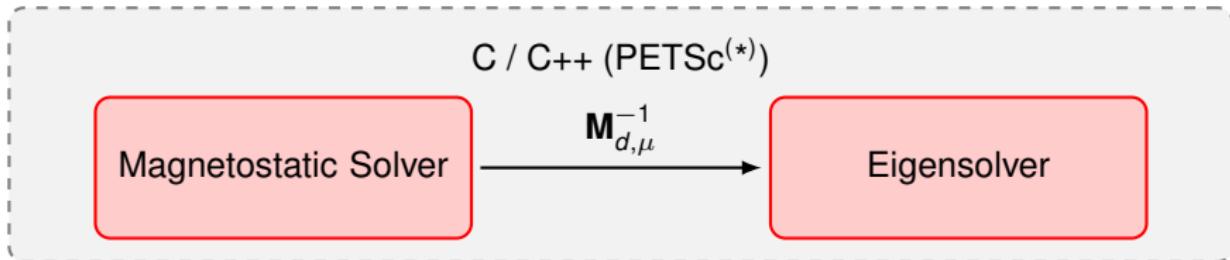


- ▶ calculation of bias magnetic field
- ▶ determination of permeability matrix  $\mathbf{M}_{d,\mu}^{-1}$
- ▶ calculation of eigenmodes

General requirements:

- ▶ support of nonlinear material
- ▶ support of lossy material
- ▶ parallel computation with distributed memory (scalability)

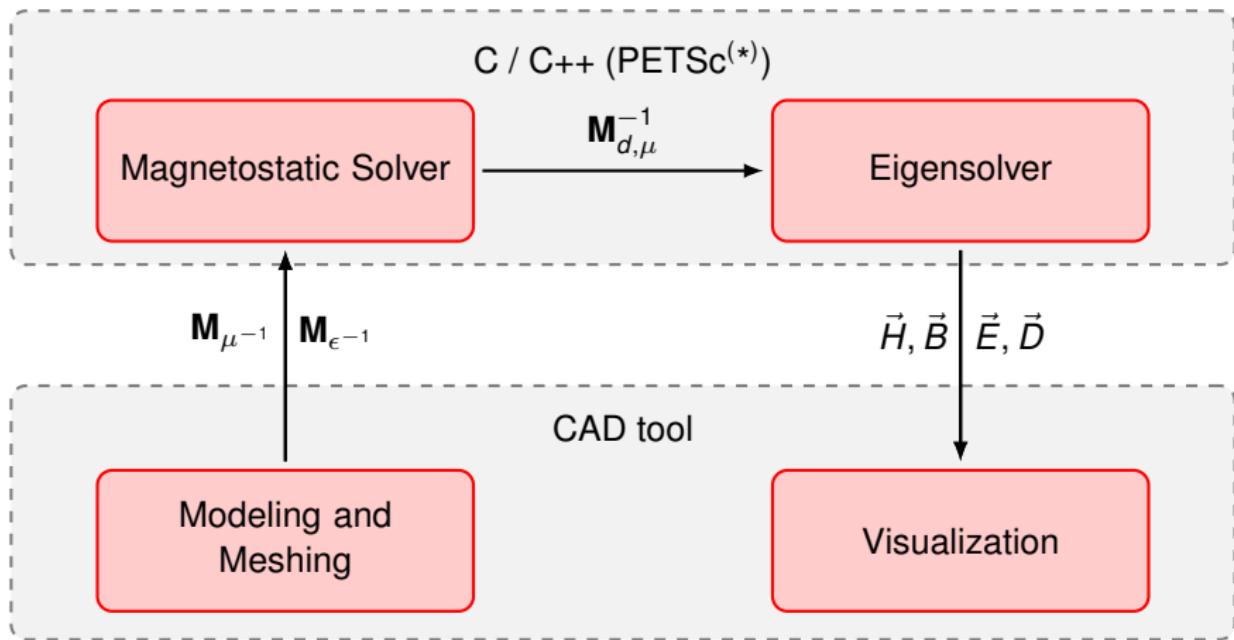
# Computational Model: Implementation



(\*) Portable, Extensible Toolkit for Scientific Computation

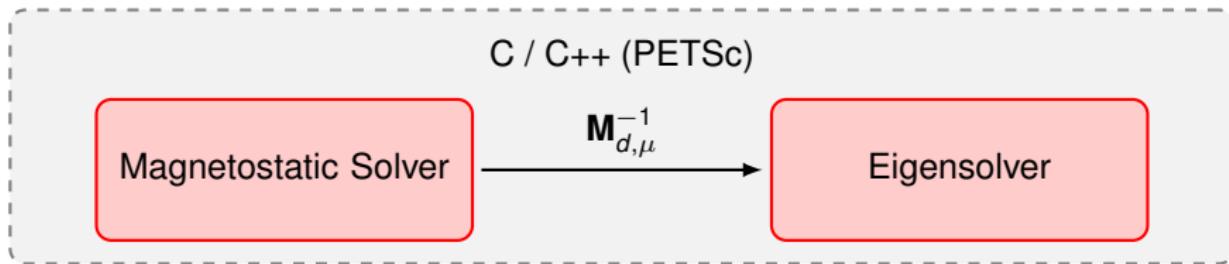


# Computational Model: Implementation



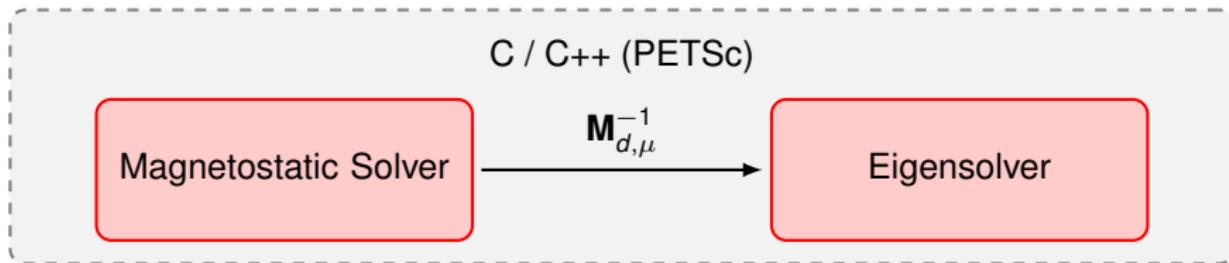
(\*) Portable, Extensible Toolkit for Scientific Computation

# Computational Model: Implementation



- ▶  **$H_i$ -algorithm**  
Helmholtz decomposition  
 $\vec{H} = \vec{H}_i + \vec{H}_h$  with  
 $\nabla \times \vec{H}_i = \vec{J}$  and  $\vec{H}_h = -\nabla \varphi$
- ▶ Solution of nonlinear equation:  
successive substitution or  
Newton method

# Computational Model: Implementation



- ▶  **$H_i$ -algorithm**  
Helmholtz decomposition  
 $\vec{H} = \vec{H}_i + \vec{H}_h$  with  
 $\nabla \times \vec{H}_i = \vec{J}$  and  $\vec{H}_h = -\nabla \varphi$
- ▶ Solution of nonlinear equation:  
successive substitution or  
Newton method
- ▶ **Jacobi-Davidson algorithm**  
harmonic Ritz-values for  
computation of interior  
eigenvalues
- ▶ Solution of nonlinear problem:  
successive substitution

# Contents

Motivation

Computational Model

Fundamental Relations

Implementation

Parallel Computing

Numerical Examples

Biased Cylinder Resonator

Biased Cavity With Ferrite Ring Cores

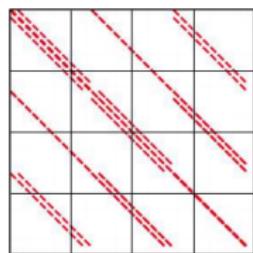
Summary



## Aim: Efficient distributed computing

Structure of system matrix

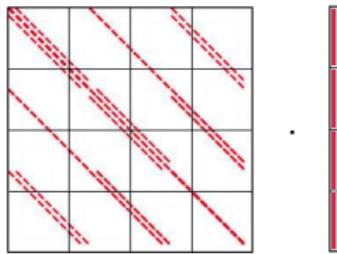
standard  
arrangement



## Aim: Efficient distributed computing

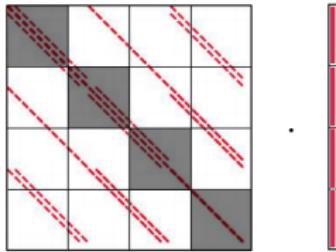
Structure of system matrix

standard arrangement



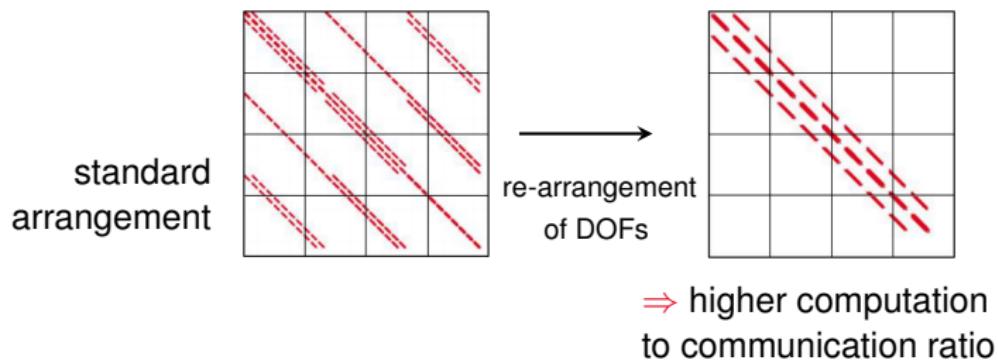
**Aim: Efficient distributed computing**

Structure of system matrix



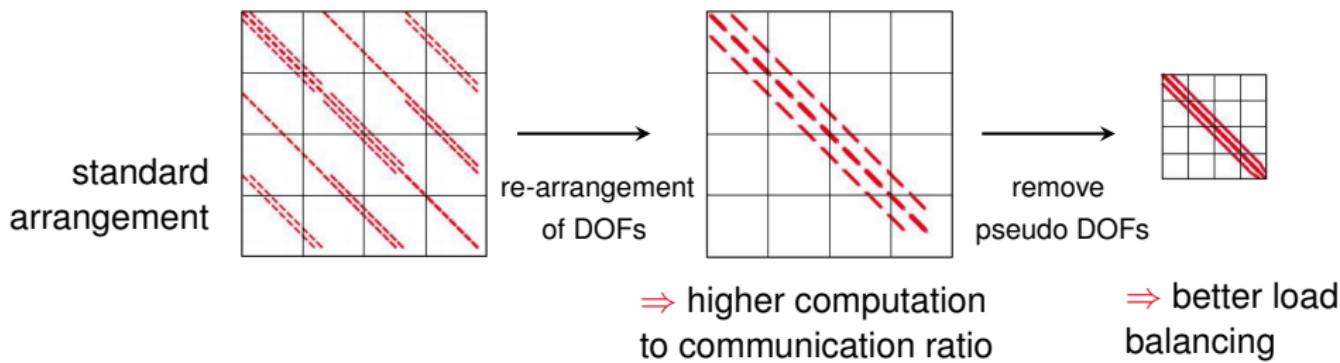
## Aim: Efficient distributed computing

Structure of system matrix



## Aim: Efficient distributed computing

Structure of system matrix



# Contents



Motivation

Computational Model

Fundamental Relations

Implementation

Parallel Computing

Numerical Examples

Biased Cylinder Resonator

Biased Cavity With Ferrite Ring Cores

Summary

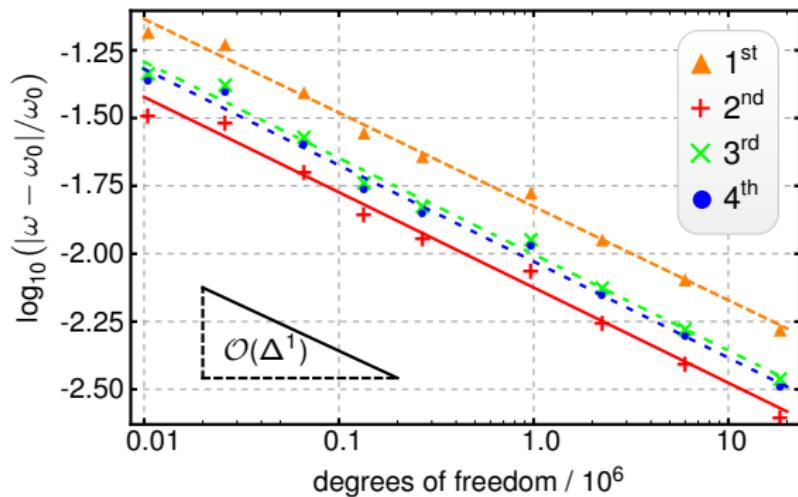
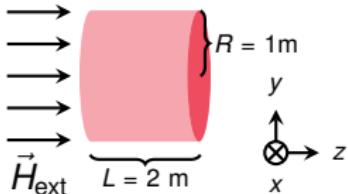
# Numerical Examples

## Biased Cylinder Resonator



- ▶ test model:  
lossless, ferrite-filled cylindrical cavity resonator  
longitudinally biased by homogeneous magnetic field
- ▶ semi-analytical solution available [Chinn, Epp and Wilkins]

$$(|\vec{H}_{\text{ext}}| = 2750 \frac{\text{A}}{\text{m}}; \mu_r = 7)$$

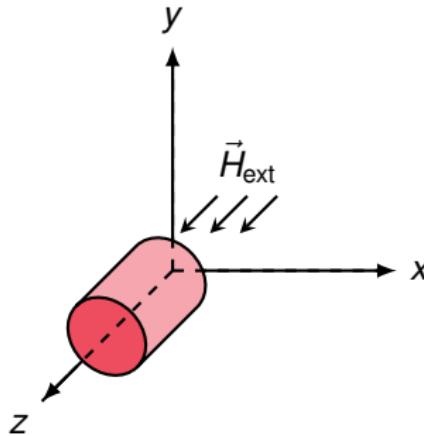


# Numerical Examples

## Biased Cylinder Resonator

### ► test model:

lossless, ferrite-filled cylindrical cavity resonator  
longitudinally biased by homogeneous magnetic field



$$\vec{H}_{\text{ext}} \parallel \vec{e}_z:$$

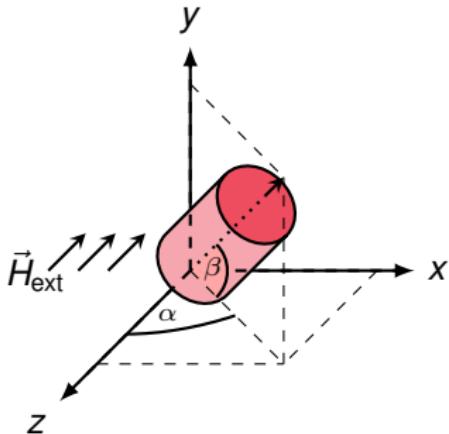
$$\overset{\leftrightarrow}{\mu}_d = \begin{pmatrix} \mu_1 & i\mu_2 & 0 \\ -i\mu_2 & \mu_1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

# Numerical Examples

## Biased Cylinder Resonator

### ► test model:

lossless, ferrite-filled cylindrical cavity resonator  
longitudinally biased by homogeneous magnetic field



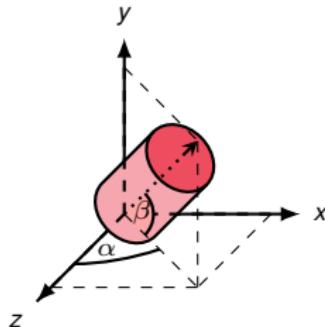
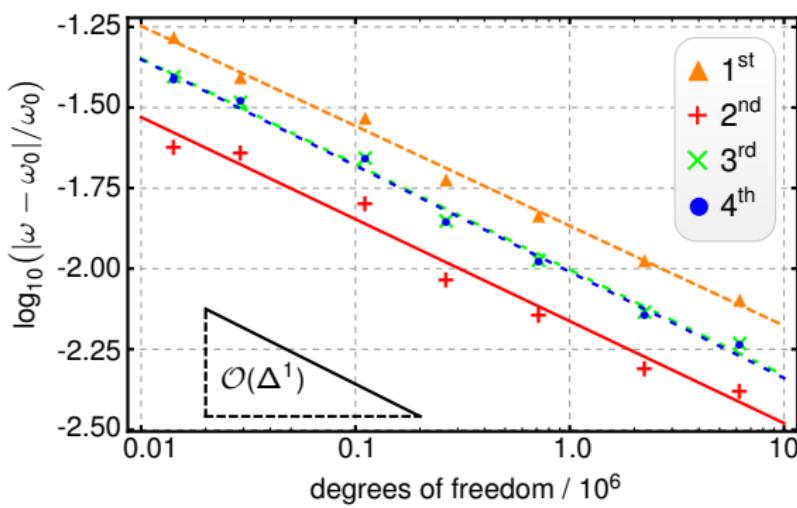
$$\vec{H}_{\text{ext}} \nparallel \vec{e}_z:$$

$$\overset{\leftrightarrow}{\mu_d} = \begin{pmatrix} \mu_{x,x} & \mu_{x,y} & \mu_{x,z} \\ \mu_{y,x} & \mu_{y,y} & \mu_{y,z} \\ \mu_{z,x} & \mu_{z,y} & \mu_{z,z} \end{pmatrix}$$

# Numerical Examples

## Biased Cylinder Resonator

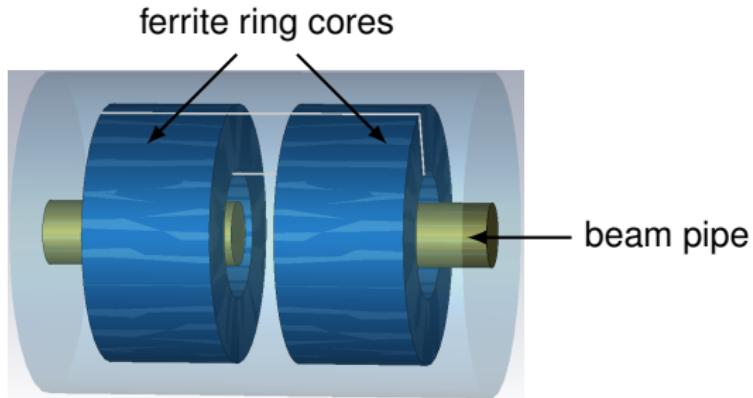
- ▶ test of construction of permeability tensor for different orientations of cylinder axis to coordinate axes
- ▶ example shown for  $\alpha = 45^\circ$  and  $\cos \beta = \sqrt{2}/3$



# Numerical Examples

## Biased Cavity With Ferrite Ring Cores

### Model description

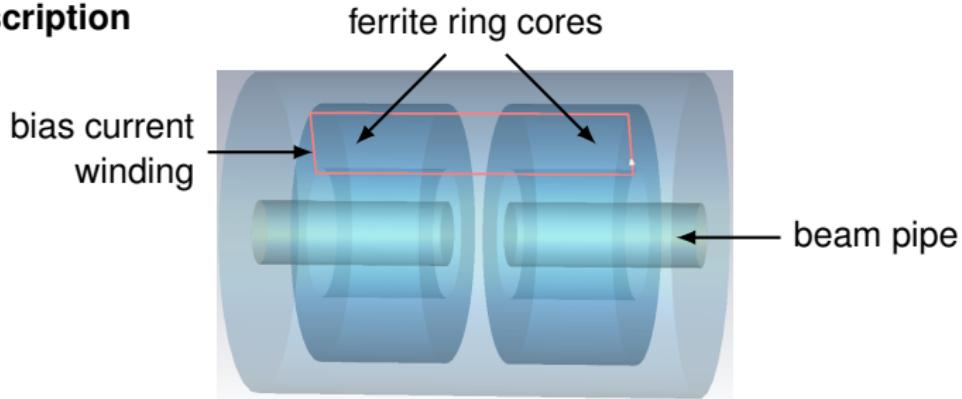


- ▶ Ferrite material is characterized by  
$$B(H) = \mu_0 \cdot 2.5 \cdot 10^4 \tanh\left(H \cdot 10^{-2} \frac{m}{A}\right) \frac{A}{m} + \mu_0 H \text{ and } \epsilon_r = 1$$

# Numerical Examples

## Biased Cavity With Ferrite Ring Cores

### Model description

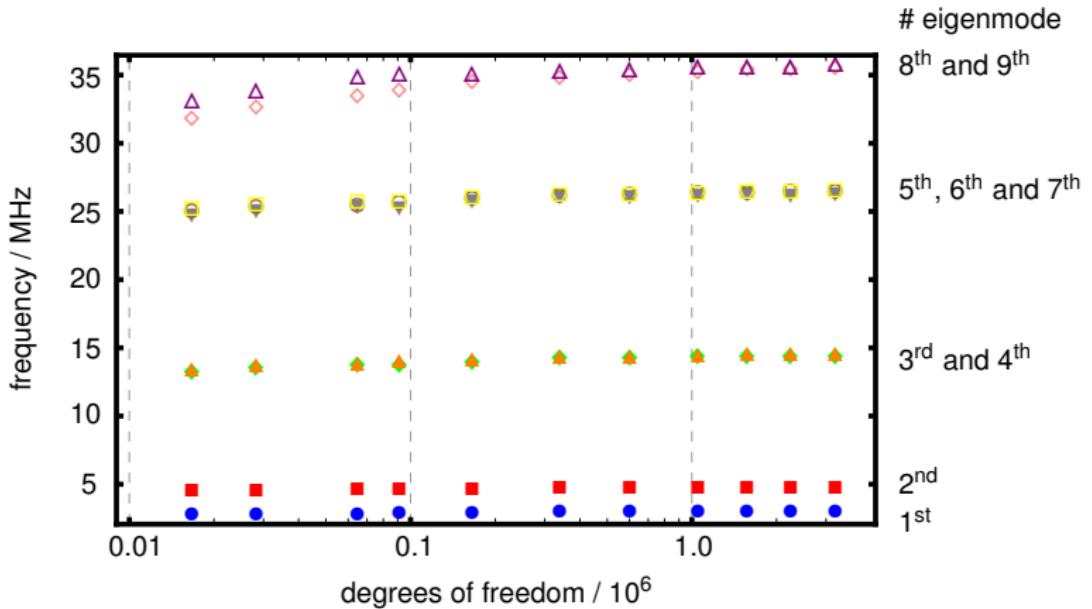


- ▶ Ferrite material is characterized by
$$B(H) = \mu_0 2.5 \cdot 10^4 \tanh\left(H \cdot 10^{-2} \frac{\text{m}}{\text{A}}\right) \frac{\text{A}}{\text{m}} + \mu_0 H \text{ and } \epsilon_r = 1$$
- ▶ bias magnetic field excited by current winding (2 kA)

# Numerical Examples

## Biased Cavity With Ferrite Ring Cores

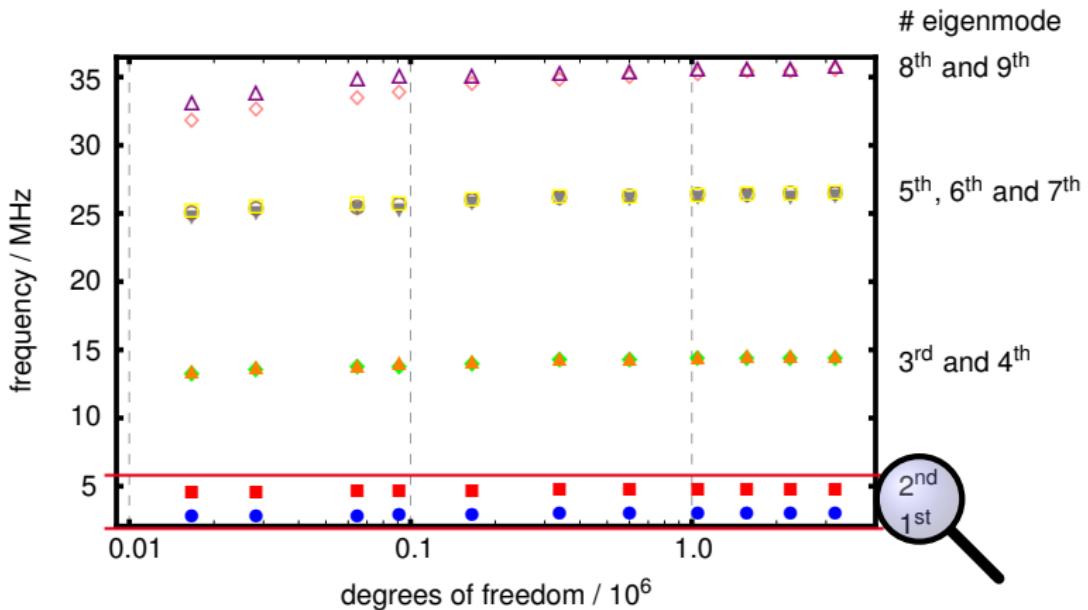
**Results of fully nonlinear computation**  
Spectrum of the lowest nine eigenmodes



# Numerical Examples

## Biased Cavity With Ferrite Ring Cores

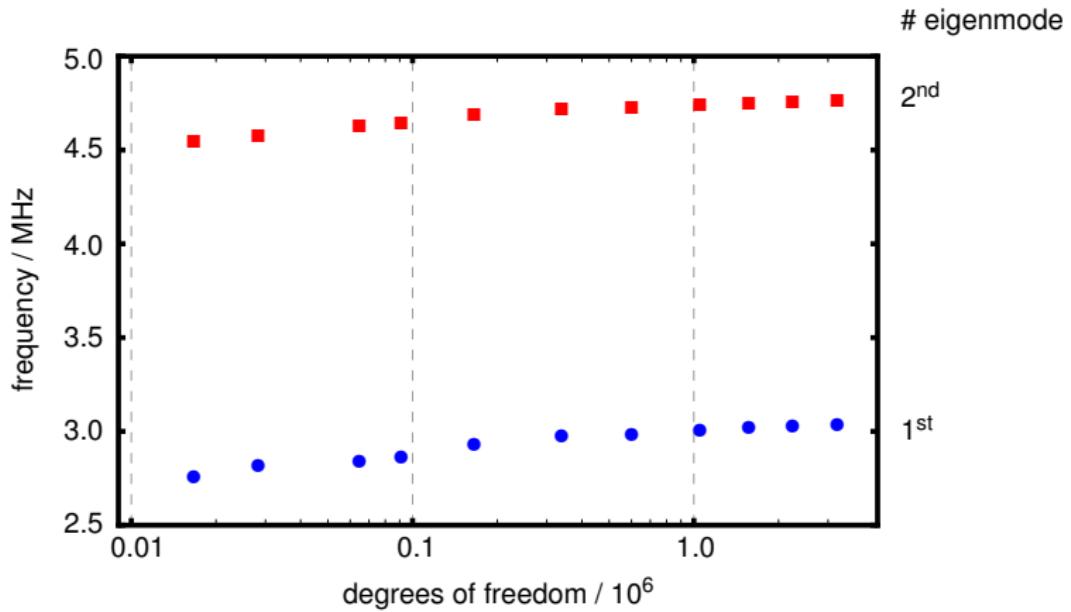
**Results of fully nonlinear computation**  
Spectrum of the lowest nine eigenmodes



# Numerical Examples

## Biased Cavity With Ferrite Ring Cores

### Results of fully nonlinear computation



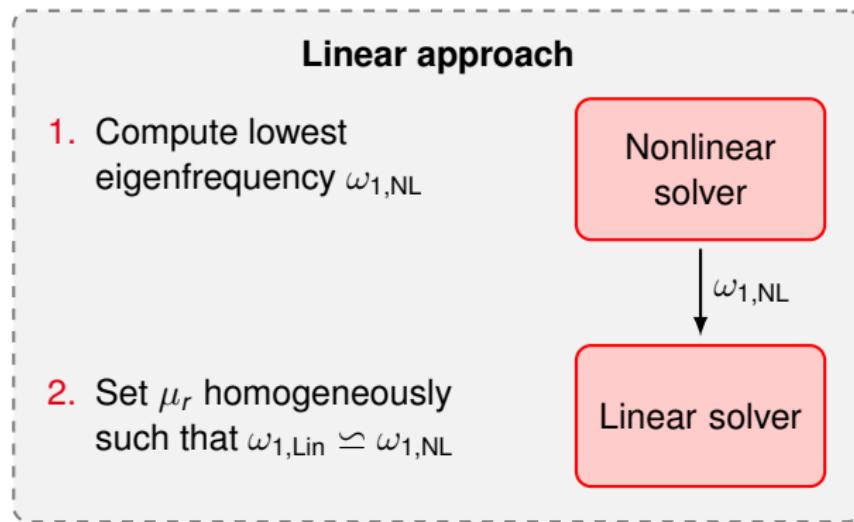
# Numerical Examples

## Biased Cavity With Ferrite Ring Cores



TECHNISCHE  
UNIVERSITÄT  
DARMSTADT

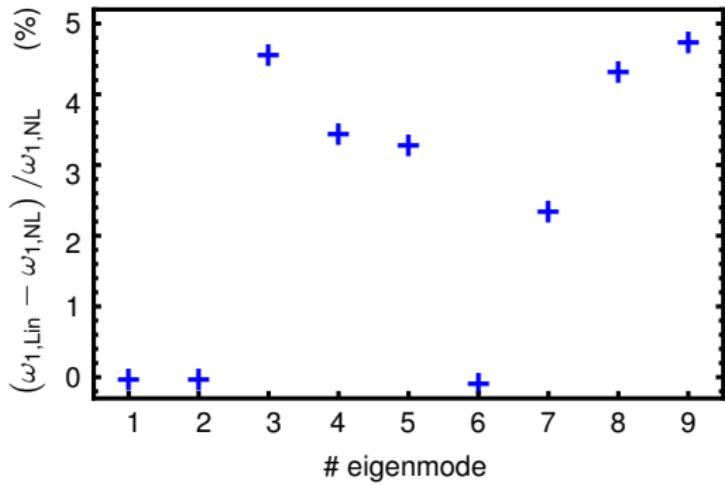
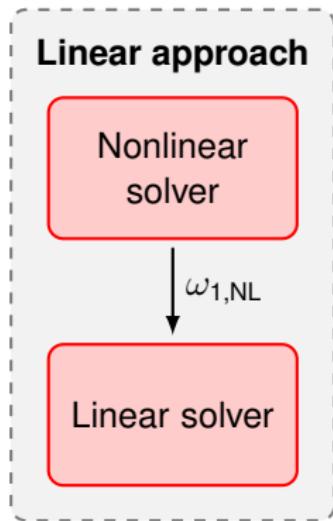
### Comparison nonlinear — linear computation



# Numerical Examples

## Biased Cavity With Ferrite Ring Cores

### Comparison nonlinear — linear computation



# Contents

Motivation

Computational Model

Fundamental Relations

Implementation

Parallel Computing

Numerical Examples

Biased Cylinder Resonator

Biased Cavity With Ferrite Ring Cores

Summary



# Summary

► **Goal:**

calculation of eigenvectors for biased ferrite cavities

1. Magnetostatic solver (nonlinear material):

⇒ permeability tensor  $\overset{\leftrightarrow}{\mu}_d$

Magnetostatic  
solver

$$\downarrow \overset{\leftrightarrow}{\mu}_d^{-1}$$

2. Eigensolver:

⇒ nonlinear complex eigenvalue problem

Eigensolver

# Summary

► **Goal:**

calculation of eigenvectors for biased ferrite cavities

1. Magnetostatic solver (nonlinear material):

⇒ permeability tensor  $\overset{\leftrightarrow}{\mu}_d$

Magnetostatic  
solver

$$\downarrow \overset{\leftrightarrow}{\mu}_d^{-1}$$

2. Eigensolver:

⇒ nonlinear complex eigenvalue problem

Eigensolver

► **Status:**

Functionality of fully nonlinear solver for Hermitian  
problems demonstrated

