

KECK TELESCOPE CONTROL SYSTEM UPGRADE (TCSU) PROJECT STATUS [MOCOAB05]

J.Johnson, K.Tsubota, J.Mader
W.M. Keck Observatory



The Telescope Control System Upgrade

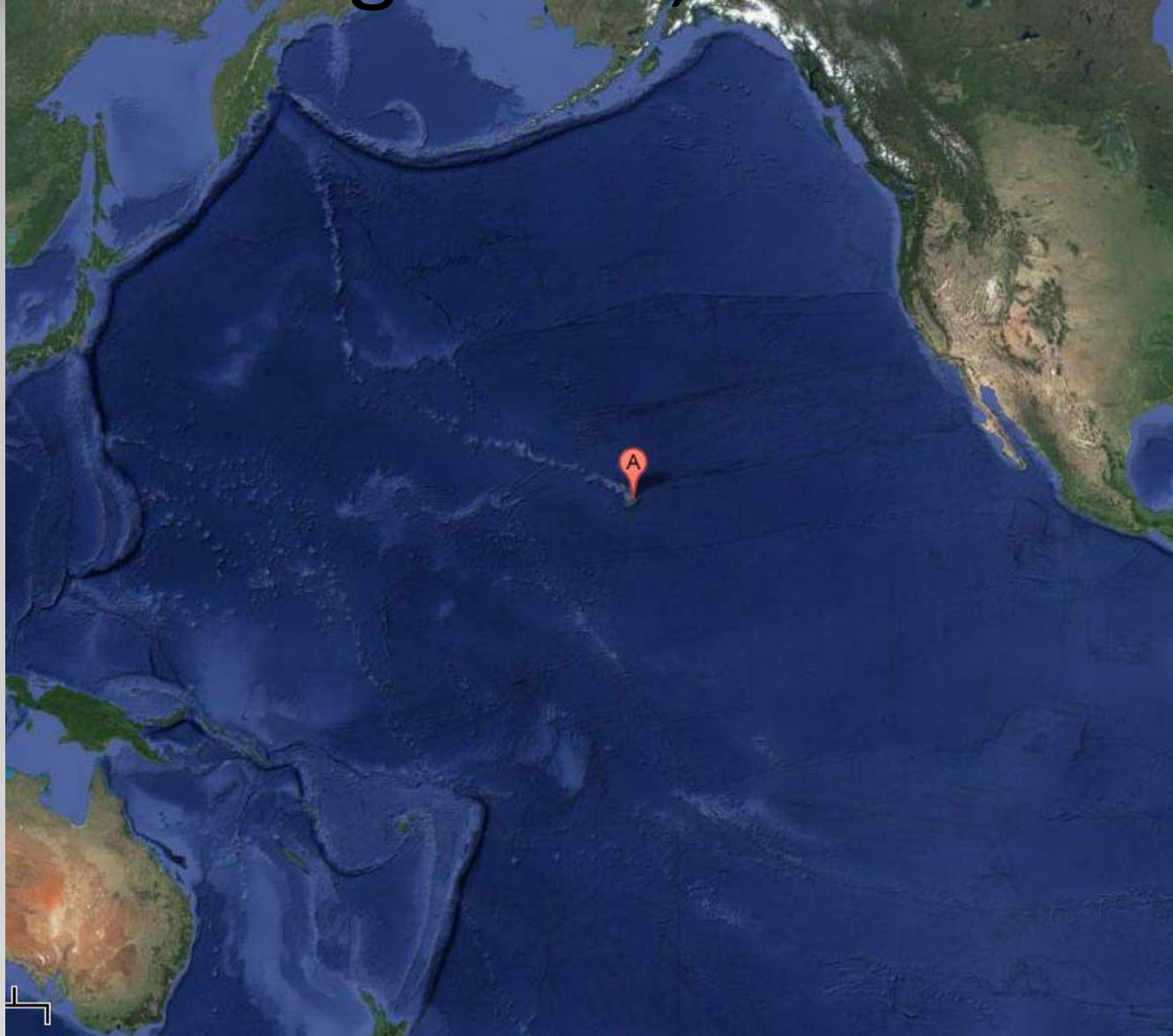
- The Keck telescopes, located at one of the world's premier sites for astronomy, were the first of a new generation of very large ground-based optical/infrared telescopes.
- The first Keck telescope began science operations in May of 1993, and the second in October of 1996 making the components of the telescopes and control systems more than 15 years old.
- The upgrade to the control systems of the telescopes consists of mechanical, electrical, software and network components .



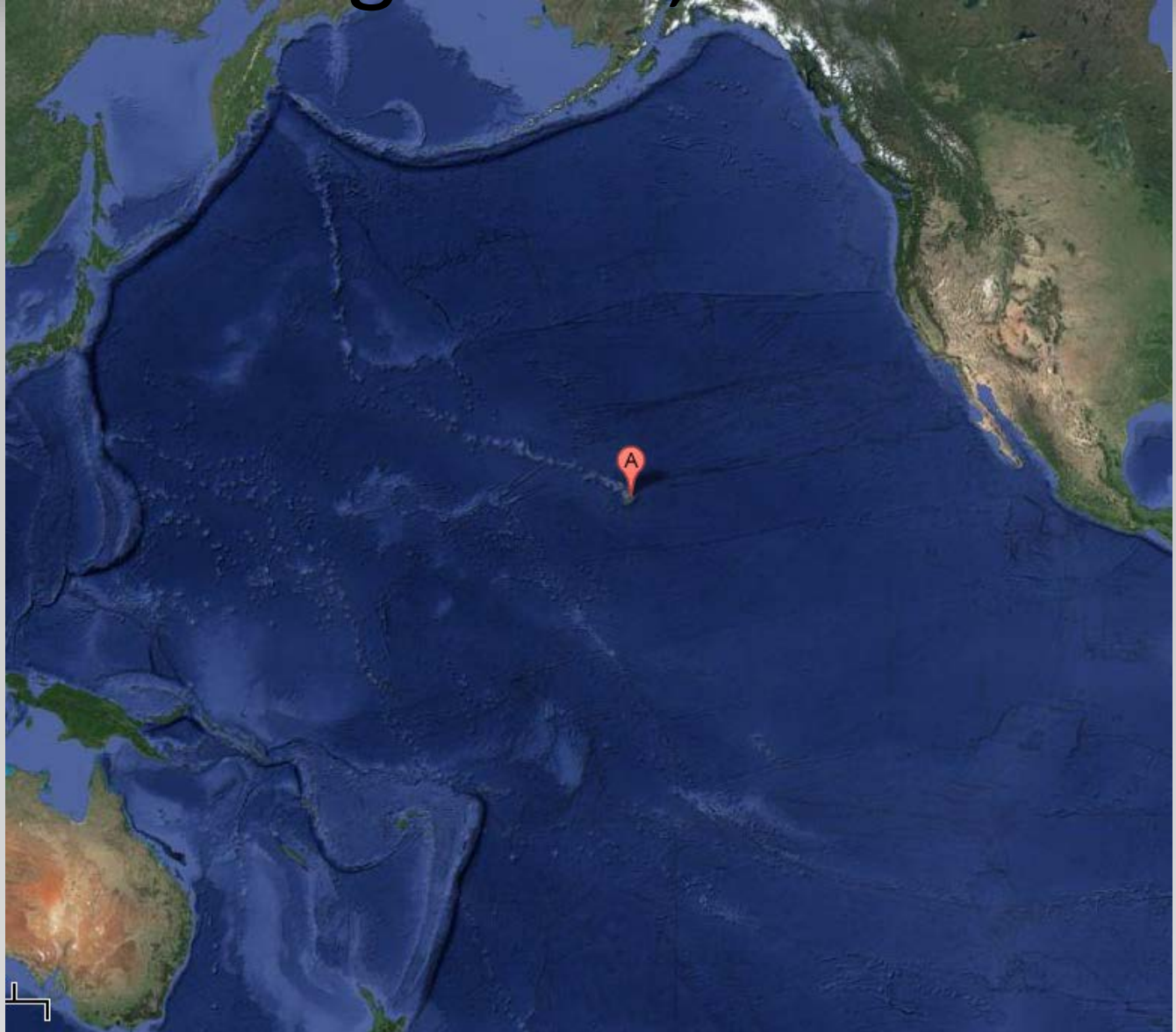
Additional Talks & Posters

- THCOBB05
 - Challenges and solutions to upgrading a running system
- THPPC067
 - New EPICS (ASYN based) device drivers for TCSU
 - National Instruments RIO, Heidenhain EIB, Symmetricom BC635PCle,
- TUPPC032
 - A database-backed configuration service for IOC persistence

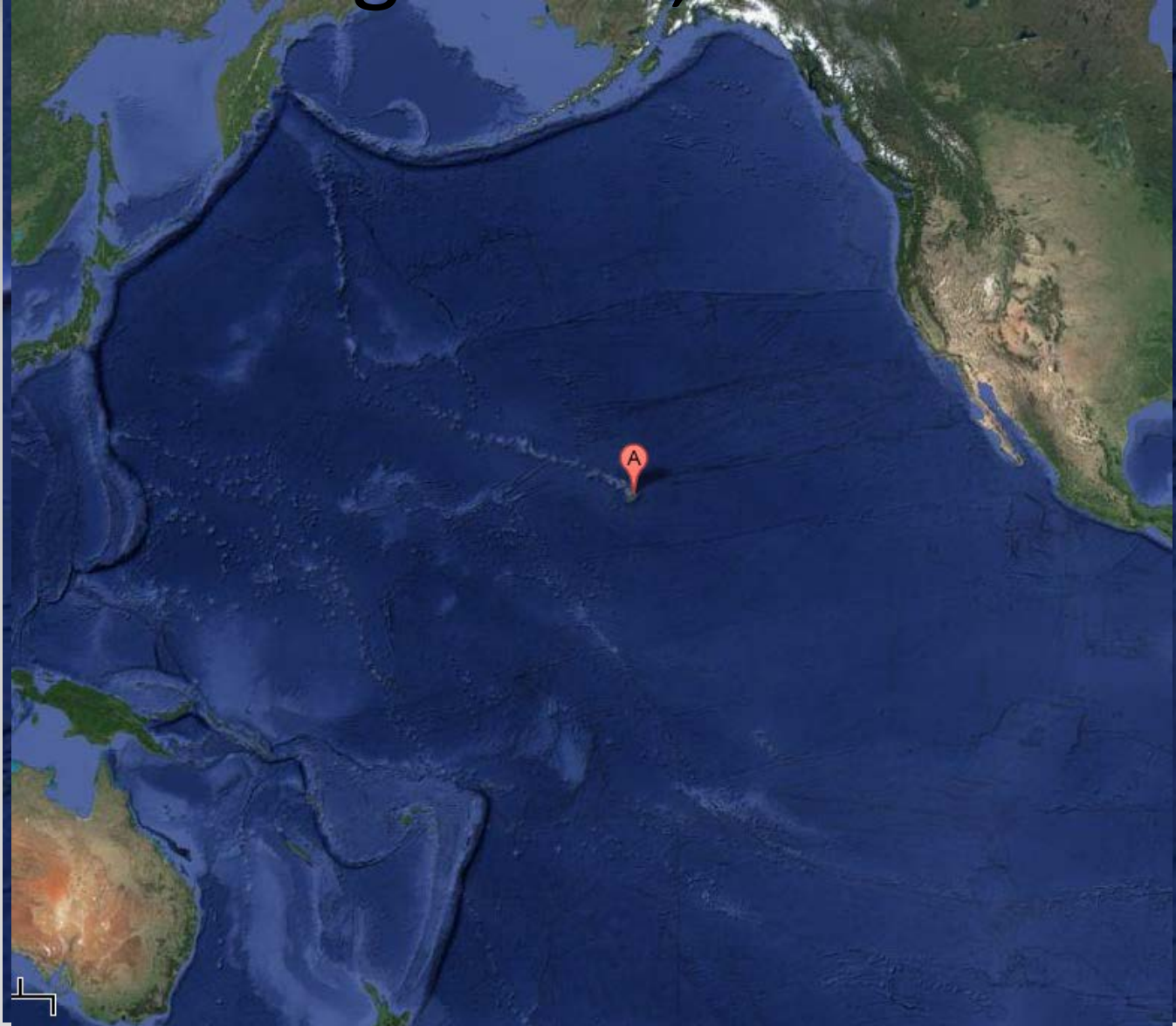
The Big Island, Hawaii



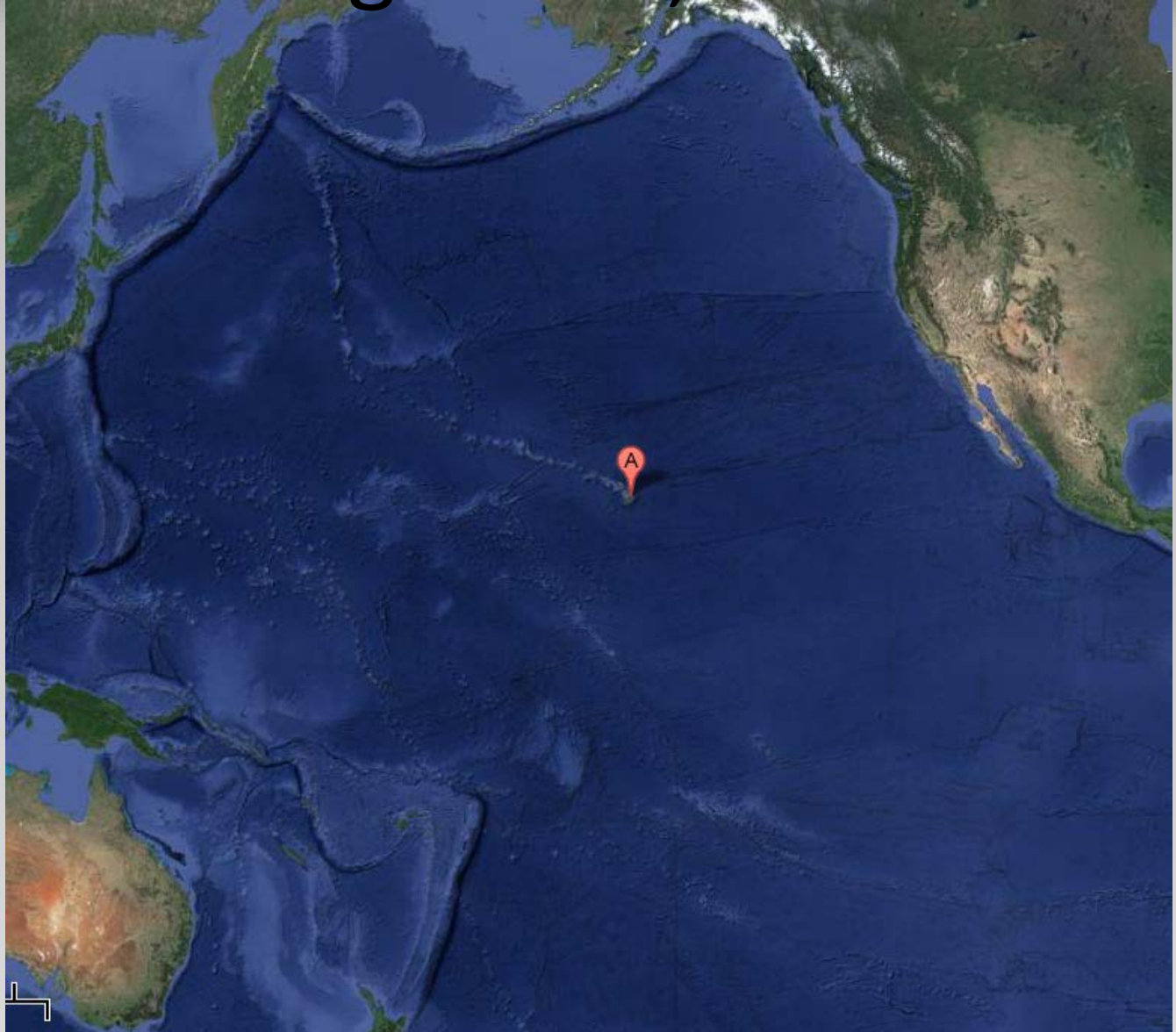
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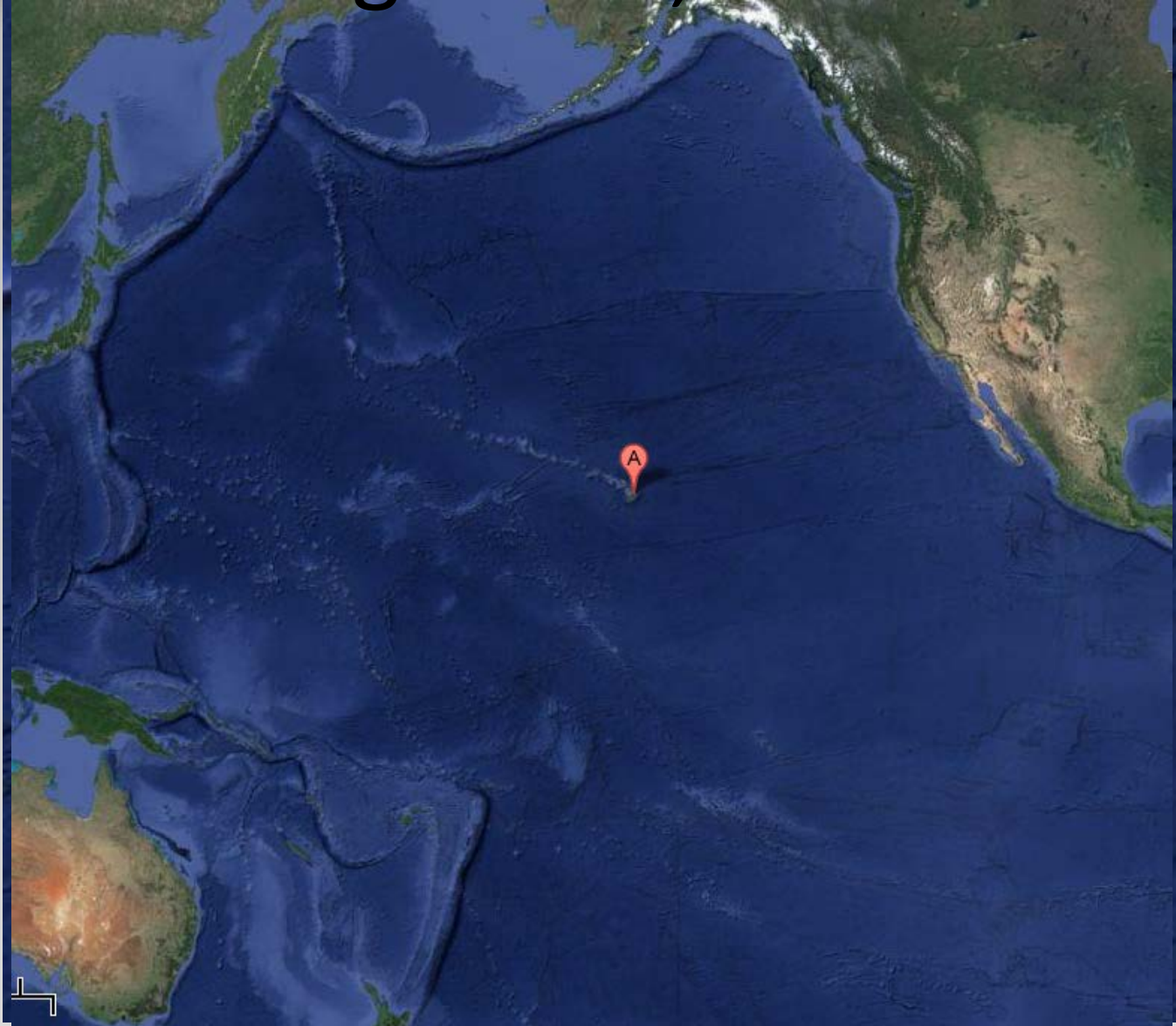
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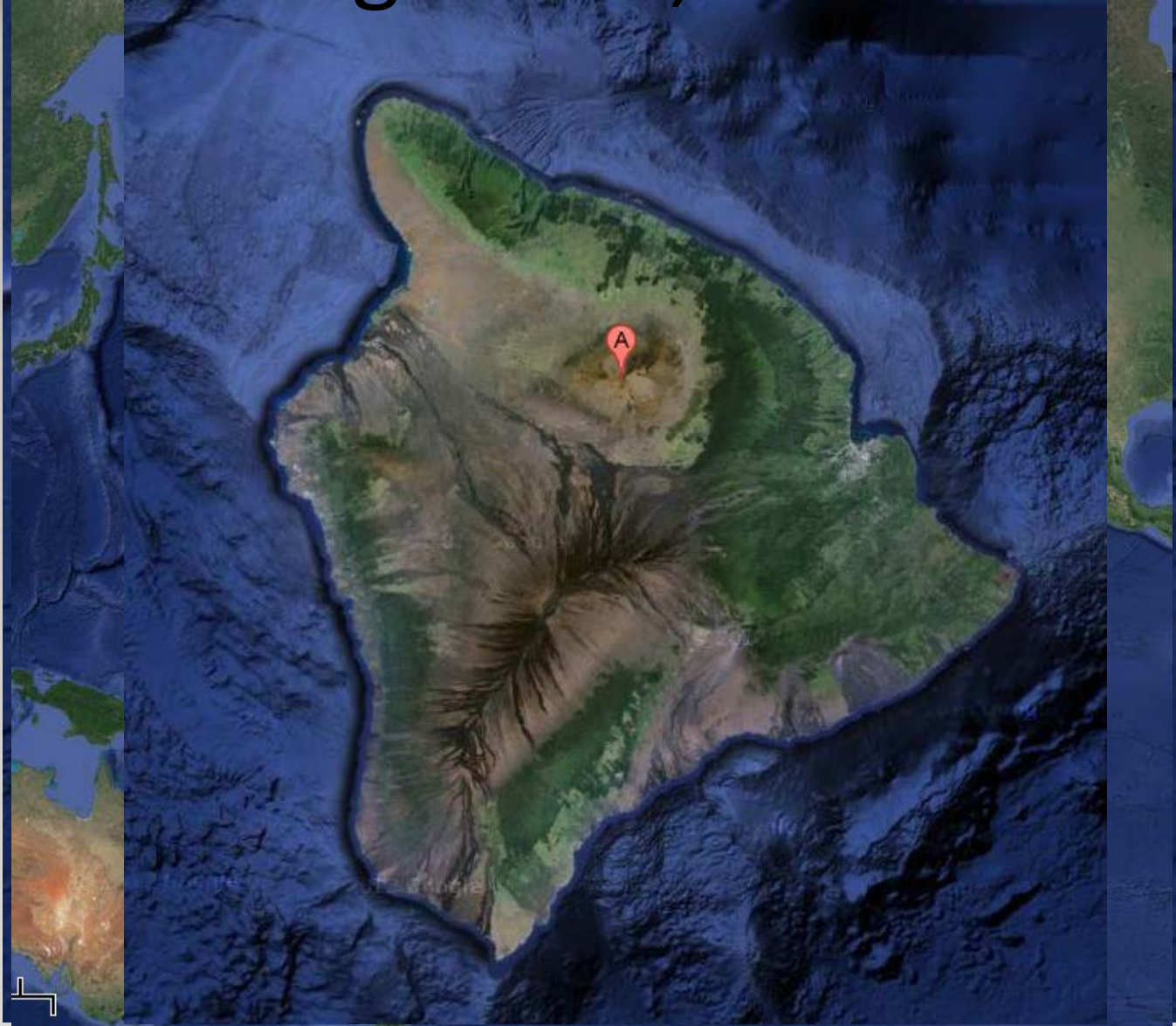
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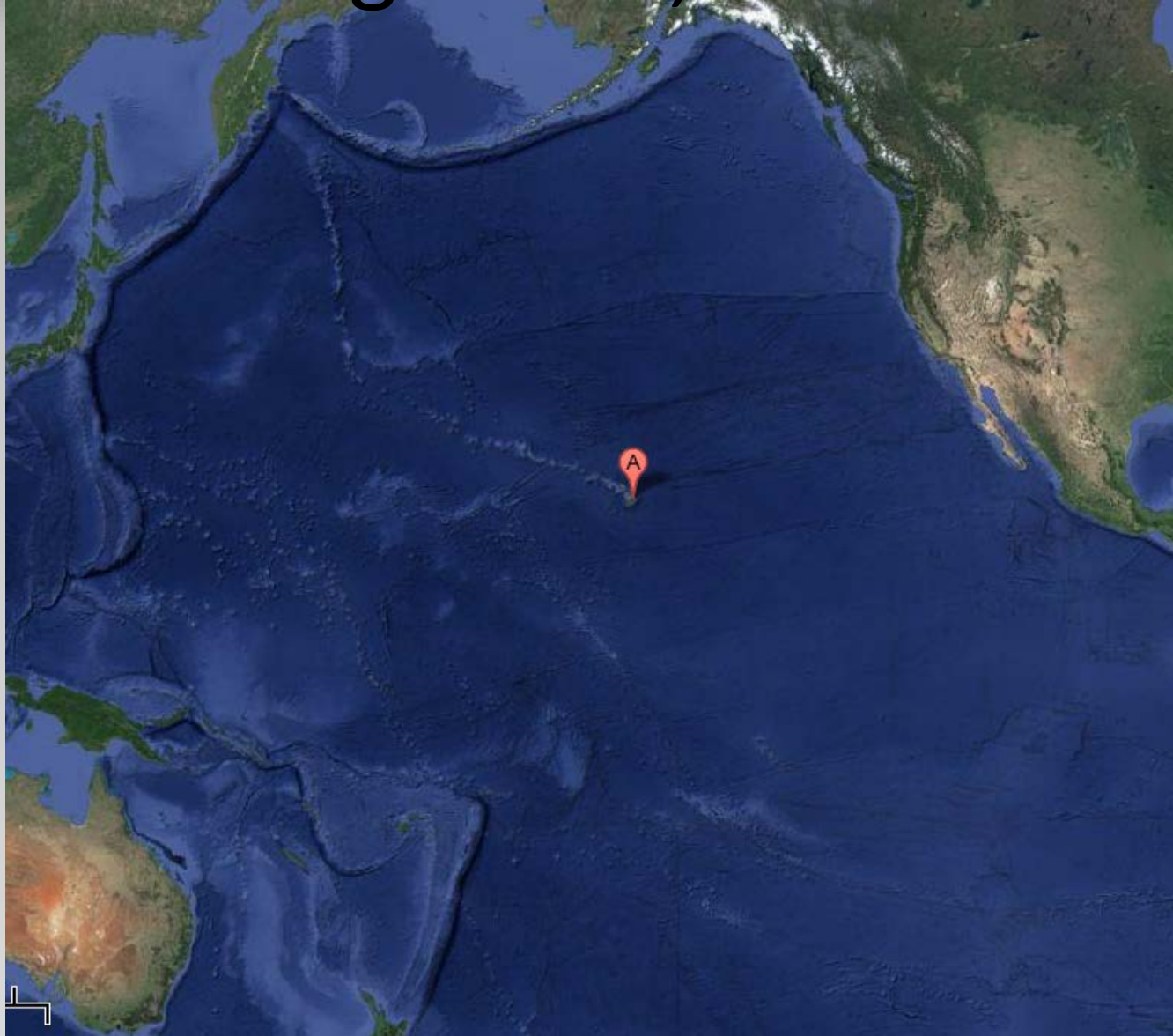
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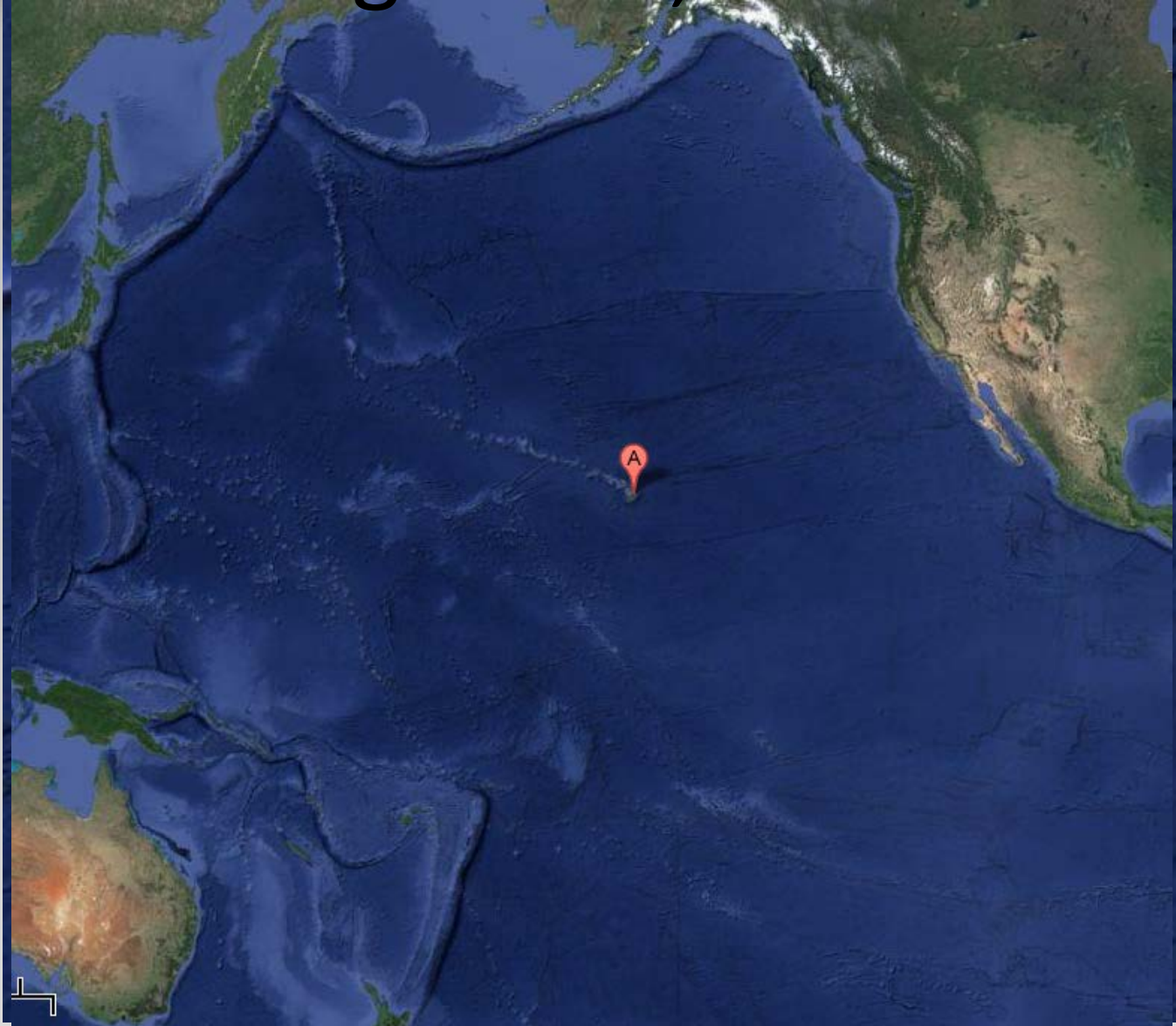
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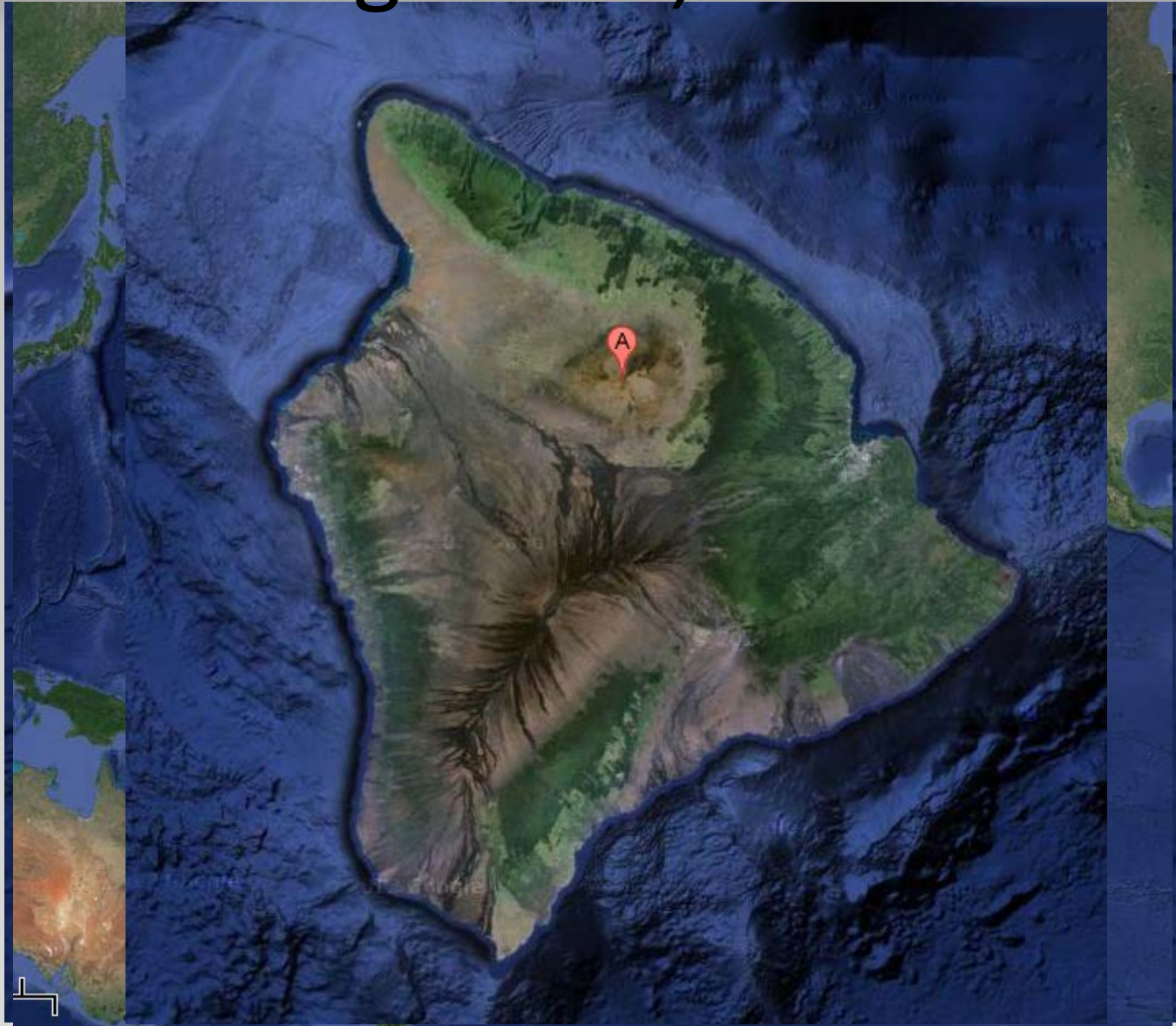
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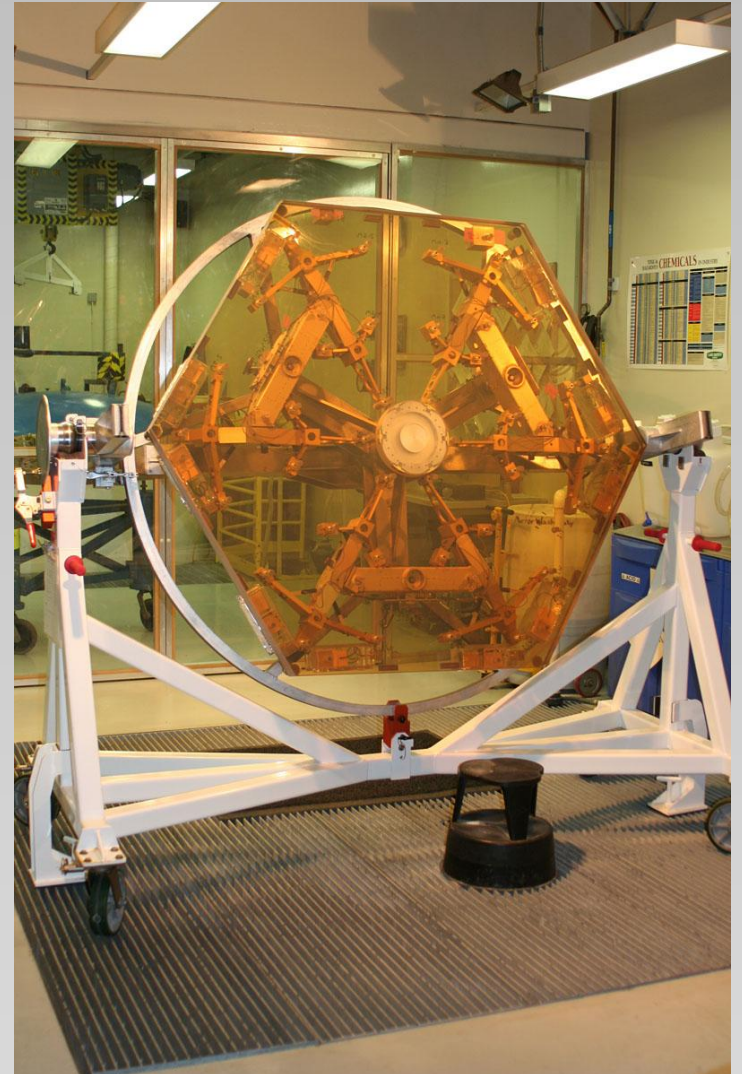
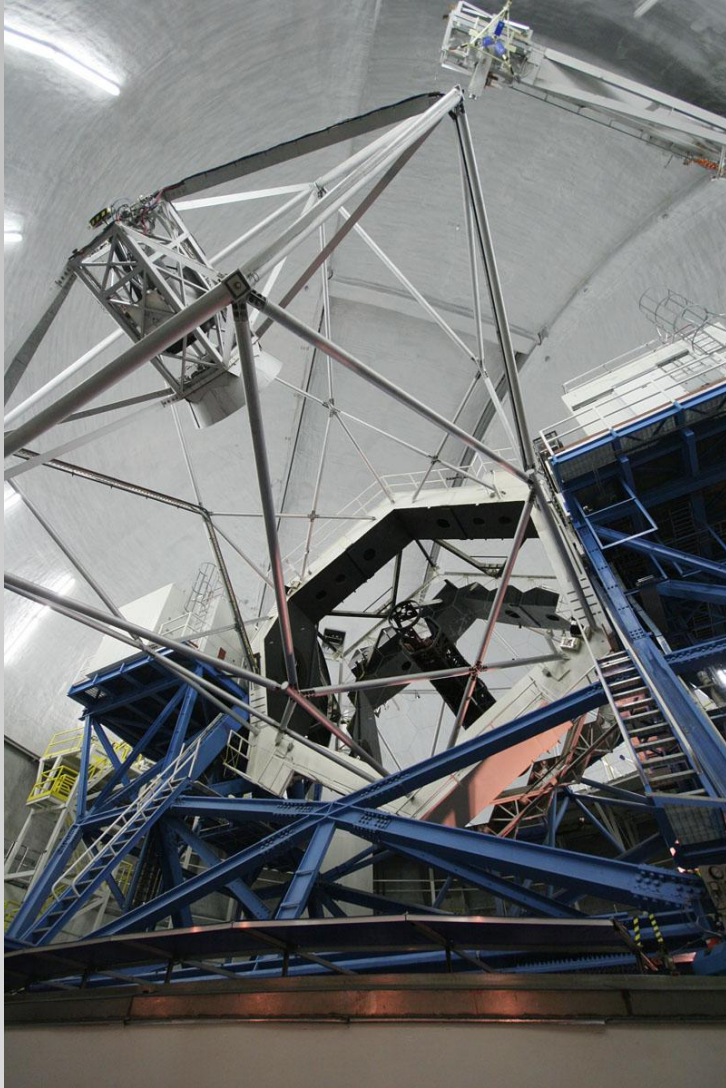


Headquarters at Kamuela, HI

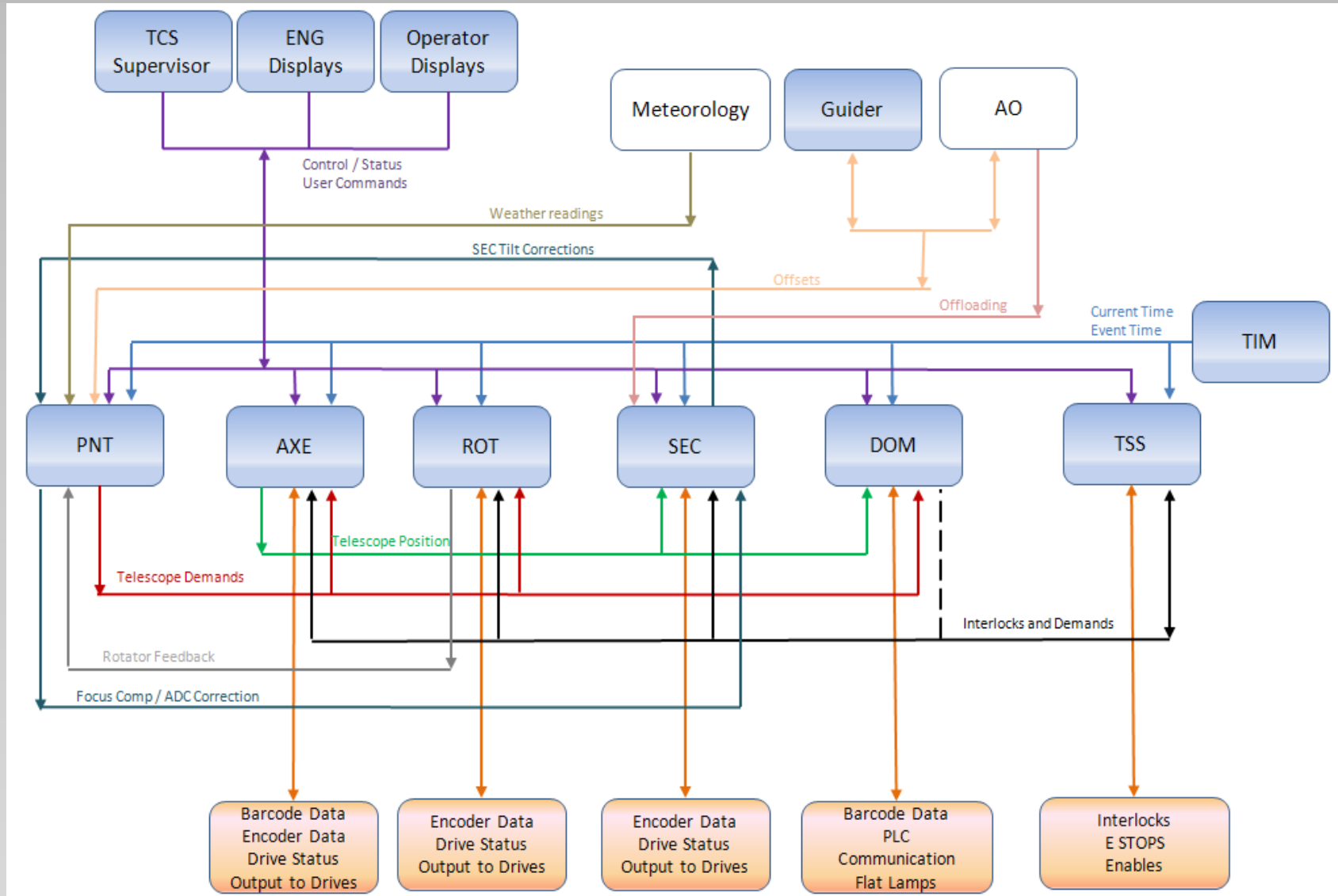


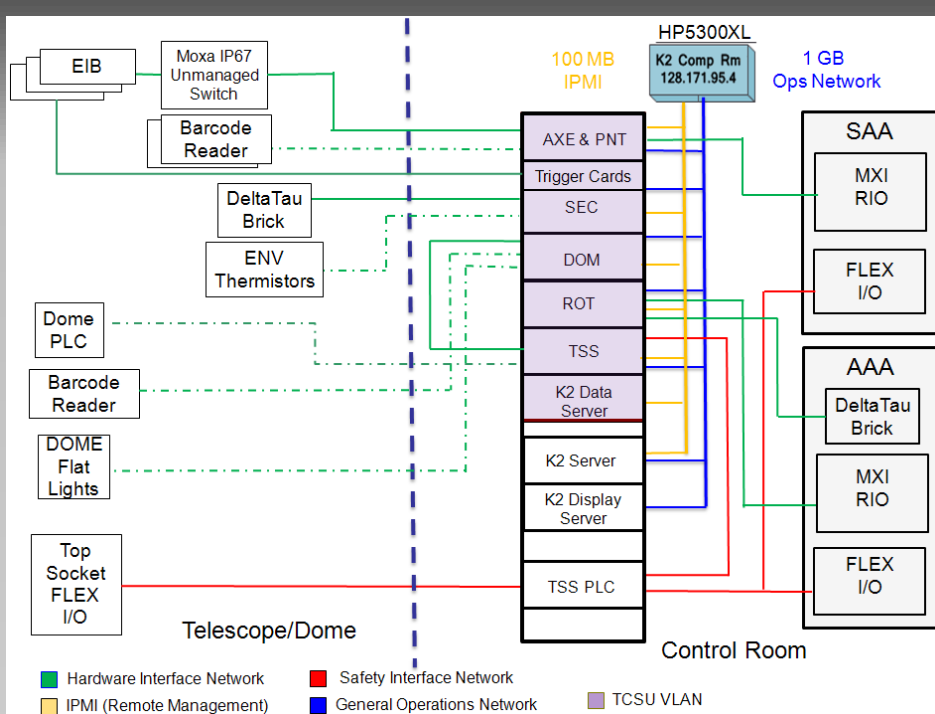


Telescope, Dome and Mirror(s)



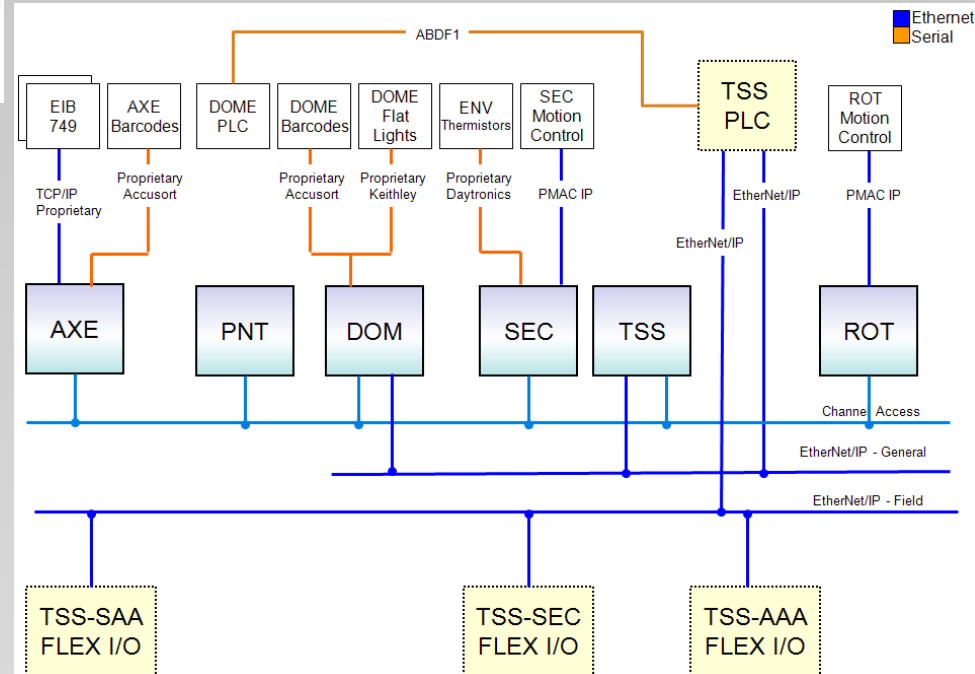
TCS Subsystems



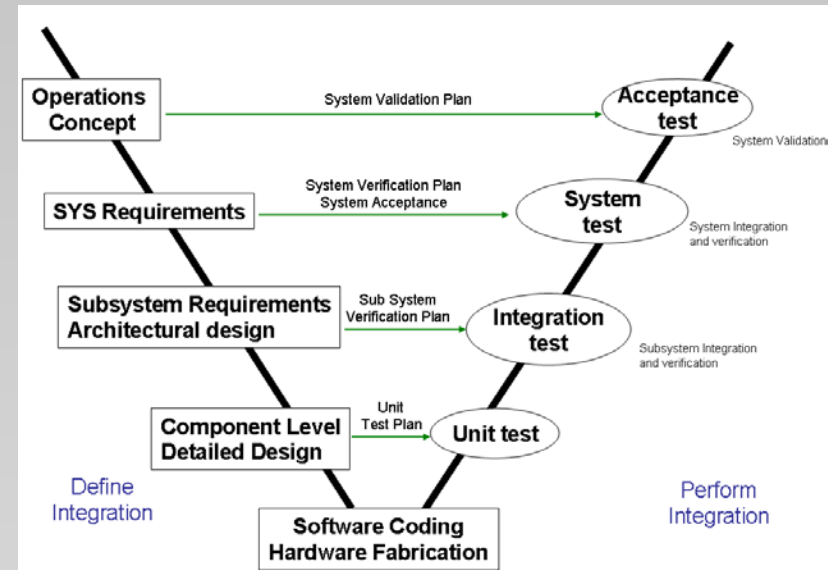
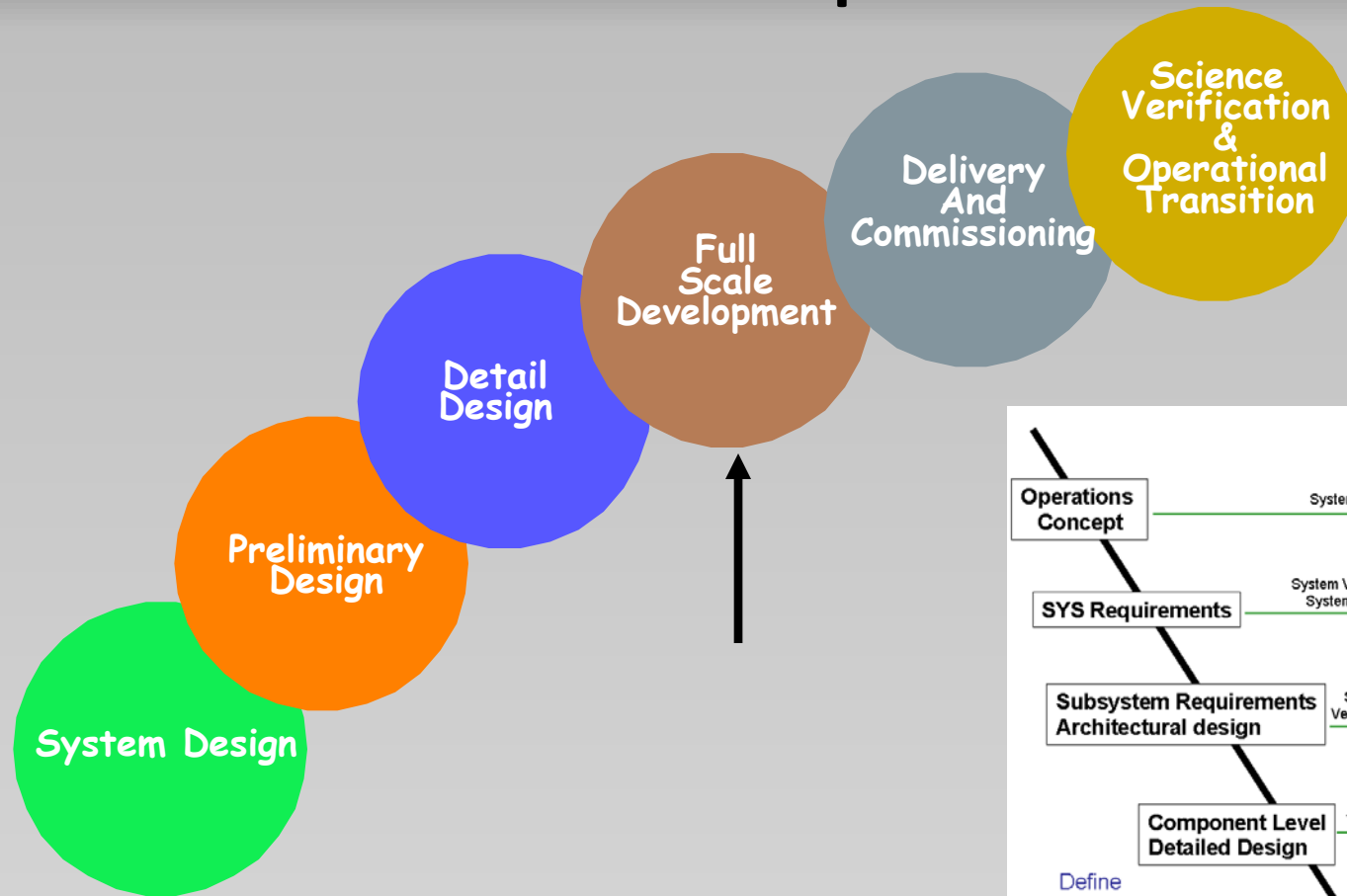


Subsystem Physical View

Subsystem Protocols

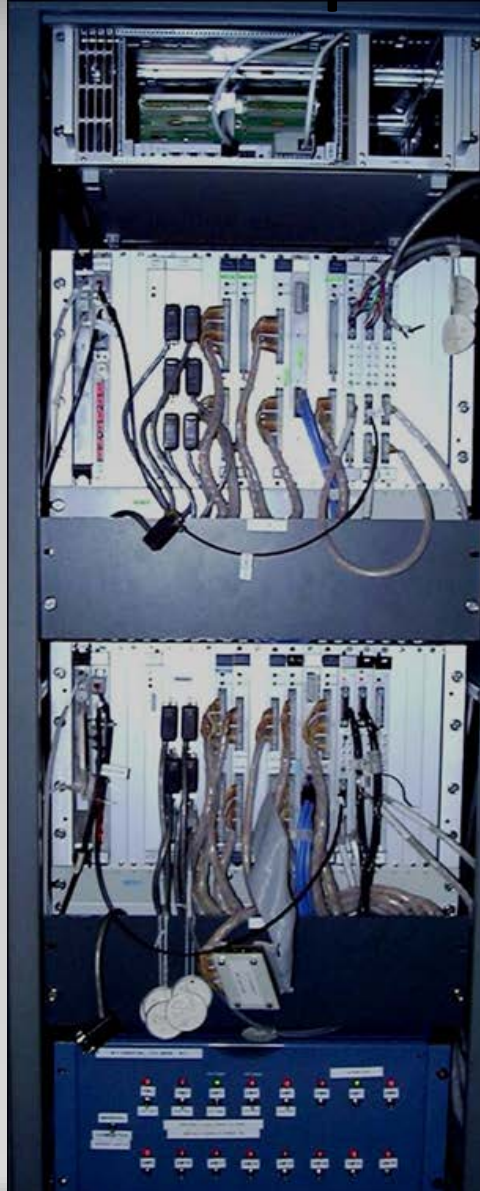


The Development Process



JAMA Suite (formerly Contour) for requirements management
Six Sigma "Failure Modes and Effects Analysis (FMEA) for risk analysis
Microsoft Project for schedule and tracking

Examples of Existing Hardware



Logic Boards for drive amplification



*Telescope Drive
Analog Logic*



IO Racks for auxiliary control

*VME Crates for the K1 telescope
control system*



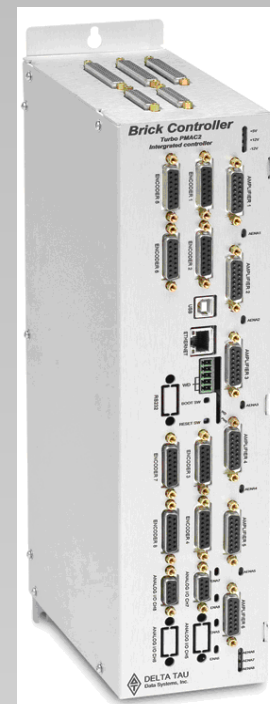
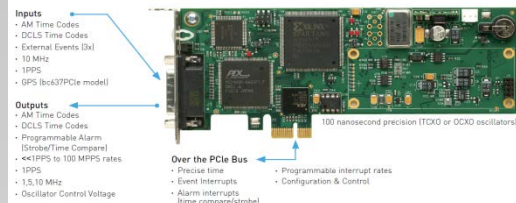
*Azimuth Manual
Control Panel*



New TCSU COTS Hardware



Precision Time & Frequency
in the PCIe Form Factor



What	Principal Subsystem
IPMI	ALL
Multi Port Ethernet	ALL
bc635PCIe	ALL
RocketPort Express	AXE, DOM, SEC
MXI	AXE, ROT
Brick	ROT, SEC

Hardware components mapped to subsystem



Existing Encoder Solution



K2 Azimuth – Encoder, barcode and Precision Reference Mark (PRM)



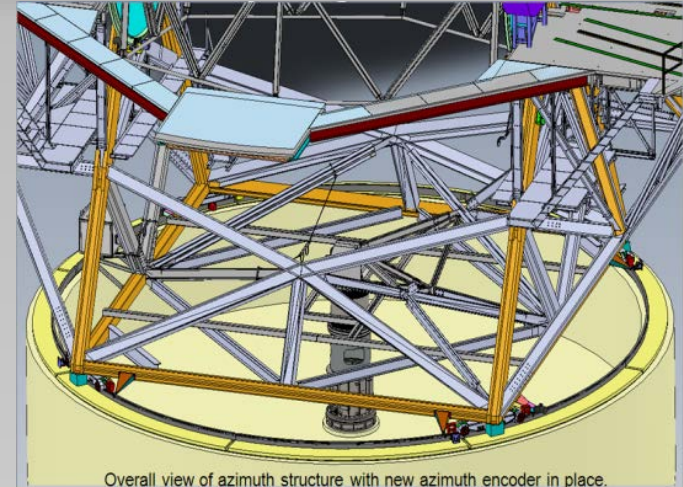
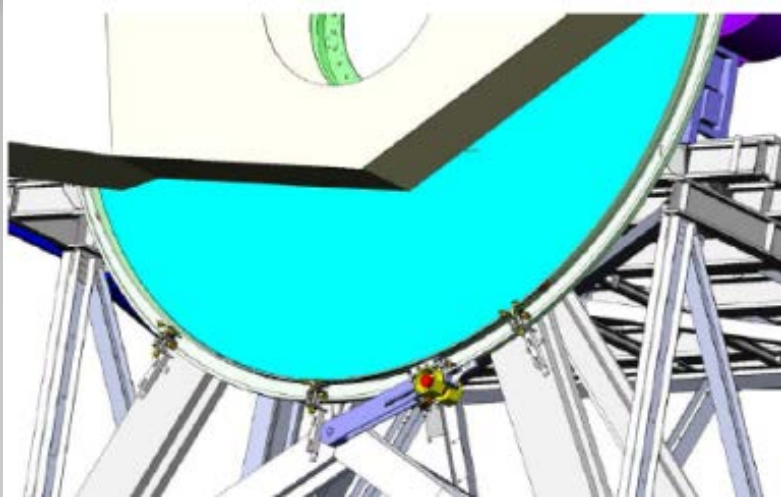
K2 Azimuth - PRM close up



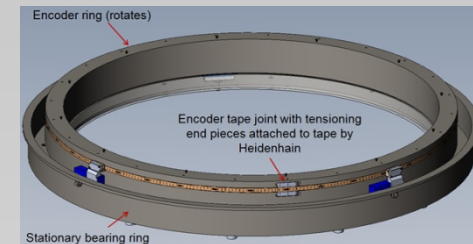
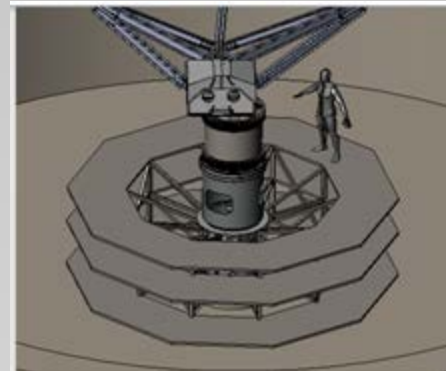
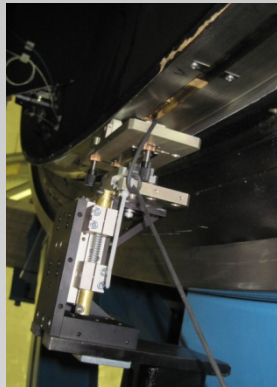
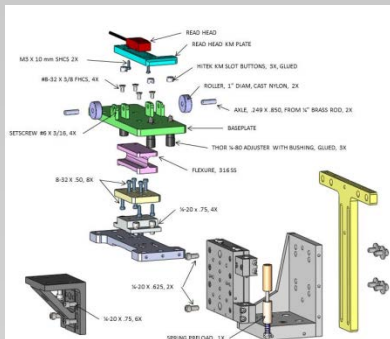
K2 Encoder Interface

Heidenhain ROD 800 - Sealed Incremental Angle Encoders with Solid Shaft
Barcode solution for absolute positioning to 1 degree
Precision Reference Marks (PRMs) for absolute positioning to 0.1 degree
Custom Electronics and VME Counter Cards

New Encoder Solution



Overall view of azimuth structure with new azimuth encoder in place.



Heidenhain ERA 8480 Read Heads
Heidenhain ERA 8400 C/I Tape (with Distance Coded Reference Marks)
Heidenhain EIB 749 – Encoder Interface Box

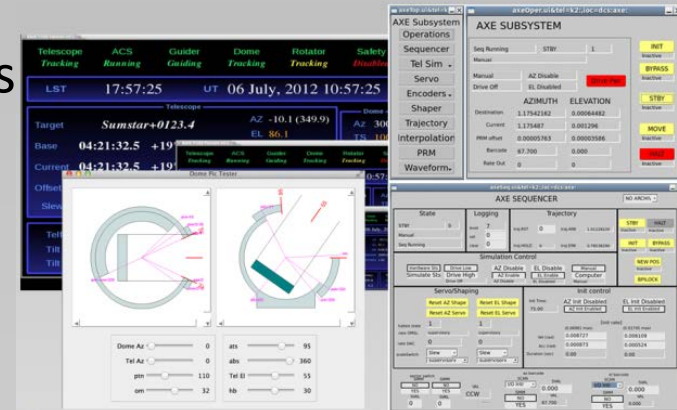
Full Scale Development To Date

- Build Environment complete with full configuration management and tools (TDCT, make, debuggers, release scripts etc.)
- All COTS hardware has been purchased and integrated with EPICS
- The HQ Lab has Linux servers with MRG real time running EPICS IOCs and functioning implementations for:
 - All necessary drivers
 - TIM subsystem
 - Infrastructure and tools
 - PLC communication and basic programming
 - FPGA communication and basic programming
 - IOC monitoring
 - AXE, ROT, SEC, DOM and PNT software



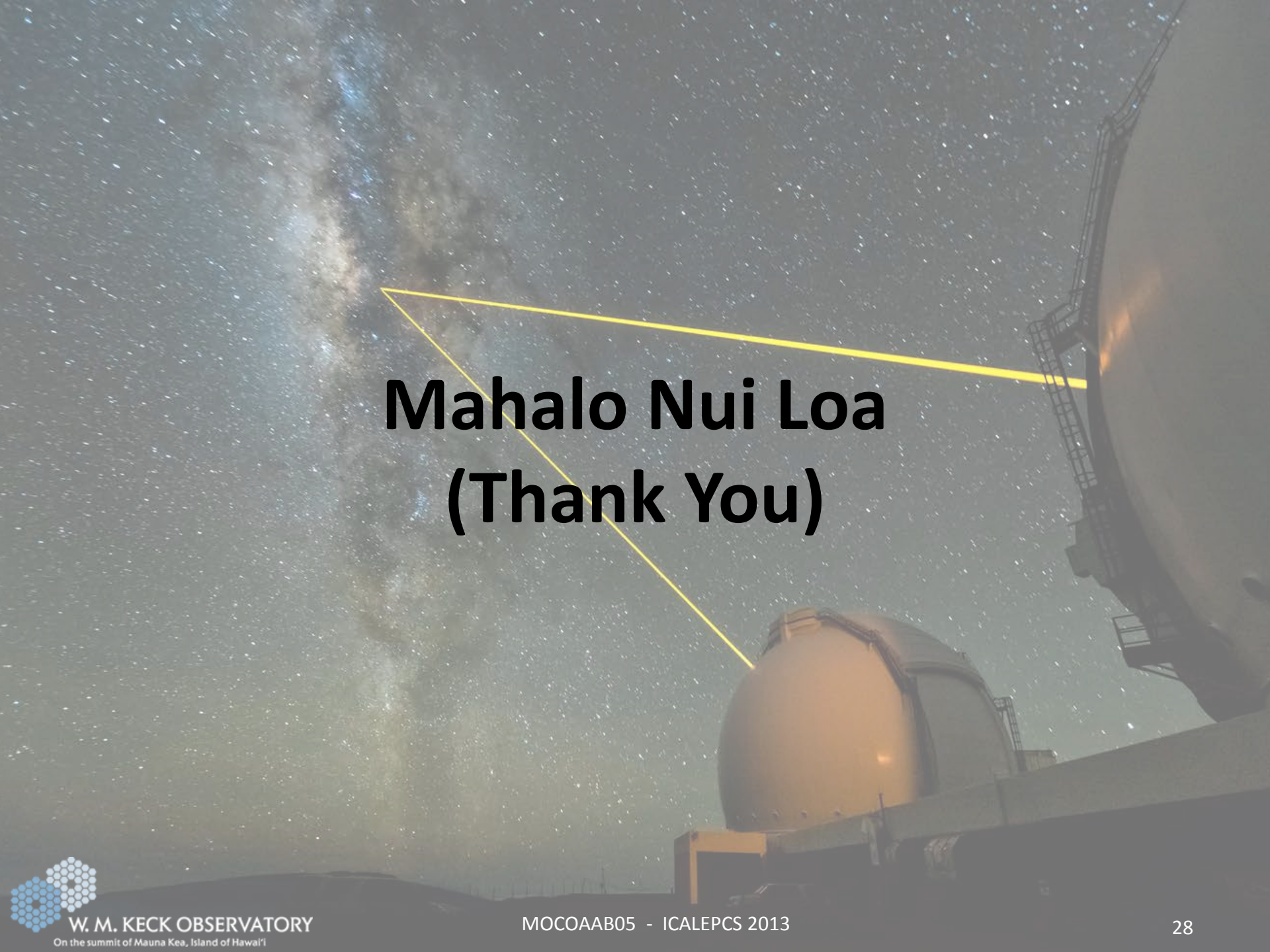
Full Scale Development To Date

- All existing engineering user interfaces have been ported (painlessly) from DM to caQtDM
- QT based prototypes completed for ops displays
- Elevation Encoder Prototype Complete
 - More engineering nights planned
- Azimuth Encoder Prototype work has started
 - Basic collocation and vibration analysis complete
 - Expect summit installation January 2014
- New feed-forward and revised structural filter for servo solution has been tested
- Secondary load-side encoder installation will start in October
- Kinematic programming for secondary coordinated moves are finished
- Telescope testing has begun with aspects of the new DOM subsystem



What is Next?

- Complete full scale development
- Complete azimuth encoder prototype
- Perform headquarters integration and test
- Perform summit preparations
 - Install switch boxes, pull cables, cable the switching solution and field I/O
- Start KII Deployment, commissioning and operational hand over
 - Goal completion date: December 2014
- Start KI Deployment, commissioning and operational hand over
 - Goal completion date: September 2015



Mahalo Nui Loa (Thank You)