# **Analyzing Off-Normals In Large Distributed Control Systems Using Deep Packet Inspection and Data Mining Techniques** M.Fedorov, G.Brunton, C.Estes, J.Fisher, C.Marshall, E.Stout

Network packet inspection using port mirroring provides the ultimate tool for understanding complex behaviors in large distributed control systems. The timestamped captures of network packets embody the full spectrum of protocol layers and uncover intricate and surprising interactions. No other tool is capable of penetrating through the layers of software and hardware abstractions to allow the researcher to analyze an integrated systems, closed-source embedded controllers, software libraries and middleware. Being completely passive, the packet inspection does not modify the timings or behaviors. The completeness and fine resolution of the network captures present an analysis challenge, due to huge data volumes and difficulty of determining what constitutes the signal and noise in each situation. We discuss the development of a deep packet inspection toolchain and application of the R language for data mining and visualization. We present case studies demonstrating off-normal analysis in a distributed real-time control system. In each case, the toolkit pinpointed the problem root cause which had escaped traditional software debugging techniques.

## **Benefits and Challenges of Network Packet Captures**

### **Pros:**

- Works across server and embedded platforms
- Captures variety of protocols
- Cuts across network layers
- Passive, does not modify timings or behaviors
- Millisecond-scale accuracy of event timestamps
- Supported by high-end network routers
- Open-source tools are available (tcpdump)
- Commercial tools are available (OPNET)

### Cons:

- Specialized network hookup is required
- Dedicated capture host is needed • Large fast storage is required,
- **GBs/host** Visualization is slow with WireShark
- or **OPNET** Hard to identify interesting events

## Identification of Distributed **Event Patterns**

	4	ac-tgt-2 CORBA calls summary before and after NIF Shot performance optimizations Blue circles: Ops/min. Red: Retries/min. Accumulated at 15min intervals
	approve_Move - cancel_Proposed_Move - continue_Current_Move - disable_Bounded_Moves - execute_Proposed_Move -	
	mark_Aligned - propose_Next_Move - get_Managed_Service_Ref -	
	move_Not_Approved ping clear_Mert do_Request get_Managed_Ref	
	get_Process_Info get_Process_Info heartbeat nonexistent publish_Atert store_Machine_History_Data	
	update_Report -	
	move_Abo a move_Approve - move_Cancelled -	npacted by slowdown
	move_Progress - move_Proposed -	
creat	change_Setpoint_Position - copy_Setpoint_Set_Locks - te_Or_Modify_Setpoint_From_Current_Position -	
	create_Setpoint_From_Current_Position delete_Locked_Setpoint - delete_Setpoint - rename_Setpoint -	Triggering slowdown
	at_Last_Goto- at_Setpoint = at_Some_Setpoint = calc_Timeout = get_Anyfied_Current_Position = get_Anyfied_Current_Position = get_Setpoint = get_Setpoint =	
ē	get_serpoint - goto_setpoint - goto_Setpoint_Hater - setpoint_Names_For_Current_Position -	
Operation Nar	convert To,Or,From TOC - convert To,Or,From TOC - create_Setpoint_From_Any_With_Locks - deregister_GUI - get_Alignment_State - get_Async_Status - get_Axes_From_Position_And_Systick - get_Axes_From_TCC_Cartesian -	
	get_Axis_Rates - get_Commissioning_Modes - get_Components - get_Components_Status - get_Components_Status -	
	get_Configuration - get_Emulation_Status - get_Exposure - get_Exposure -	o ∞o o o o o o o o o o o o o o o o o o
	get_Interface_For_Framework_Use_Only get_Interface_For_Framework_Use_Only get_Interface_Names = get_Joystick_Aris_Vectors = get_Joystick_Freedoms = get_Joystick_Traces = get_Joystick_Video_Settings = get_Mode ont_Moter_Torces	
	get_Operating_Mode - get_pair - get_Position - get_Scale -	
	get_Settings - get_Status - get_Stored_Status = get_Tap_Components - get_Tas_Illuminator_Taxon - get_Taxon - get_Taxon -	
	_get_Units - get_Usable_Joysticks - _s_a = is_initialized - _non_existent - ping -	
	receive_Status register_GUI- release set_Depth_Limit set_Direction_To_Get_Status set_Liminator - set_Iluminator -	
stop	set_Led_Spotlight_Intensity - sot_Operating_Mode start_Attribute_Monitor stop - p_Attribute_Monitor_For_Framework_Use_OID+ wait For_Commention	

- The API Breadth and an efficient tool for Visualization covered
- operations
- events was accurately represented
- events were not lost
- TCP retransmits) were

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**Volume Diagram provided** identifying event patterns millions of distributed operations over days of

Volume of high-frequency

Single and low-frequency Additional attributes (e.g.

overlaid and color-coded

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