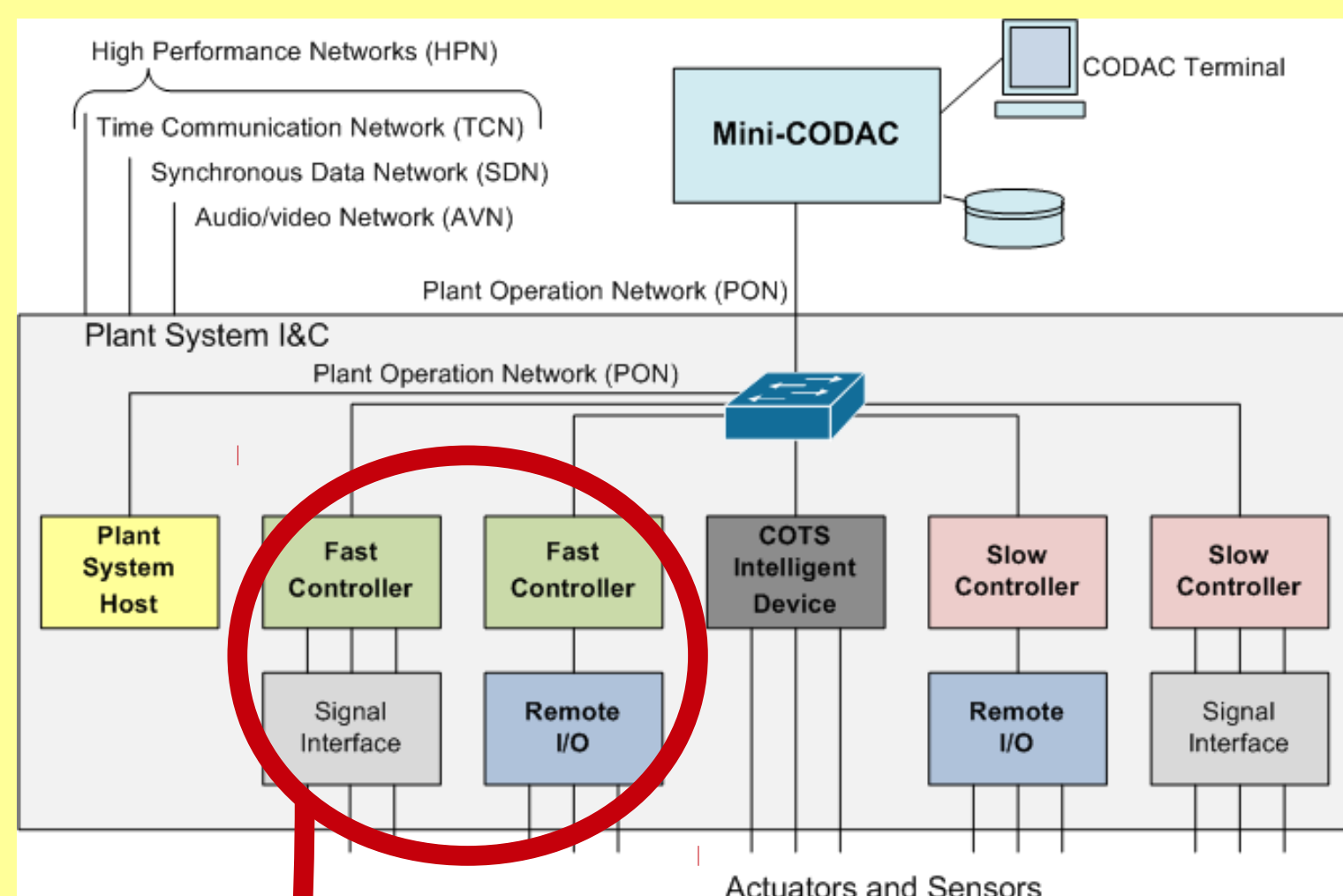


ICALEPCS 2013

14th International Conference on
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Physics Control Systems
06-11th October 2013
San Francisco, USA

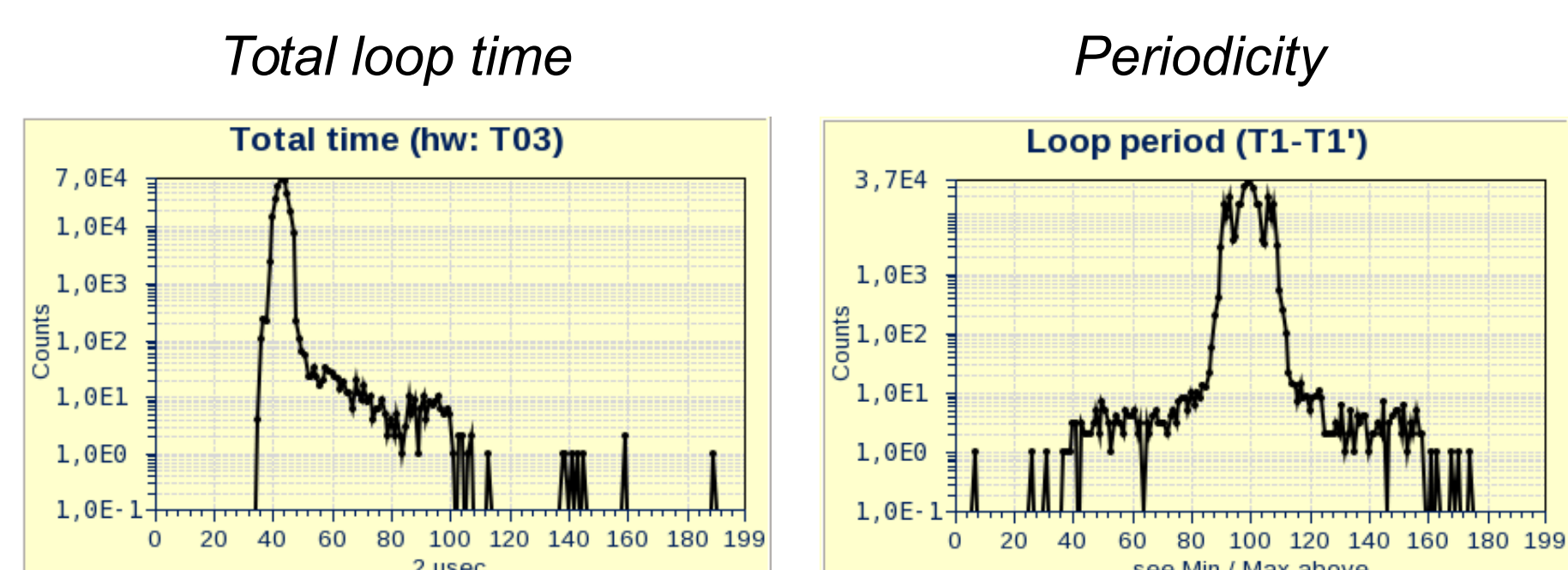
ITER Fast Controller



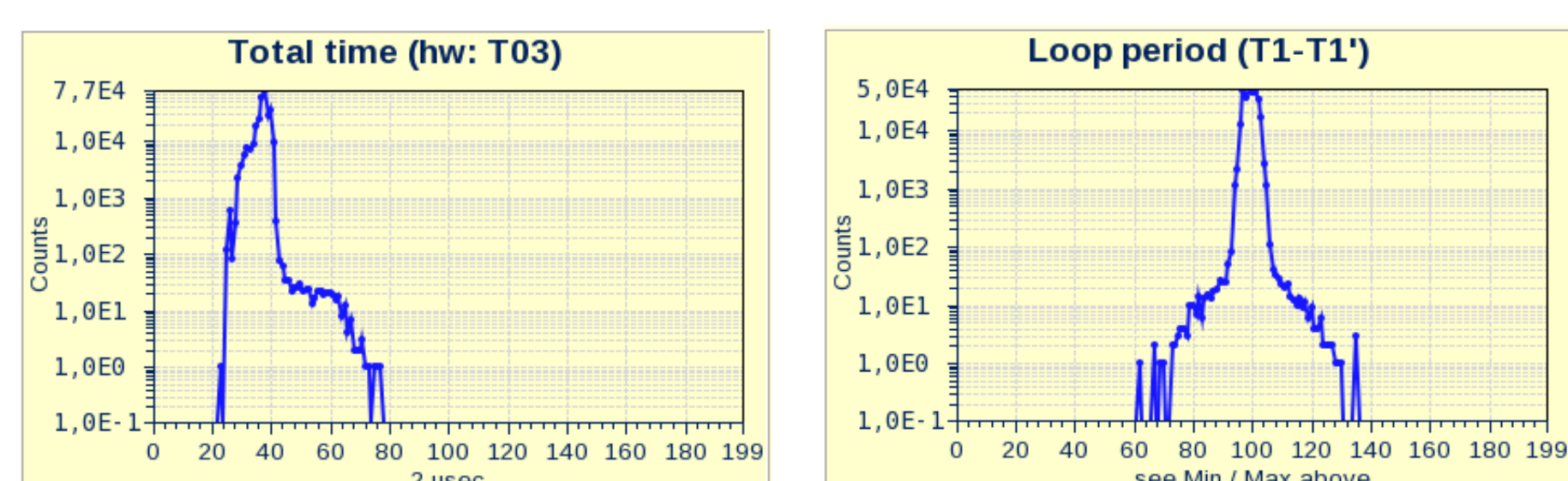
- PICMG 1.3 compliant industrial PC
- PXI/PXIe/cPCI chassis over PCIe link
- Red Hat Enterprise Linux (RHEL)
- Real-time extensions (RHEL MRG-R)

First Results

Improvement of real-time behavior on a test system running a simulated fast control loop, sampling an analog signal from an A/D converter and reading time stamps from a timing card



No optimization.



Dedicated core, high priority.

Optimizing EPICS for Multi-Core Architectures

Abstract

EPICS is a widely used software framework for real-time controls in large facilities, accelerators and telescopes. Its multithreaded IOC (Input Output Controller) Core software has been developed on traditional single-core CPUs. The ITER project will use modern multi-core CPUs, running the RHEL Linux operating system in its MRG-R real-time variant. An analysis of the thread handling in IOC Core shows different options for improving the performance and real-time behavior, which are discussed and evaluated. The implementation is split between improvements inside EPICS Base, which have been merged back into the main distribution, and a support module that makes full use of these new features. This paper describes design and implementation aspects, and presents results as well as lessons learned.

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Improvements

- **Enhancement of EPICS thread show routines**

Easier correlation with Linux system level commands

- **Parallelization of callback threads**

Less latency, lower queue usage, higher processing throughput

- **Rule-based CPU affinity, scheduling policy, and priority settings**

Fine-tuning to run IOC on subset of CPUs, dedicate CPUs to EPICS or external real-time processing, optimize system's performance

```
top - 08:50:00 up 18 days, 13:49, 7 users, load average: 1.20, 1.54, 1.20
Threads: 29 total, 1 running, 28 sleeping, 0 stopped, 0 zombie
%cpu(s): 14.0 us, 0.2 sy, 0.0 ni, 85.4 id, 0.4 wa, 0.0 hi, 0.0 si, 0.0 st
KiB Mem: 12327468 total, 11579136 used, 748332 free, 988300 buffers
KiB Swap: 23437304 total, 33776 used, 23403528 free, 6011940 cached
```

PID	USER	PR	NI	VIRT	RES	SHR	S	%CPU	MEM	TIME	COMMAND
20902	Lange	20	0	1759m	4976	2668	R	99.9	0.0	0:43.29	cbScanner
20891	Lange	20	0	1759m	4976	2668	S	14.0	0.0	0:06.00	cbLow-2
20892	Lange	20	0	1759m	4976	2668	S	14.0	0.0	0:06.02	cbLow-3
20889	Lange	20	0	1759m	4976	2668	S	13.6	0.0	0:05.97	cbLow-0
20890	Lange	20	0	1759m	4976	2668	S	13.6	0.0	0:05.98	cbLow-1
20884	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:02.37	_main_
20885	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	errLog
20887	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	taskwd
20888	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	timerQueue
20893	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	cbMedium-0
20894	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	cbMedium-1
20895	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	cbMedium-2
20896	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	cbMedium-3
20897	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	cbHigh-0
20898	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	cbHigh-1
20899	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	cbHigh-2
20900	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	cbHigh-3
20901	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	dbCaLink
20903	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	scanOnce
20904	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	scan-10
20905	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	scan-5
20906	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	scan-2
20907	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	scan-1
20908	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	scan-0.5
20909	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	scan-0.2
20910	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	scan-0.1
20911	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	CAS-TCP
20912	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	CAS-beacon
20913	Lange	20	0	1759m	4976	2668	S	0.0	0.0	0:00.00	CAS-UDP

Output of top command showing EPICS thread names.

```
# Rules for MCoreUtils
#
# Format of each line:      name:policy:priority:affinity:pattern
#
# name                      distinguishing tag
# policy                    scheduling policy (first letter suffices, case independent, * = don't change)
# priority                  CPU set (use , and - to specify ranges, * = don't change)
# affinity                  regular expression to match thread names against
# pattern

IOC:f:*0-3:*
Loop:f:99:4:TestLoop
```

Example rules file:
Run all EPICS threads on CPUs 0-3,
but run TestLoop at priority 99 on CPU 4.

Further Possibilities and Plans

- **Callbacks for Scan-I/O mechanism**

Add callbacks to the scanIoRequest API, so that drivers know when records have finished processing

- **Driver „private“ callback threads**

Add additional user-configurable priorities, so that drivers can use dedicated callback threads, with configurable number of parallel threads and queue depth (depth = 0 directly processes records from driver thread)

The authors would like to thank the ITER CODAC team and the EPICS Base Developers for their cooperation, help, and fruitful discussions.