## **Cavity BPM System for ATF2**

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16.05.2011



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## **Motivation?**

- Don't really need extra motivation to do interesting work, but what is the significance of all the BPM activities?
- Large scale precision cavity BPM systems are becoming a fact
- Operational issues and stability are important

Machine	Number of cavity BPMs
LCLS	~30
European XFEL	~100
ILC	~500
CLIC	~1000

- ATF2 is the upgraded extraction line for the Accelerator Test Facility at KEK, Japan
- ATF2 BPM system mainly uses cavity BPMs, relatively large scale
- Will try to:
  - Review the system (cavities, electronics, digital processing, analysis)
  - Highlight some issues and possible solutions
    - Stability and calibration studies
    - Multibunch processing



## **Accelerator test facility**

- Low-emittance facility, test system for 35 nm beam size next LC beam delivery system
- Very dense with instrumentation: wire scanners, OTRs, laserwires, laser interference BSM
- Relies mainly on cavity BPMs, currently ~ 40 in total



## **Cavity beam position monitor system**









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## **Cavities+Electronics**

- C and S-band cylindrical cavities with 4 symmetric couplers
- Slot-coupled structure for monopole mode rejection, based on cavities previously used in NanoBPM experiment
- Tuners for adjusting x-y coupling
- Single stage image reject mixer, converting down to 20-30 MHz
- Front-end LNA in C-band, all but 3 attenuated
- Digitise at ~100 MHz





Parameter	C-band	S-band
Frequency, MHz	6422	2888
QL	~6000	~1800
<i>x-y</i> isolation, dB	45	30 (prev. 16)

#### C-band

S-band





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## **Digital processing**

- Digitised signal is processed
  - Digital IQ mixer
  - Digital filtering (Gaussian filter)
  - LO frequency tuned to IF frequency for each channel
  - Same processing for position and reference
- Amplitude and phase are sampled at one point
- Position phasor normalised by the reference to remove the charge and length dependency, and reference the phase to the beam arrival
- The real and the imaginary parts of the resulting phasor are referred to as I's and Q's (in phase and in quadrature phase with the reference)
- I and Q carry information on position, angle and tilt (separated using calibration)





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## Tuning

- The frequency of the LO signal used in digital demodulation needs to be tuned precisely to the frequency of the cavity
- Set a relatively large offset to make S/N high
- Look at the phase of the demodulated signal trying to flatten it adjusting the LO frequency
- If the signal is saturated, the sampling point slides to the right, the amplitude must be extrapolated, but the phase stays virtually the same

$$V(t) = A e^{-\Gamma t} e^{\int (\omega_{IF} - \omega_{LO})t}$$

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- Cavity BPMs need to be calibrated in order to determine:
  - position scale
  - IQ rotation of the position signal
    - suppress angle/tilt
- Can calibrate by either:
  - moving the beam
    - may introduce angle
  - moving the BPM
    - more precise
    - need precision movers
- Calibration:
  - position changed in steps
  - I and Q averaged over several beam passes
  - fit Q vs I to get the rotation
  - fit rotated I (l'-position) to get the scale



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## **Electronics gain monitoring**

- Electronics gain drifts blamed for stability issues
- Send a burst of RF to the electronics behind every beam pulse
- Apply the same processing as to the beam generated signal
- Variations are small compared to jumps of the calibration constants

![](_page_12_Figure_5.jpeg)

# Scale BPM name Week 1 Week 2 Week 3 MOD10X 1800.35 - 1883.3

Calibration constants over

3 weeks(IPAC'10)

MQD10X	1800.35	-	1883.3
MQD16FF	138.3	111.9	111.1
MQD10BFF	929.9	906.4	1254

#### IQ rotation

BPM name	Week 1	Week 2	Week 3
MQD10X	-0.565	-	-0.676
MQD16FF	-0.814	-0.749	-0.801
MQD10BFF	-0.503	-0.427	-0.610

![](_page_12_Figure_10.jpeg)

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![](_page_12_Picture_12.jpeg)

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## **Trigger jitter/drift**

- Due to small differences between the position and reference cavities, changes of the trigger timing cause changes of the phase, even when the phase is flattened along the waveform
- Measuring the beam arrival time for each beam pass and referring the sampling point to the arrival time, it's possible to compensate for this effect

![](_page_13_Figure_3.jpeg)

![](_page_13_Figure_4.jpeg)

![](_page_13_Figure_5.jpeg)

![](_page_13_Figure_6.jpeg)

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![](_page_13_Picture_8.jpeg)

## **Jitter subtracted calibration**

![](_page_14_Figure_1.jpeg)

0 20 40 60 80 100120

x pos and tilt

0 20 40 60 80 10

y pos and till

Correlate readings from upstream BPMs to subtract the beam motion (PCA, MIA, SVD)

And then compute the calibration coefficients •

()

Effects

20 40 60 80100120

x amp and pha

KEK ATP

- Scale variation improves to  $\sim 1\%$  in both x and y •
- Still need to collect more data, but may already be limited by the • movers/variations due to guads
- EPICS/EDM + Python based system enables easy remote operation •

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![](_page_14_Picture_8.jpeg)

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![](_page_14_Picture_10.jpeg)

• • •

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Q amp and pha

y amp and pha

## **Jitter subtracted calibration**

![](_page_15_Figure_1.jpeg)

Correlate readings from upstream BPMs to subtract the beam motion (PCA, MIA, SVD)

- And then compute the calibration coefficients •
- Scale variation improves to  $\sim 1\%$  in both x and y •
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**Jitter subtracted** 

With jitter

## **Resolution as an indicator of the system performance**

- SVD using a few BPMs surrounding the one of interest and calculate the residual
- Usually a high residual signals for a re-calibration
- In some cases it indicates more fundamental problems
  - Large offsets (between the BPM and quad) and consequent saturation
- This display is now an online tool for operators

![](_page_16_Figure_6.jpeg)

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![](_page_16_Picture_8.jpeg)

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![](_page_17_Figure_6.jpeg)

![](_page_17_Picture_7.jpeg)

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## **Optics model check-out**

- Ultimately, want BPMs to work as a diagnostic!
- Example ATF2 optics model checks (done with the trigger time correction in)
- Scan varying one of the correctors and measure the kick at each position
- The model agrees very well with the measurement
- More importantly, the picture stays the same over 2-3 weeks

![](_page_18_Figure_7.jpeg)

## **Stability scales**

- We believe we identified the main sources of instabilities
- But what is the order of their importance?
- What these effects depend on?

Source of systematic	Estimate of the contribution	Driven by/connected to
Trigger variations	Phase jumps up to reverse	Precision of the trigger distribution electronics
Beam jitter	~10% scale variation	~beam size
Electronics gain	~1% scale ~1 deg phase	Complexity of the electronics and components
Temperature drifts	~1 deg/K phase	Resonant frequency

• The next thing we would like to show would be stability over ~3-4 weeks...

![](_page_19_Picture_6.jpeg)

## Japan earth quake

G. White, SLAC

- 11th March 2011, 2:46:23
- 320 km, 8 km/s gives 46 s propagation time
- Beam manually aborted

- 10-ton concrete blocks moved, cables and cable trays messed up
- Vacuum broken in several places
- Complete realignment needed
- Most problems are already fixed by KEK colleagues!
- Alignment groups are working really hard
- Operation is resuming now
- Limited by the power usage restrictions

![](_page_20_Figure_12.jpeg)

![](_page_20_Picture_13.jpeg)

#### From official KEK report

![](_page_20_Picture_15.jpeg)

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![](_page_20_Picture_17.jpeg)

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## **Multi-bunch studies**

- ATF2 cavities have a decay time of ~300 ns
- Even for ILC bunches there would be some overlapping of signals
- Interested in individual bunch positions, so need to subtract
- Digitize the whole signal, process in the normal way (but usually higher BW)
- Sample the amplitudes and phases for every bunch
- Subtract as phasors propagating from previous to next

![](_page_21_Figure_8.jpeg)

![](_page_21_Picture_9.jpeg)

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## **Multi-bunch studies**

- Real data: 3 bunches with a separation of 150 ns.
- 3 mover positions
- Signal subtraction roughly evens out the amplitudes, and hence the offsets, for all 3 bunches (there is some offset between the bunches)
- Phase rotation consistent with 2\*pi\*(f-f\_ref)
- Increased jitter for bunches 2 and 3 needs investigation

![](_page_22_Figure_7.jpeg)

![](_page_22_Figure_8.jpeg)

![](_page_22_Picture_9.jpeg)

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## **Multi-bunch studies (simulated)**

- Simulated data: same separation time
- Parameters as close to the real data as possible
- Processed in the same way as the real data and subtracted
- Subtraction works perfectly, and no jitter increase observed!
- Are we missing something? Perhaps, some interference signals?
- Need to investigate further and need more data...

![](_page_23_Figure_7.jpeg)

![](_page_23_Figure_8.jpeg)

![](_page_23_Picture_9.jpeg)

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N. Joshi, JAI PhD student

## **Summary and outlook**

- ATF2 BPM system
  - Fully operational and easily expandable (at least as before the quake)
  - Main sources of instabilities identified
  - Trigger time issues fixed
  - Online resolution monitoring implemented, other techniques for monitoring the performance in development
- As soon as the ATF2 research program resumes
  - Need to check if any repairs are required
  - Providing the hardware is functional, start-up time should not exceed 2-3 days including calibrations
  - Make jitter-subtracted calibrations routine
  - Collect as much stability data as possible
  - Continue commissioning of the multibunch processing technique

![](_page_24_Picture_12.jpeg)