



cadarache

# **Plasma Position Control and Current** Profile Reconstruction for Tokamaks



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#### Abstract

In large size tokamaks, plasma performances in term of internal temperature, radiated power, stored kinetic energy are growing year after year. A precise control of the plasma position is a key issue in order to **avoid damages** on the first wall of the device. Such a control is essential when buildings of the first wall of the certer, sound a control is essential when high-power long-duration plasmas have to be performed as on the Tore Supra tokanak. The current carried by the plasma can be localized using magnetic measurements (pick-up coils) outside the plasma. The plasma boundary can thus be identified and controlled on real time in less than a few milliseconds.

In order to get information on the **current distribution inside the sma**, more sophisticated calculation must be performed. The **2D Grad**plasma, more sophisticated calculation must be performed. Ine cu orau-Shafranov equation describing the force balance between kinetic pressure and Lorentz force in an axisymmetric toroidal geometry must be solved. Such a solver has been successfully implemented in C++ and installed on Tore Supra device. It is fast enough to enable a real time equilibrium

Because magnetic measurements are no longer sufficient to constrain the solution when detailed information on current distribution inside the plasma are mandatory, other measurements must be introduced as **external constraints** in the solver. 2 sets of constraints have been implemented: Infra-Red Interferometry measurement giving line integrated

electron density - Polarimetry which measures Faraday rotation effect provides information on line integrated magnetic field.





• PC under Windows XP OS

- © PC under Windows xr US © Visual C++ compiler and OpenGL library for RT interface © Pentium4 at 2.86hz (without Hyper Threading) © Socket 478 asustek P468X mother card,
- ATI 9700 pro AGP graphic card 2x512 Mo SDRAM.
- standalone package
- RT network: shared memory ring SCRAMNet® (Systran corp.) at 150MHz
   Time stamp of samples and Synchronization with the timing sysstem: National Instruments PCI-6601 & PCI-6533 cards.
- \* Connection to the RT network: SYSTRAN Corp. PCI 150+ card



chords 1.5 Magnetic 000 sensors 0.5 Ξo -0.5 Toroidal -1 coil 1st Wall Poloida -1.5 coils -2 2.5 3 3.5 1 1.5 2 4 4.5 R (m)

### **2D Grad-Shafranov Equation**

#### Grad-Shafranov equation:

Axisymmetric geometry = 2D equation (r and z cylindrical coordinates) & balance between Lorentz force j  $\times$  B and the  $\nabla p$  force due to pressure gradient & quasi-static form of Maxwell equations

$$\psi = rp'(\psi) + \frac{1}{\mu_0 r} (ff')(\psi) \quad \text{where} \quad \Delta^* \cdot = \frac{\partial}{\partial r} (\frac{1}{\mu_0 r} \frac{\partial}{\partial r}) + \frac{\partial}{\partial z} (\frac{1}{\mu_0 r} \frac{\partial}{\partial z}).$$

- $\psi(\mathbf{r}, \mathbf{z})$  is the poloidal magnetic flux function, The right hand side (non linear) of GS
- $\mu_0$  is the poloid coordinates,  $\mu_0$  is the magnetic permeability p' pressure gradient distribution f = r B<sub>0</sub> and f' its derivative

 $-\Delta^* v$ 

- $j_{\boldsymbol{\phi}}$  of the plasma current density which is governed by p', f and f' functions (null outside the plasma). prime derivative is with respect to ψ

Solving 65 equation with given boundary conditions from magnetic measurements is a free boundary problem in which the plasma boundary is free to evolve. This is an ill-posed problem which needs a dedicated algorithm to be solved.

- GS equation is solved numerically using finite element method
- $\Omega$  domain of the vacuum vessel: decomposed in P1 triangle mesh.  $\partial\Omega$  its boundary  $\Omega_p$  plasma boundary  $\Omega_p = \{\mathbf{x} \in \Omega, \ \psi(\mathbf{x}) \geq \psi_b\}$  where  $\psi_b$  = max<sub>b</sub>  $\psi$  (limiter configuration).

J. Blum et al, ICIPE 2008: 6th Int. Conf. on Inverse Problems in Engineering, Dourdan : France (2008)

## Real Time & Off-Line Results



#### 2 types of Off-line Display (GIF/EPS picture)

Display variation to magnetic measurements, and comparis with EFIT equilibrium solver

Microsoft Visual C++ compiler, Also available for Linux (GNU gcc, Kai KCC) and SunOS (DEC CXX and GNU gcc-g++) • Interface with Tore Supra Database:

equation represents the toroidal component

MATLAB® script Standalone interface for GIF or EPS picture generation

• Capability for comparing results with other equilibrium solvers (EFIT), and RT results Optional display of the mesh, variation to measurements...

## Display of profiles: p' and ff' functions

- pressure, flux (psibar), plasma current, safety factor • density (when interferometry constraint is
- used)
- Generation of result: text and matlab files Use Interferometry and polarimetry
- data as external constraints.

Display variation to interferometry measurements, and comparison with EFIT equilibrium solver

# $\int_{C_{e}} n_{e} dl = \beta_{i}.$

 Magnetic measurements:
 Integration of inductive magnetic sensor voltage

 © 51 pick-up coils: local B<sub>0</sub>
 © 51 pick-up coils: local B<sub>r</sub>

 © 6 toroidal flux loops
 © 2 poloidal flux loops

Infra-Red polarimetry measurements: 10 chords crossing the plasma & Faraday rotation effect of a polarized IR laser beam Measure the magnetic field component parallel to the laser beam.

$$\int_{C_i} \frac{n_e}{r} \frac{\partial \psi}{\partial n} dl = \alpha_i$$

Poloidal View of Tore Supra Tokamak & Used Measurements

Tore Supra Mesh used for Real Time Equinox solver 412 nodes, 762 P1 triangle eleme 60 nodes on boundary (Black: TS first wall) Boundary mesh is chosen to be closed to agnetic sensor localisation



### **Iterative Algorithm**

 ${\pmb 0}$  Starting guessing ( $\psi,\,\Omega_p,\,p',\,ff')^o$  from the previous time step

Optimization step: computation of p'(ψ<sup>n</sup>)<sup>n+1</sup> and Optimization step: computation of p(w<sup>m</sup>)<sup>n+</sup> and ff(w<sup>m</sup>)<sup>n+</sup> inuctions using a least square minimization procedure and including Neumann boundary conditions as external constraints. The cost function takes into account the accuracy of each measurement. The p' and ff' functions are decomposed on a basis (cubic splines, polynomids)....) which reduces the problem to find a few free parameters (typically 5 to 10)

 $\label{eq:problem_step:} \begin{array}{c} \textbf{O} \mbox{ Direct problem step: solve GS equation to compute} \\ \psi^{n+1} \mbox{ and } \Omega^{n+1} \mbox{ using the } p^{n+1} \mbox{ and } ff^{n+1} \mbox{ functions} \\ previously calculated and Dirichlet boundary conditions. \end{array}$ 

G Check for convergence

Tikhonov regularization term added to the cost function (ill-posed problem)

## Boundary conditions & Constraints:

From magnetics: • toroidal flux loops  $\Rightarrow$  Dirichlet condition  $\psi = h$ • pick-up coils  $\Rightarrow$  Neumann condition  $\frac{1}{r} \frac{\partial \psi}{\partial n} = g$ 

Other Constraints: Interferometry & Polarimetry

Real-Time Equinox Display Snapshot



Real Time Display using OpenGL library (8ms/frame)

- Isoflux contour lines (color ranges with the flux value)
  Current profile in equatorial plane
  Safety factor profile in equatorial plane
- Magnetic axis and Shafranov shift (information on
- plasma pressure)

#### Solver Outputs

- Isoflux contour lines
- Plasma boundary position & shape (barycentre, minor radius, ellipticity, triangularity)
   Magnetic axis localization, Shafranov shift...
   Kinetic energy, internal inductance

- Profiles
- Current, safety factor

p' function and pressure
f' and f functions