

# TOWARDS BUILDING REUSABILITY IN CONTROL SYSTEMS – A JOURNEY

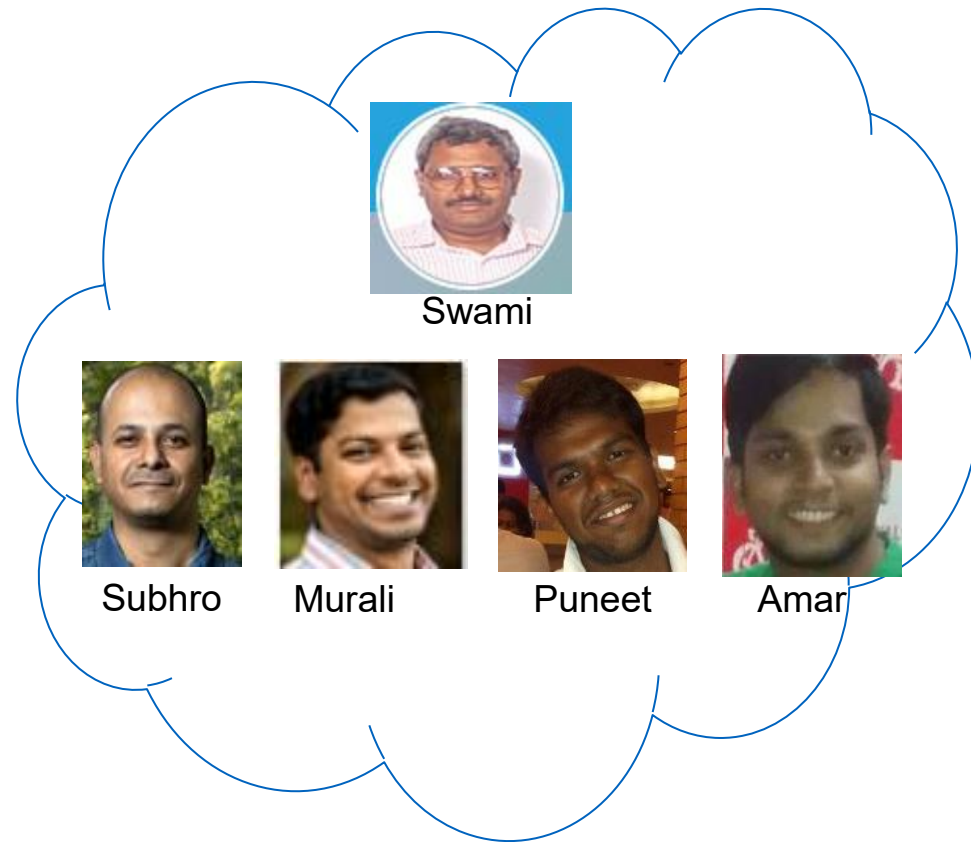
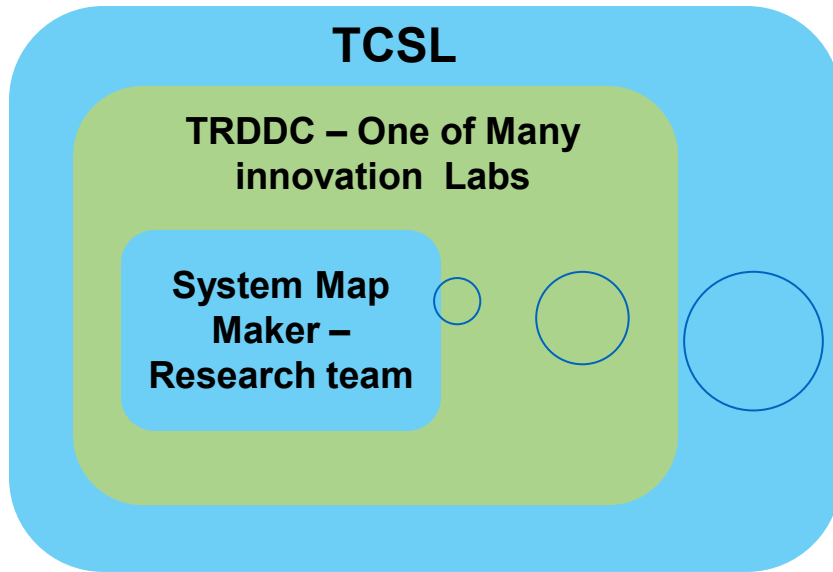
ICALEPCS 15, Melbourne, Australia

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# Talk - Overview

- Brief about who we are
- Challenges and opportunities
  - Towards reusability
- Specific problem areas
  - Reuse across all phases of development lifecycle
  - Solution approach – MDE approach with a focus on knowledge reuse
- Conclusion
  - Where are we going with this – towards knowledge based systems

# Who we are – System Map Maker



Broad area of focus:

- Integrated family of models that capture all the systems engineering information related to a particular system
  - Work out information architecture to facilitate System Engineering

# Collaborations - Control systems

- Translate the ITER CODAC architecture into design
- Demonstrate using prototype
- Build Mini CODAC

**Engagement with ITER**  
Year: 2007

**Collaboration with GMRT**

Year: 2008-09

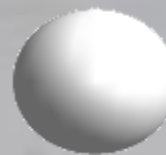
- Architect the NextGen GMRT Control system
- Develop reusable architecture and environment

**CoDR SKA**  
Year: 2010-11

Participate in the creation of the Concept of Design for SKA Supervisory Control System

**Part of SKA TM**  
– 2013-Till date

- Participate in the capacity of TM Project Engineer and TELMGT Lead
- Create detailed design and prototypes for TM of SKA



# Key observation – Opportunity/Motivation

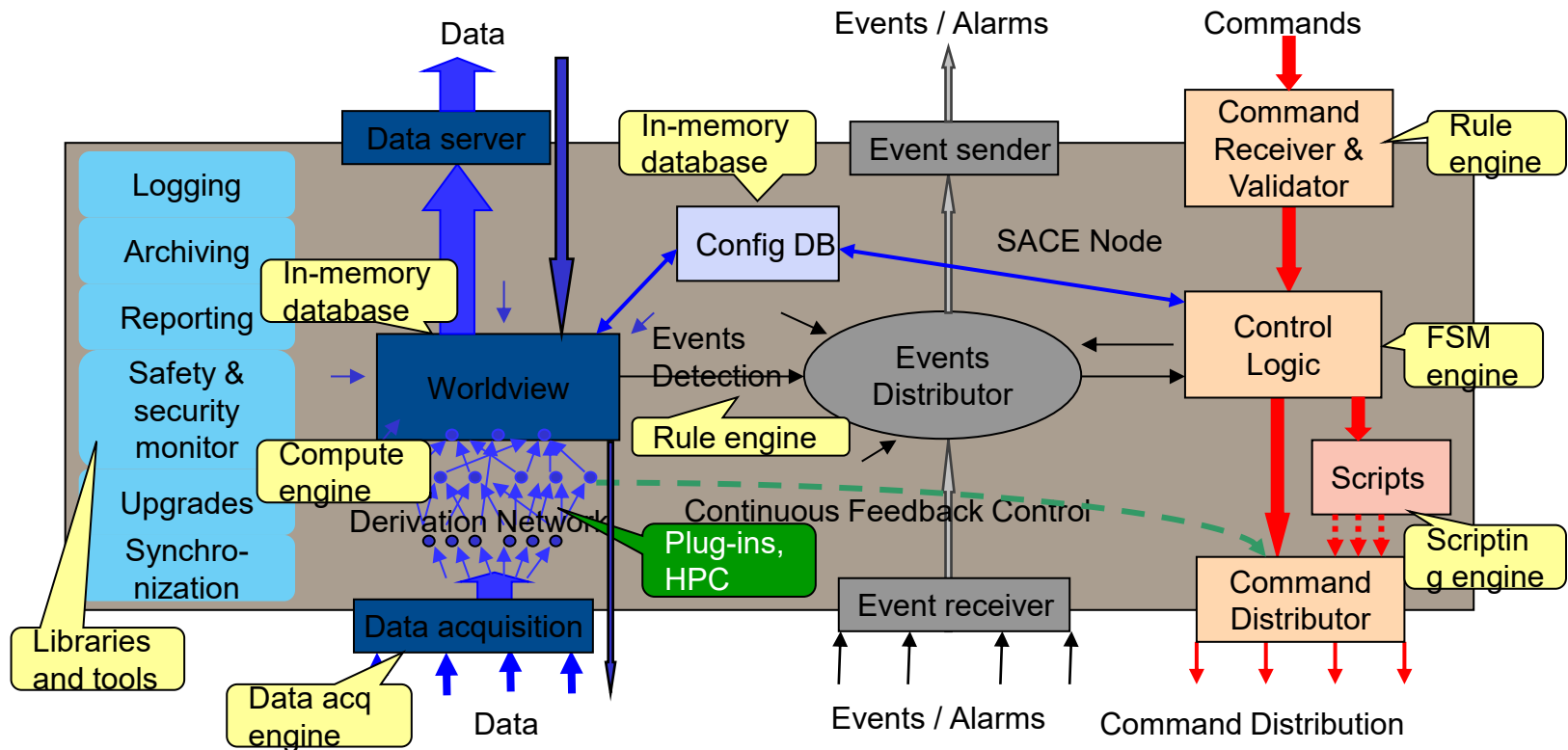
- Very robust solutions available for reuse for the purpose of implementation
  - EPICS, TANGO, ACS and so on
- Challenges and areas of opportunities
  - Significant amount of time spent in the early design life cycle
    - E.g. – ~ 3 years to design TM
  - Each project recreate the design thinking from scratch – and reinvent common M&C concerns, requirements, solution concepts and so on.
    - Usage of SysML does help communicate better, but still falls short on the reusability aspect !
  - Much of the knowledge reside with the domain experts

# Solution opportunity – Start with reusable architecture M&C

Can we create a common solution architecture for M&C - requirements, non functional concerns, functional blocks and so on

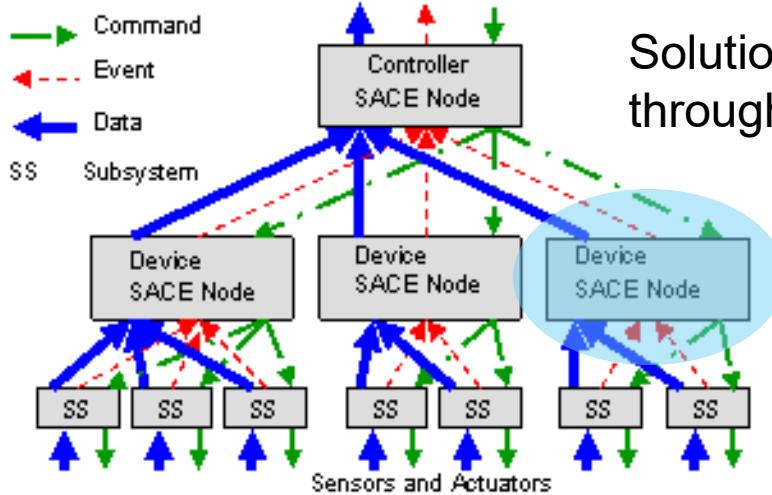
# Solution opportunity – Start with reusable architecture M&C

Can we create a common solution architecture for M&C - requirements, non functional concerns, functional blocks and so on



**Independent of implementation technology,  
Retargetable to multiple off the shelf options  
Completely Data Driven**

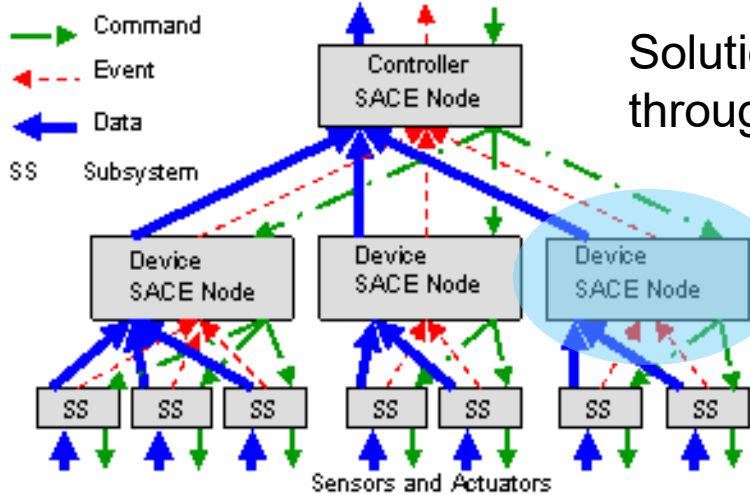
# Identification of the input data



Solution to each control problem created through the composition of such nodes



# Identification of the input data

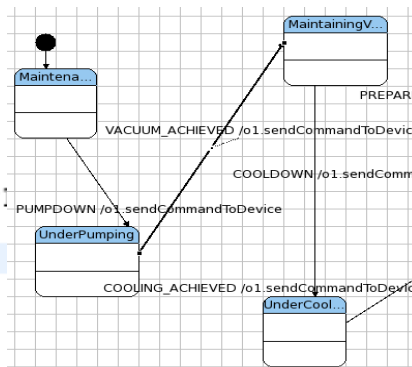


Solution to each control problem created through the composition of such nodes

*Each node configured using its Self Description*

```

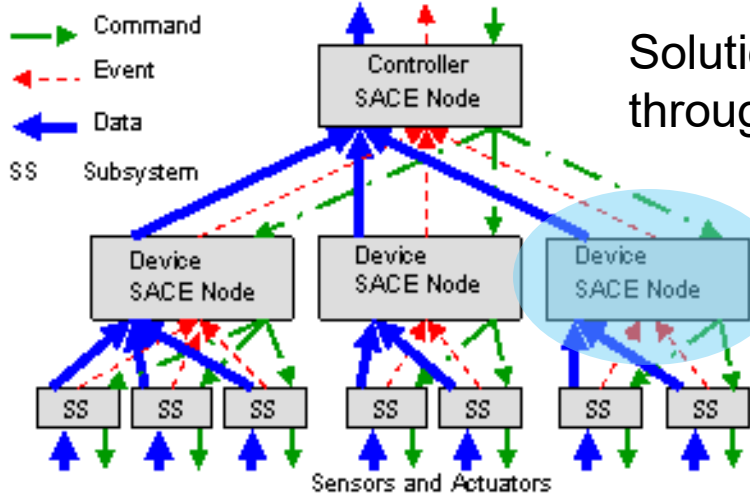
<Command Name = "PUMPDOWN"/>
<Command Name = "COOLDOWN"/>
<Command Name = "PREPARETF">
  <CommandAttachment Name = "PowerSupply"/>
</Command>
<Signal Name = "Cryo_Vacuum_Pressure" Type = "Pressure">
  <UpdateRate Value = "10"/>
</Signal>
  
```



| Action Name | Parameter               | Values |
|-------------|-------------------------|--------|
| PUMPDOWN    | DataSim:Amplitude       | 60     |
|             | DataSim:Offset          | 40     |
|             | DataSim:Frequency       | 1      |
|             | DataSim:Sine            | 1      |
|             | DataSim:Square          | -1     |
|             | DataSim:Triangle        |        |
|             | DataSim:UpdateFrequency |        |
|             | DataSim:Ramp            |        |
|             | DataSim:Amplitude       | 15     |
|             | DataSim:Offset          | 7      |
| COOLDOWN    | DataSim:Frequency       | 1      |
|             | DataSim:Sine            | 1      |
|             | DataSim:Square          | -1     |
|             | DataSim:Triangle        |        |

| Device Name  | Stream Name          | Byte at location | Has values | Event            |
|--------------|----------------------|------------------|------------|------------------|
| MagnetSystem | Cryo_Vacuum_Pressure |                  | 24         | VACUUM_ACHIEVED  |
| MagnetSystem | TF_Temperature       |                  | 20         | QUENCH_OCCURRED  |
| MagnetSystem | Cryo_Vacuum_Pressure |                  | 0          | COOLING_ACHIEVED |

# Identification of the input data



Solution to each control problem created through the composition of such nodes

*Each node configured using its Self Description*

```

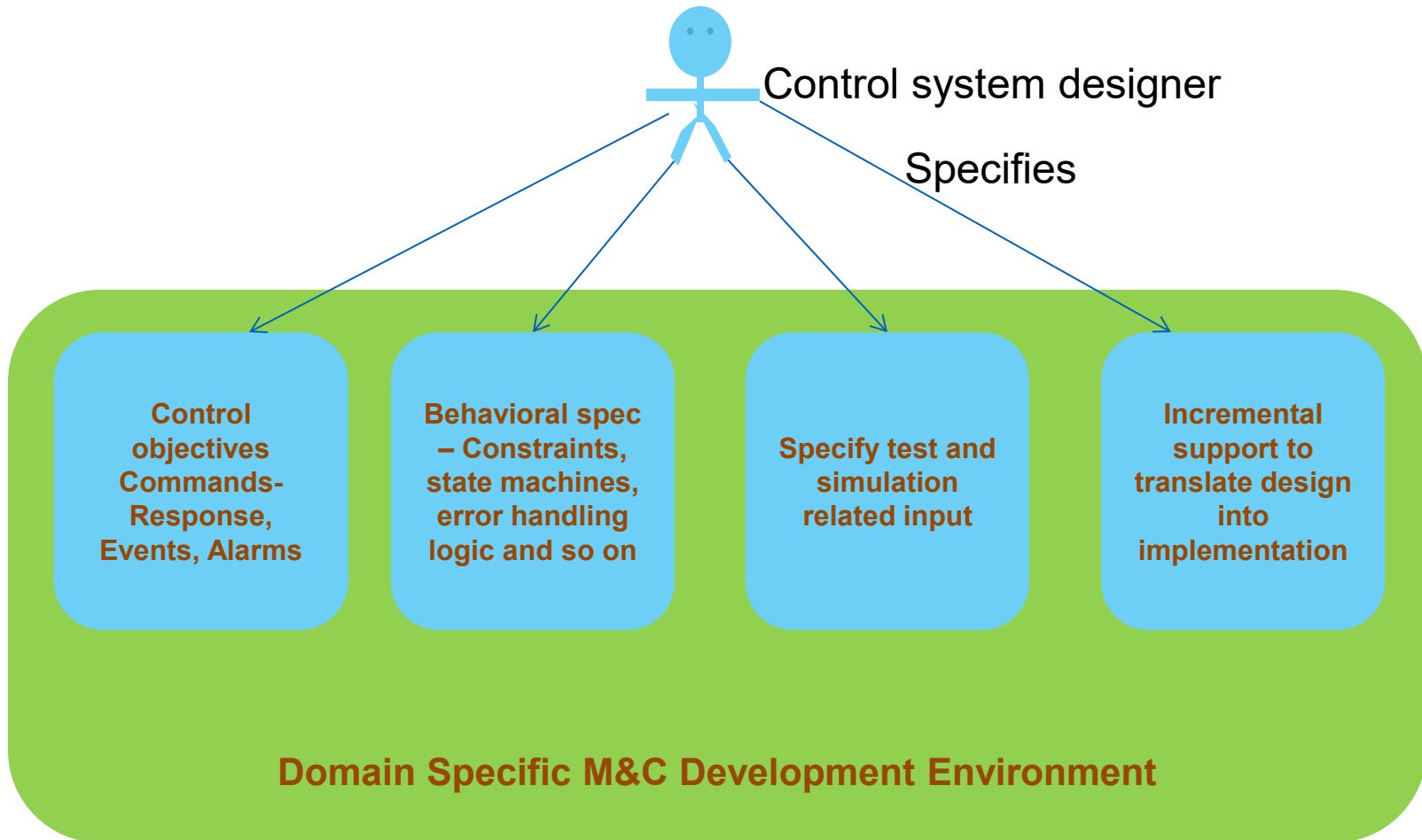
<Command Name = "PI
<Command Name = "C
<Command Name = "PI
  <CommandAttach
</Command>
<Signal Name = "Cr
  <UpdateRate Va
</Signal>
    
```

There might be thousands of such specifications and hence needs support to maintain consistency - A development environment in its own right!!

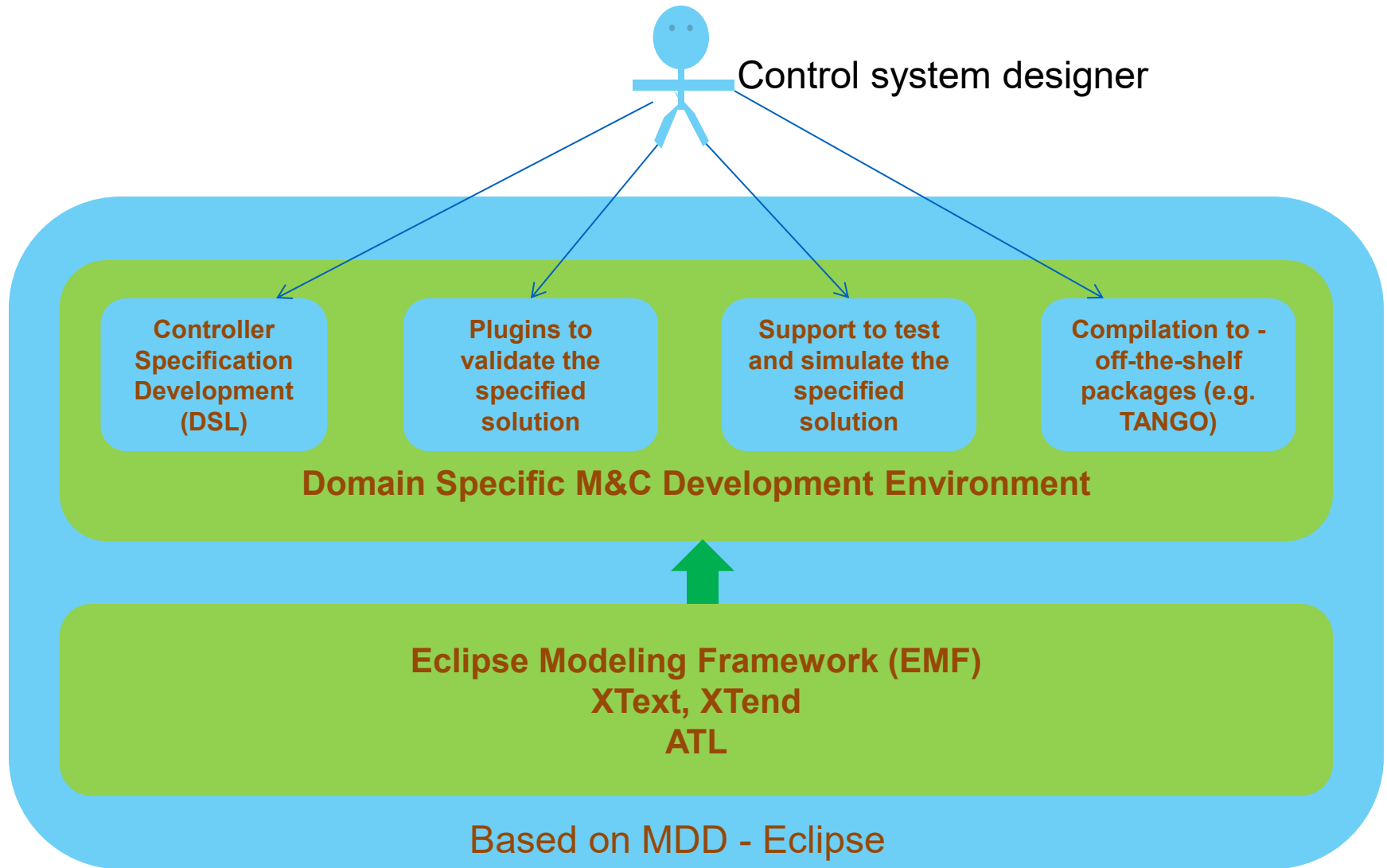
| Action Name | Parameter         | Values |
|-------------|-------------------|--------|
|             | DataSim:Amplitude | 60     |
|             |                   | 40     |
|             |                   | 1      |
|             |                   | 1      |
|             |                   | -1     |
|             |                   |        |
|             |                   | 15     |
|             | DataSim:Onset     | 7      |
|             | DataSim:Frequency | 1      |
|             | DataSim:Sine      | 1      |
|             | DataSim:Square    | -1     |
|             | DataSim:Trianpla  |        |

| Device Name  | Stream Name          | Byte at location | Has values | Event            |
|--------------|----------------------|------------------|------------|------------------|
| MagnetSystem | Cryo Vacuum Pressure |                  | 24         | VACUUM ACHIEVED  |
| MagnetSystem | TF Temperature       |                  | 20         | QUENCH OCCURRED  |
| MagnetSystem | Cryo Vacuum Pressure |                  | 0          | COOLING ACHIEVED |

# Architecting Environment – Domain Driven Engineering



# M&C Architecting Environment –Implementation



# Areas covered in the DSL as of now

## ■ Specification of control structures

- Control nodes
- Commands, parameters
- Responses
- Events, Alarms
- Data streams
- States

```
InterfaceDescription ID_Test{  
    commands{  
        Start[  
            ]  
        }  
    dataPoints {  
        int a  
    }  
    events{  
        event1[]  
    }  
    alarms{  
        A1[]  
    }  
}
```

## ■ Behavior

- Dependencies-Control Hierarchies
- State machines
- Command validation logic
- Alarm detection logic
- Alarm handling specifications
- Data processing

```
ControlNode AggregationNode{  
    Associated Interface Description : GMRT.Controller_ID  
  
    childNodes (GMRT.Controller)  
    commandValidation {  
        command GMRT.Controller_ID.DOSET  
        [parameter bw1 (Possible Values = (6, 16, 32))]  
    }  
    statemachine AgnStMc{  
        state GMRT.Controller_ID.Start  
        [  
            transitions  
            event GMRT.Controller_ID.BOOT_Performed => state GMRT.Controller_ID.Connec  
        ]  
    }  
}
```

- alarmConditions
- alarmHandling
- commandTranslation
- dataPointHandling
- eventTranslation
- operations
- parentNode
- responseValidation

## ■ Placeholder

- External/detailed logic

# Process – Working of the environment

```
Model GWRT
InterfaceDescription ID_IF{
  dataPoints{
    float IF_healthStatus = 10.0
  }
  commands{
    DOSET[
      parameter int bw1 = 1
      parameter int bw2 = 16
      parameter int alc1 = 0
      parameter int alc2 = 0
    ]
  }
  responses{
    RES_DOSET[
      parameter int DeviceNo = 10
      parameter int CmdStat = 0
      parameter string SETStr = ""
    ]
  }
  events{
    DOSET_Performed[]
  }
  states{
    Start[]
    Subscribe[]
  }
  commandResponseMap{
    command DOSET => expectedResponse RES_DOSET
  }
  commandEventMap{
    command DOSET => event DOSET_Performed
  }
  alarms{
    A1[ level : 5 ]
  }
}

ControlNode IF_Controller{
  AssociatedInterfaceDescription : ID_IF
  statemachine IF_SM{
    state GWRT.ID_IF.Start[
      transitions
      event GWRT.ID_IF.DOSET_Performed => state GWRT.ID_IF.Subscribe
    ]
  }
  commandValidation{
    command GWRT.ID_IF.DOSET [
      parameter bw1 (Possible Values = {6, 16, 32})
      Max Value = 32 Min Value = 0
      parameter bw2 (Possible Values = {6, 16, 32})
      Max Value = 32 Min Value = 0
    ]
  }
  alarmConditions{
    AC2[
      dataPoint IF_healthStatus ( Min Value = 5 )
      fireAlarm => GWRT.ID_IF.A1
    ]
  }
}
}

A1 - GWRT.ID_IF.A1
ID_IF
```

} Specify M&C solution description using DSL – M&C ML

# Process – Working of the environment

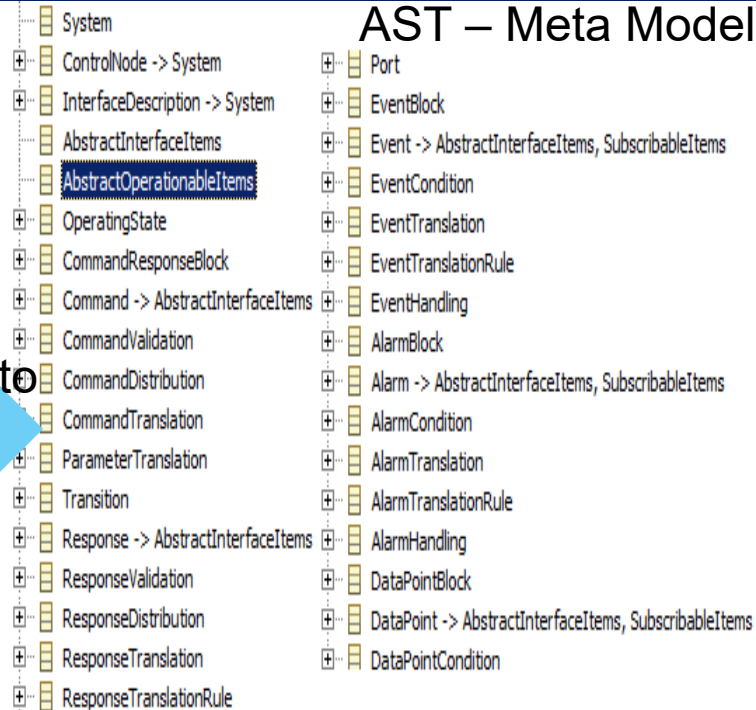
```

Model GWRT
InterfaceDescription ID_IF{
  dataPoints{
    float IF_healthStatus = 10.0
  }
  commands{
    DOSET[
      parameter int bw1 = 1
      parameter int bw2 = 16
      parameter int alc1 = 0
      parameter int alc2 = 0
    ]
  }
  responses{
    RES_DOSET[
      parameter int DeviceNo = 10
      parameter int CmdStat = 0
      parameter string SETStr = ""
    ]
  }
  events{
    DOSET_Performed[]
  }
  states{
    Start[]
    Subscribe[]
  }
  commandResponseMap{
    command DOSET => expectedResponse RES_DOSET
  }
  commandEventMap{
    command DOSET => event DOSET_Performed
  }
  alarms{
    A1[ level : 5 ]
  }
}
    
```

```

ControlNode IF_Controller{
  Associated Interface Description : ID_IF
  statemachine IF_SM{
    state GWRT.ID_IF.Start[
      transitions
      event GWRT.ID_IF.DOSET_Performed => state GWRT.ID_IF.Subscribe
    ]
  }
  commandValidation{
    command GWRT.ID_IF.DOSET [
      parameter bw1 (Possible Values = {6, 16, 32}
      Max Value = 32 Min Value = 0)
      parameter bw2 (Possible Values = {6, 16,
      Max Value = 32 Min Value = 0)
    ]
  }
  alarmConditions{
    AC2[
      dataPoint IF_healthStatus ( Min Value =5 )
      fireAlarm => GWRT.ID_IF.A1
    ]
  }
}
    
```

Parse into



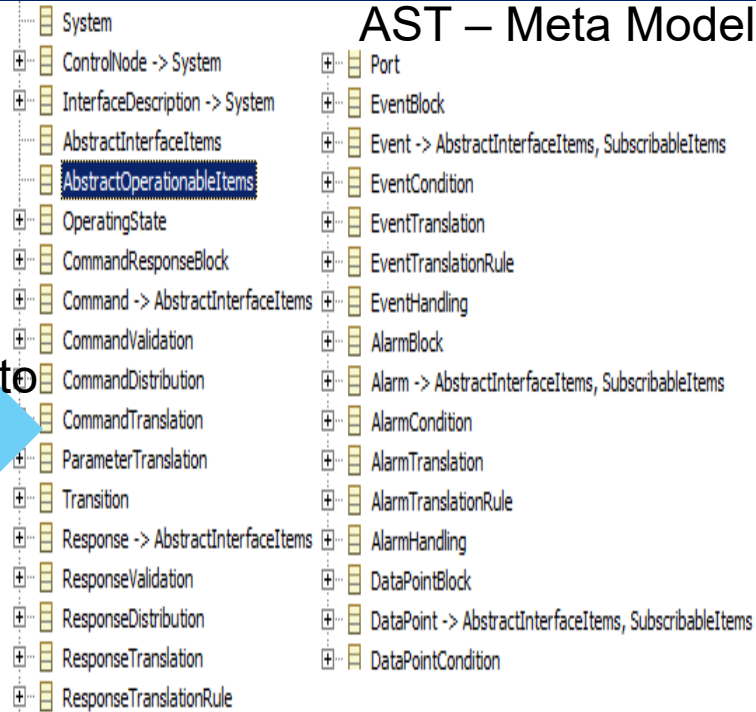
Specify M&C solution description using DSL – M&C ML

# Process – Working of the environment

```

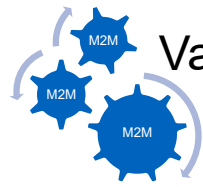
Model GWRT
InterfaceDescription ID_IF{
  dataPoints{
    float IF_healthStatus = 10.0
  }
  commands{
    DOSET[
      parameter int bw1 = 1
      parameter int bw2 = 16
      parameter int alc1 = 0
      parameter int alc2 = 0
    ]
  }
  responses{
    RES_DOSET[
      parameter int DeviceNo = 10
      parameter int CmdStat = 0
      parameter string SETStr = ""
    ]
  }
  events{
    DOSET_Performed[]
  }
  states{
    Start[]
    Subscribe[]
  }
  commandResponseMap{
    command DOSET => expectedResponse RES_DOSET
  }
  commandEventMap{
    command DOSET => event DOSET_Performed
  }
  alarms{
    A1[ level : 5 ]
  }
}
ControlNode IF_Controller{
  Associated Interface Description : ID_IF
  statemachine IF_SM{
    state GWRT.ID_IF.Start[
      transitions
      event GWRT.ID_IF.DOSET_Performed => state GWRT.ID_IF.Subscribe
    ]
  }
  commandValidation{
    command GWRT.ID_IF.DOSET [
      parameter bw1 (Possible Values = {6, 16, 32}
      Max Value = 32 Min Value = 0)
      parameter bw2 (Possible Values = {6, 16,
      Max Value = 32 Min Value = 0)
    ]
  }
  alarmConditions{
    AC2[
      dataPoint IF_healthStatus ( Min Value =5 )
      fireAlarm => GWRT.ID_IF.A1
    ]
  }
}

```



Parse into

Specify M&C solution description using DSL – M&C ML



Validation, M2M/T Translation...

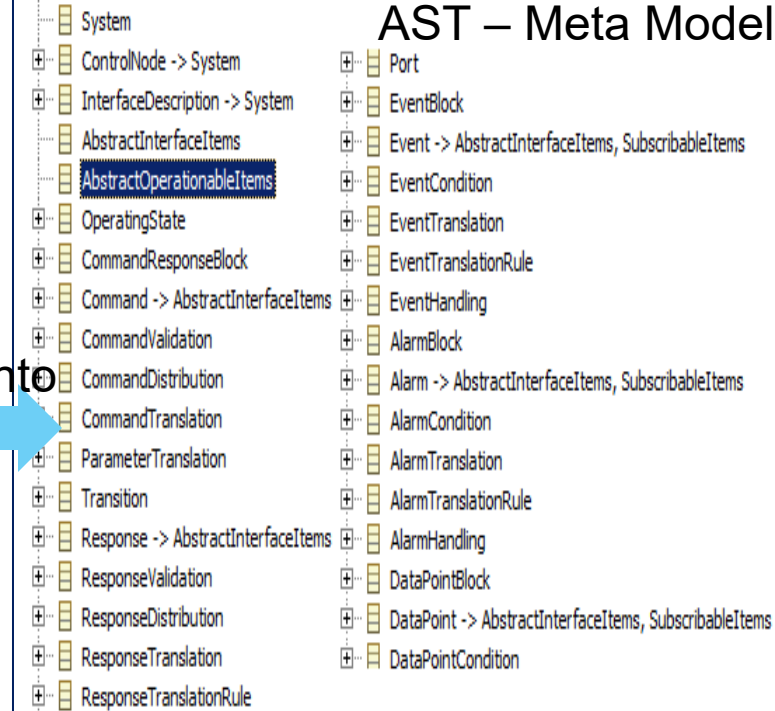


# Process – Working of the environment

```

Model GWRT
InterfaceDescription ID_IF{
  dataPoints{
    float IF_healthStatus = 10.0
  }
  commands{
    DOSET[
      parameter int bw1 = 1
      parameter int bw2 = 16
      parameter int alc1 = 0
      parameter int alc2 = 0
    ]
  }
  responses{
    RES_DOSET[
      parameter int DeviceNo = 10
      parameter int CmdStat = 0
      parameter string SETStr = ""
    ]
  }
  events{
    DOSET_Performed[]
  }
  states{
    Start[]
    Subscribe[]
  }
  commandResponseMap{
    command DOSET => expectedResponse RES_DOSET
  }
  commandEventMap{
    command DOSET => event DOSET_Performed
  }
  alarms{
    A1[ level : 5 ]
  }
}
ControlNode IF_Controller{
  Associated Interface Description : ID_IF
  statemachine IF_SM{
    state GWRT.ID_IF.Start[
      transitions
      event GWRT.ID_IF.DOSET_Performed => state GWRT.ID_IF.Subscribe
    ]
  }
  commandValidation{
    command GWRT.ID_IF.DOSET [
      parameter bw1 (Possible Values = {5, 16, 32}
      Max Value = 32 Min Value = 0)
      parameter bw2 (Possible Values = {0, 16,
      Max Value = 32 Min Value = 0)
    ]
  }
  alarmConditions{
    AC2[
      dataPoint IF_healthStatus ( Min Value = 5 )
      fireAlarm => GWRT.ID_IF.A1
    ]
  }
}

```



Parse into

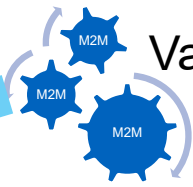
Specify M&C solution description using DSL – M&C ML

```

@Device
public class Controller {
  private static final logger logger = LoggerFactory.getLogger(Controller.class);
  private static final XLogger xlogger = XLoggerFactory.getXLogger(Controller.class);
  private String className = this.getClass().getName();
  private static String deviceName = "nodes/Controller/test";
  private String parentDeviceName = "nodes/LMC/test";
  private String[] childDeviceName = {};
  /**Declaire Variables Here */
  /* Variables Declaration Ends */
  /*-----Initialization Code-----*/
  @Init(lazyLoading = false)
  public final void initDevice() throws DevFailed{
    xlogger.entry();
    logger.debug("init");
  }
  @Command(name = "DOSET")
  public synchronized String DOSET(String parameters) throws DevFailed {
    System.out.println("Executing command DOSET ([mncModel.impl.SimpleTypeImpl@73a460 (name: bw1
    String inCommand = new CommandHandler().getCurrentMethod(this);
    if (new NodeCommandResponseValidation().validateCommand(inCommand, parameters)) {
      String responseReceived = new ControllerSimulator().simulateResponse(inCommand, parameters);
      // Code To Be Written
      if (new NodeCommandResponseValidation().validateResponse(inCommand, responseReceived)) {
        // Calling EventDOSET_Triggered()
        return responseReceived;
      } else {
        return new String("BAD RESPONSE");
      }
    } else {
      return new String("BAD COMMAND");
    }
  }
}

```

Translation into TANGO implementation



Validation, M2M/T Translation...

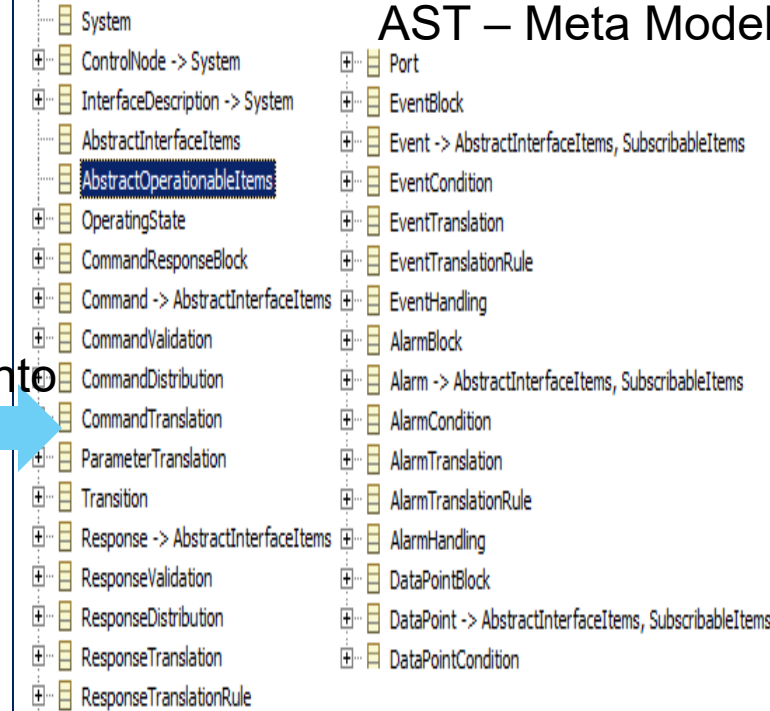
# Process – Working of the environment

```

Model GVRT
InterfaceDescription ID_IF{
  dataPoints{
    float IF_healthStatus = 10.0
  }
  commands{
    DOSET[
      parameter int bw1 = 1
      parameter int bw2 = 16
      parameter int alc1 = 0
      parameter int alc2 = 0
    ]
  }
  responses{
    RES_DOSET[
      parameter int DeviceNo = 10
      parameter int CmdStat = 0
      parameter string SETStr = ""
    ]
  }
  events{
    DOSET_Performed[]
  }
  states{
    Start[]
    Subscribe[]
  }
  commandResponseMap{
    command DOSET => expectedResponse RES_DOSET
  }
  commandEventMap{
    command DOSET => event DOSET_Performed
  }
  alarms{
    A1[ level : 5 ]
  }
}
    
```

```

ControlNode IF_Controller{
  Associated Interface Description : ID_IF
  statemachine IF_SM{
    state GVRT.ID_IF.Start{
      transitions
      event GVRT.ID_IF.DOSET_Performed => state GVRT.ID_IF.Subscribe
    }
  }
  commandValidation{
    command GVRT.ID_IF.DOSET [
      parameter bw1 (Possible Values = {5, 16, 32}
      Max Value = 32 Min Value = 0)
      parameter bw2 (Possible Values = {0, 16,
      Max Value = 32 Min Value = 0)
    ]
  }
  alarmConditions{
    AC2[
      dataPoint IF_healthStatus ( Min Value = 5 )
      fireAlarm => GVRT.ID_IF.A1
    ]
  }
}
    
```



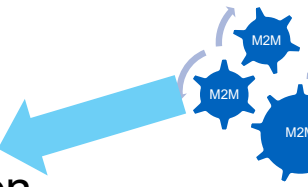
Parse into

Specify M&C solution description using DSL – M&C ML

```

@Device
public class Controller {
  private static final logger logger = LoggerFactory.getLogger(Controller.class);
  private static final XLogger xlogger = XLoggerFactory.getXLogger(Controller.class);
  private String className = this.getClass().getName();
  private static String deviceName = "nodes/Controller/test";
  private String parentDeviceName = "nodes/LMC/test";
  private String[] childDeviceName = {};
  /*Declaring Variables Here */
  /* Variables Declaration Ends */
  /*-----Initialization Code-----*/
  @Init(lazyLoading = false)
  public final void initDevice() throws DevFailed{
    xlogger.entry();
    logger.debug("init");
  }
  @Command(name = "DOSET")
  public synchronized String DOSET(String parameters) throws DevFailed {
    System.out.println("Executing command DOSET ([mcModel.impl.SimpleTypeImpl73a460 (name: bw1
    String inCommand = new CommandHandler().getCurrentMethod(this);
    if (new NodeCommandResponseValidation().validateCommand(inCommand, parameters)) {
      String responseReceived = new ControllerSimulator().simulateResponse(inCommand, parameters);
      // Code To Be Written
      if (new NodeCommandResponseValidation().validateResponse(inCommand, responseReceived)) {
        // Calling EventDOSET_Triggered()
        return responseReceived;
      } else {
        return new String("BAD RESPONSE");
      }
    } else {
      return new String("BAD COMMAND");
    }
  }
}
    
```

Translation into TANGO implementation



Validation, M2M/T Translation...

Generation of Simulators and Test Cases

```

public class ControllerSimulator {
  String parseResponse = "{ \"DOMON\": { \"RES_DOMON\": { \"allowValues\": { \"IF_Monitoring_HealthStatus\": { \"allow
  String parseDataPoint = \"{ \"IF_Monitoring_HealthStatus\": { \"allow
  String deviceName = \"nodes/Controller/test\";
  JSOObject datapointJSOObject = (JSOObject) JSOValue.parse(parseResponse);
  JSOObject jsonkk = (JSOObject) JSOValue.parse(parseResponse);
  Object object[] = datapointJSOObject.keySet().toArray();
  public String simulateResponse(String commandName, String commandParam
  JSOArray jSONarr = (JSOArray) jsonkk.get(commandName);
  if(jSONarr==null){
    return \"RESPONSE RECEIVED FOR \" +commandName. toUpperCase();
  }
  JSOObject alk = (JSOObject) jSONarr.get(0);
  JSOObject jso = (JSOObject)JSOValue.parse(commandParameters);
  if(jso != null){
    JSOObject fixedResp = (JSOObject) jso.get(\"fixedResponse\");
    if(fixedResp!=null){
      Set<String> map = fixedResp.keySet();
      Iterator<String> iterat = map.iterator();
      String hh = fixedResp.get(\"Response\");
      while(iterat.hasNext()){
        String mm = (String) iterat.next();
        if(!mm.equals(\"Response\")){
          hh += hh + mm + \":\" +fixedResp.get(mm) + \":\";
        }
      }
      System.out.println(hh);
      return hh;
    }
  }
}
    
```

# Factors influencing DSL design

## Key drivers to the DSL design

- Important to understand the stakeholder concerns
  - In our case M&C designers
  - Leave out the details of the application domain (e.g. Astronomy), projects specifics
- Understanding and extracting key concerns from the domain
  - Important input is the vocabulary using while specifying M&C design
- Capturing the underlying architecture pattern
  - SACE suggests a strict hierarchical
  - Hence the flow of the DSL reflects the same
  - However, cant be applied to other patterns, such as Agent based systems
- Decoupling the meta-modeling from the grammar definition
  - Capture the domain concerns in a structured form with relations
  - Don't worry about the language syntax while doing so
- Careful analysis of the user intuitions for language syntax definition
  - Can be based on the combination of functional building blocks and architecture flows
- Extensibility
  - Support for incremental domain specific validations
  - Incremental addition of concepts (e.g. Radio telescope) and separation of concerns

# Future direction – knowledge based engineering environment and conclusion

- We plan to try this out for uGMRT, SKA
- Such an environment is a stepping stone towards identification of domain models and capturing of knowledge –
  - Technical domain such as M&C, Networks, Security and so on
  - Application domain such as Radio astronomy Nuclear fusion
- Learnings can be used to build similar domain environment or contribute towards general capability such as SysML and so on.

**Thank You!**