Abstract

Higher efficiency of TESLA based free electron lasers (FLASH, XFEL) by means of increased quantity of photon bursts can be achieved using continuous wave (CW) operation mode. In order to maintain constant beam acceleration in superconducting cavities and keep short pulse to CW operation transition costs reasonably low some substantial modification of accelerator subsystems are necessary. Changes in: RF power source, cryo systems, electron beam source, etc. have to be also accompanied by adjustments in LLRF system. In this paper challenges for well defined LM systems adjustments set of tests have been done on CMTB. Results from these tests together with achieved regulation performance data are also presented.

Introduction

Although the European X-ray Free Electron Laser (XFEL) is still in the construction stage possible facility upgrades are already under discussion. The possibility of constant beam acceleration is one of the attractive option of future laser operation. In order to evaluate the potential impact of the operation scenario change to the existing infrastructure and define initial requirements for linac systems. CW/LP operation limitations: - increased load on the cryogenic systems (limit 20W/module), - input cavity coupler acceptable power level (different duty factor scenarios needed).

CW/LP test environment

CMTB facility equipped with: - single 8 TESLA cavities cryomodule - cryogenics system, - high power RF sources (klystron and IOT). - LLRF system infrastructure (VME and MTCA.4). - slow motor frequency tuners, piezo tuners control system

MTCA.4 system based results

Usual (short pulse operation) conditions: - pulse ~1.3ms length - repetition rate = 10Hz, - sampling rate = 9MHz, - 16384 samples/waveform (acquisition window of ~1.8ms).

Continuous wave operation: - repetition rate = 1 Hz, - acquisition time window = 1s, - data transfer rate 654Hz – 9MHz, - 65536 samples/waveform.

LLRF feedback (actual implementation - MTCA.4)

The system consists of MTCA.4 hardware components for data acquisition fast feedback loops realization, cavities signals down-conversion, drive signal up-conversion, piezo driver communication and others.

Piezo Feedback

The CPU hosts few DOOCS servers responsible for: - LLRF system management and slow control algorithms realization, - timing signal distribution and synchronization. Operators GUI has been provided using JDDD environment.

Initial system structure and results

Possible improvements

As the CW operation level was achieved according to expectation the LP was not successful for LLRF/piezo loops for operation with higher gradients (above 16 MV/m). Perturbation (65kHz) have not been successfully suppressed. This additional excitation has been caused by the cryo and vacuum pumps. Because of its mechanical nature this distortion has been expected to be minimized by the piezo FB loop. Although the tuner feedback was able to reduce the impact of this oscillations its performance has to be improved.

Conclusions & next steps

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